

## Subject card

Subject name and code	Navigation Systems,	PG_00049081							
Field of study	Automatic Control, Cy	ybernetics and	Robotics						
Date of commencement of studies	October 2020		Academic year of realisation of subject		2023/2024				
Education level	first-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	4		Language of instruction			Polish			
Semester of study	7		ECTS credits			3.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Marine Electronic Systems -> Faculty of Electronics, Telecommunications and Informatics					Informatics			
Name and surname	Subject supervisor Teachers		dr hab. inż. Jacek Marszal						
of lecturer (lecturers)			dr hab. inż. Jacek Marszal						
			mgr inż. Andrzej Jedel						
			mgr inż. Aleks	mgr inż. Aleksander Schmidt					
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	aboratory Project		Seminar	SUM	
of instruction	Number of study hours	30.0	0.0	15.0 0.0			0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in classes include plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	45		3.0		27.0		75	
Subject objectives	The aim of the course of navigation systems		students with t	the basics of th	e theor	y of nav	rigation, as w	ell as the use	
Learning outcomes	Course outcome  [K6_W03] Knows and understands, to an advanced extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum  [K6_U06] can analyse the operation of components, circuits and systems related to the field of study, measure their parameters and examine technical specifications		Subject outcome			Method of verification			
			Student defines navigation tasks and its basic concepts. Discusses mapping methods and maps. Classifies and describes classic navigation methods and technical methods of their implementation. Presents the principles of work and parameters of navigation devices. Explains the principle of work and gives the parameters of the GPS satellite navigation system.			[SW1] Assessment of factual knowledge			
			Student discusses the basics of functioning and application of hydroacoustic navigation systems. Describes the operation of the radar as a navigation device used in sea and air navigation.			[SU3] Assessment of ability to use knowledge gained from the subject [SU1] Assessment of task fulfilment			

Data wydruku: 27.04.2024 07:29 Strona 1 z 2

0. 1. 1 1 1.	1 Organizira isana sulas afirm	a consultations literatures						
Subject contents	Organizing issue: rules of passin     Fundamentals of navigation	g, consultations, literatures						
	Navigation and geodesy							
	4. Shape of the Earth							
	5. Geographical position							
	6. Reference systems - review 7. WGS-84 i GRS'80							
	8. Projection types							
	9. Mercator Projection							
	10. Gauss-Krüger Projection and Universal Transversal Mercator							
	11. Projection "65"							
	12. Navigational maps							
	<ul><li>13. ECDIS digital maps</li><li>14. Directions, corrections – course</li></ul>	hearing track angle						
	15. Magnetic declination and compa							
	16. Drift, wind correction							
	17. Terrestric navigation							
	18. Inertial navigation							
	19. Magnetic compasses - classical							
	20. Magnetic compasses - electroni 21. Gyro-compasses	C						
	22. Ring Laser Gyro							
	23. Screw log							
	24. Pitometer log							
	25. Electromagnetic log							
	26. Ultrasonic Doppler log							
	27. Ship berthing control systems 28. Accelerometers, inertial platforms 29. Structure and GPS principles 30. GPS space segment 31. GPS control segment							
	32. Position determination in GPS system							
	33. Signal trasmitted by satelite GPS 34. Depesza nawigacyjna							
	35. DGPS, WAAS, EGNOS differential systems							
	36. GPS receivers 37. GPS in geodesy							
	38. Global navigational system GALILEO							
	39. Errors and precision of position							
	<ul><li>39. Errors and precision of position</li><li>40. Underwater navigation systems</li></ul>	in GPS system						
	<ul><li>39. Errors and precision of position</li><li>40. Underwater navigation systems</li><li>41. Hydroacoustic buoys- pingers, t</li></ul>	in GPS system ransponders						
	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation 43. Hydroacoustic local navigation	in GPS system ransponders	se					
	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder	in GPS system ransponders, responders system with long base	se					
	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar	in GPS system ransponders, responders system with long base	se					
	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation	in GPS system ransponders, responders system with long base	se					
Dragonicko	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar	in GPS system ransponders, responders system with long base	se					
Prerequisites	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation	in GPS system ransponders, responders system with long base	6 <b>e</b>					
and co-requisites	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS	in GPS system ransponders, responders system with long base system with short and super short bas						
and co-requisites Assessment methods	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation	in GPS system ransponders, responders system with long base	Se Percentage of the final grade					
and co-requisites	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS	in GPS system ransponders, responders system with long base system with short and super short bas						
and co-requisites Assessment methods	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation of 43. Hydroacoustic local navigation of 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS	in GPS system ransponders, responders system with long base system with short and super short base	Percentage of the final grade					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium  Practical exercise	in GPS system ransponders, responders system with long base system with short and super short base Passing threshold 60.0%	Percentage of the final grade 67.0% 33.0%					
and co-requisites Assessment methods	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium	ransponders, responders system with long base system with short and super short base system with short and super short base follows:  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współc	Percentage of the final grade 67.0%					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium  Practical exercise	ransponders, responders system with long base system with short and super short base system with short and super short base for the system with short and super short bases for the system with short and short bases for the system with short bases for the system with short and short bases for the system with short ba	Percentage of the final grade 67.0% 33.0% zesna w zarysie. Wyd. Wiedza i					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium  Practical exercise	ransponders, responders system with long base system with short and super short base system with short and super short base for the system with short and super short bases for the system with short and short bases for the system with short bases for the system with short and short bases for the system with short ba	Percentage of the final grade 67.0% 33.0%					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium  Practical exercise	ransponders, responders system with long base system with short and super short base  Passing threshold  60.0%  1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli	Percentage of the final grade 67.0% 33.0% zesna w zarysie. Wyd. Wiedza i					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium  Practical exercise	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007.	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium  Practical exercise	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H.,	Percentage of the final grade 67.0% 33.0% zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współo Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S	Percentage of the final grade 67.0% 33.0% zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning springer, Wien 1997					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria Midterm colloquium  Practical exercise	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S 1. Stateczny A. Nawigacja porów	Percentage of the final grade 67.0% 33.0% zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współoc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S 1. Stateczny A. Nawigacja porów 2001.	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ  Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie,					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature	ransponders, responders system with long base system with short and super short base of the system with short and short base of the system with short base of the syste	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ  Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa,					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature  Supplementary literature	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S 1. Stateczny A. Nawigacja porów 2001. 2. Narkiewicz J. GPS globalny sy działanie, zastosowania. WKŁ	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ  Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa,					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współo Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S 1. Stateczny A. Nawigacja porów 2001. 2. Narkiewicz J. GPS globalny sy działanie, zastosowania. WKŁ Adresy na platformie eNauczanie:	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa, Warszawa 2006.					
and co-requisites Assessment methods and criteria	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature  Supplementary literature	ransponders, responders system with long base system with short and super short base system with short and super short base  Passing threshold 60.0% 60.0%  1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S 1. Stateczny A. Nawigacja porów 2001. 2. Narkiewicz J. GPS globalny sy działanie, zastosowania. WKŁ	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa, Warszawa 2006. Moodle ID: 33992					
Assessment methods and criteria  Recommended reading	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature  Supplementary literature	Passing threshold 60.0% 60.0% 1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S. 1. Stateczny A. Nawigacja porów 2001. 2. Narkiewicz J. GPS globalny sy działanie, zastosowania. WKŁ Adresy na platformie eNauczanie: Systemy nawigacyjne AiR 2023 - N.	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa, Warszawa 2006. Moodle ID: 33992					
Assessment methods and criteria  Recommended reading  Example issues/	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature  Supplementary literature	Passing threshold 60.0% 60.0% 1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S. 1. Stateczny A. Nawigacja porów 2001. 2. Narkiewicz J. GPS globalny sy działanie, zastosowania. WKŁ Adresy na platformie eNauczanie: Systemy nawigacyjne AiR 2023 - N.	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa, Warszawa 2006. Moodle ID: 33992					
Assessment methods and criteria  Recommended reading  Example issues/ example questions/	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature  Supplementary literature	Passing threshold 60.0% 60.0% 1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S. 1. Stateczny A. Nawigacja porów 2001. 2. Narkiewicz J. GPS globalny sy działanie, zastosowania. WKŁ Adresy na platformie eNauczanie: Systemy nawigacyjne AiR 2023 - N.	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa, Warszawa 2006. Moodle ID: 33992					
Assessment methods and criteria  Recommended reading  Example issues/	39. Errors and precision of position 40. Underwater navigation systems 41. Hydroacoustic buoys- pingers, t 42. Hydroacoustic local navigation s 43. Hydroacoustic local navigation s 44. Navigational echo sounder 45. Principles of radar 46. Radar in navigation 47. Instrument landing system ILS  Subject passing criteria  Midterm colloquium  Practical exercise  Basic literature  Supplementary literature	Passing threshold 60.0% 60.0% 1. Czarnecki K. Geodezja współc Życie Warszawa 1997. 2. Narkiewicz J. Podstawy układó 1999. 3. Narkiewicz J. GPS i inne sateli Warszawa 2007. 4. Hogmann B., Lichtenegger H., System Theory and Practice. S. 1. Stateczny A. Nawigacja porów 2001. 2. Narkiewicz J. GPS globalny sy działanie, zastosowania. WKŁ Adresy na platformie eNauczanie: Systemy nawigacyjne AiR 2023 - N.	Percentage of the final grade 67.0% 33.0%  zesna w zarysie. Wyd. Wiedza i w nawigacyjnych. WKŁ Warszawa tarne systemy nawigacyjne. WKŁ Collind J. Global Positioning springer, Wien 1997 nawcza, Wydawnictwo Gdańskie, stem pozycyjny GPS, budowa, Warszawa 2006. Moodle ID: 33992					

27.04.2024 07:29 Strona 2 z 2 Data wydruku: