

Subject card

Subject name and code	Theory of mechanisms and machines dynamics, PG_00008954							
Field of study	Mechatronics, Mechatronics							
Date of commencement of studies	October 2020		Academic year of realisation of subject			2021/2022		
Education level	first-cycle studies		Subject group			Obligatory subject group in the field of study Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery			at the university		
Year of study	2		·			Polish		
Semester of study	4		ECTS credits		2.0			
Learning profile	general academic profile		Assessment form		assessment			
Conducting unit	Department of Mechanics and Mechatronics -> Faculty of Mechanical Engineering and Ship Technology							
Name and surname	Subject supervisor	dr hab. inż. Krzysztof Lipiński						
of lecturer (lecturers)	Teachers		dr hab. inż. Krzysztof Lipiński					
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM
	Number of study hours	15.0	15.0	0.0	0.0		0.0	30
	E-learning hours included: 0.0							
	Adresy na platformie eNauczanie:							
	Teoria mechanizmów i dynamika maszyn, PG_00008954 - Moodle ID: 23736 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=23736							
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study		SUM
	Number of study hours	30		5.0		15.0		50
Subject objectives	Familiarize students with the major concepts of the theory of mechanisms and machines. Review of the types of mechanisms. The introduction of the main concepts of structural analysis. Presentation of selected methods used for determining the position, velocity and acceleration. Presentation of methods of dynamics of mechanisms. Introduction to the free and forced vibration of discrete systems.							

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K6_W04 The student knows the most important concepts of the theory of mechanisms and of mechanisms. The student can recognizes the main types of mochanisms. The student can concepts and mechanisms and of mechanisms. The student can concepts and maintenance of mechanisms. The student can concepts and maintenance of mechanisms. The student is able to designate position, speed and acceleration of elements to selected concepts and methods of dynamics of mechanisms. Student can determine equations of independently can determine paintenance of the most important can determine quasicus of mechanisms. Student can determine paintenance of the most important concepts of the concepts of the most important concepts	Learning outcomes	Course outcome	Subject outcome	Method of verification		
The student independently acquires knowledge of the most important concepts of theories of mechanisms is machines. The student can independently conduct a structural analysis of mechanism and he can determine their mobility. Student can independently position, speed and acceleration of elements of mechanisms. The student can independently position, speed and acceleration of elements of mechanisms. The student can independently determine equations of kinetostatics and the associated forces. In kinematic pairs. In kinematic pairs in kinematic pairs in kinematic pairs.			The student knows the most important concepts of the theory of mechanisms and machines. The student can recognizes the main types of mechanisms. The student can conduct a structural analysis of mechanisms and he can determine their mobility. Student knows the most important concepts and methods of kinematics of mechanisms. The student is able to designate position, speed and acceleration of elements fo mechanisms. The student knows selected concepts and methods of dynamics of mechanisms. Student can determine equations of kinetostatics and determine the associated forces in kinematic pairs. The student is able to determine free and forced vibrations of discrete systems of one and of	[SW1] Assessment of factual		
Rowledge of the most important concepts of theories of mechanisms and machines. The student can independently conduct an analysis of structural mechanism and determine its mobility. Student can designate independently position, speed and acceleration of of elements of planar mechanisms. The student can independently determine equations kinetostatics and determine equations kinetostatics and determine associated forces in kinematic pairs. The student can independently determine free vibrations and forced vibrations of discrete systems of one and of many degrees of freedom Subject contents Elements of machins and mechanisms, open chains, closed kinematic chains, classification of kinematic pairs and kinematical sets. Types of mechanisms – an overview. Structural analysis, mobility of mechanisms - structural equation for mechanisms, degrees of freedom, method used to determine positions, velocities and accelerations of components of mechanisms. The dynamics of mechanisms - kinetostatyki equation, determination of forces in kinematic pairs, differential equations of motion of mechanisms. The solution of equations of motion of free mechanisms. Balancing of planar mechanisms – static and dynamic. Free and		K6_U03	The student independently acquires knowledge of the most important concepts of theories of mechanisms i machines. The student can independently conduct a structural analysis of mechanism and he can determine their mobility. Student can designate independently position, speed and acceleration of elements of mechanisms. The student can independently determine equations of kinetostatics and the associated forces in kinematic pairs. The student can independently determine free and forced vibrations of discrete systems of one and of many degrees of	use methods and tools [SU1] Assessment of task		
pairs and kinematical sets. Types of mechanisms – an overview. Structural analysis, mobility of mechanisms - structural equation for mechanisms, degrees of freedom, method used to determine positions, velocities and accelerations of components of mechanisms. The dynamics of mechanisms - kinetostatyki equation, determination of forces in kinematic pairs, differential equations of motion of mechanisms. The solution of equations of motion of the mechanism. Balancing of planar mechanisms - static and dynamic. Free and		K6_U01	knowledge of the most important concepts of theories of mechanisms and machines. The student can independently conduct an analysis of structural mechanism and determine its mobility. Student can designate independently position, speed and acceleration of of elements of planar mechanisms. The student can independently determine equations kinetostatics and determine associated forces in kinematic pairs. The student can independently determine free vibrations and forced vibrations of discrete systems of one and of	use methods and tools [SU1] Assessment of task		
	Subject contents	Elements of machins and mechanisms, open chains, closed kinematic chains, classification of kinematic pairs and kinematical sets. Types of mechanisms – an overview. Structural analysis, mobility of mechanisms - structural equation for mechanisms, degrees of freedom, method used to determine positions, velocities and accelerations of components of mechanisms. The dynamics of mechanisms - kinetostatyki equation, determination of forces in kinematic pairs, differential equations of motion of mechanisms. The solution of equations of motion of the mechanism. Balancing of planar mechanisms - static and dynamic. Free and				

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Prerequisites and co-requisites	Mechanics including statics, kinematics, dynamics of mechanical systems. Mathematics including algebra, matrix calculus, differential and integral calculus, linear differential equations.				
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade		
and criteria	final test of the theory	56.0%	50.0%		
	colloquia with solving practical problems	56.0%	50.0%		
Recommended reading	Basic literature	Morecki A., Knapczyk J., Kędzior K.: Teoria mechanizmów i manipulatorów WNT 2002 Olędzki A.: Podstawy teorii maszyn i mechanizmów. WNT 1978			
	Supplementary literature	Miller S.; Teoria maszyn i mechanizmów – analiza układów kinematycznych; Oficyna Wydawnicza Politechniki Wrocławskiej; Wrocław 1996 Młynarski T., Listwan A., Pazderski E.; Zbiór zadań z teorii mechanizmów i maszyn do analizy kinematycznej mechanizmów; skrypt Politechniki Krakowskiej; Kraków 1992			
	eResources addresses	Teoria mechanizmów i dynamika maszyn, PG_00008954 - Moodle ID: 23736 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=23736			
Example issues/ example questions/ tasks being completed					
Work placement	Not applicable				

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