

Subject card

Subject name and code	Components of mechatronic systems, PG_00038856							
Field of study	Mechatronics, Mechatronics							
Date of commencement of studies	October 2020		Academic year of realisation of subject			2021/2022		
Education level	first-cycle studies		Subject group			Obligatory subject group in the field of study		
						Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery			at the university		
Year of study	2		Language of instruction		Polish			
Semester of study	4		ECTS credits		5.0			
Learning profile	general academic profile		Assessme	ssessment form		exam		
Conducting unit	Department of Mechanics and Mechatronics -> Faculty of Mechanical Engineering and Ship Technology							
Name and surname of lecturer (lecturers)	Subject supervisor	dr hab. inż. Ryszard Jasiński						
	Teachers		dr hab. inż. Ryszard Jasiński					
			dr inż. Marcin Bąk					
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM
of instruction	Number of study hours	20.0	0.0	30.0	0.0		0.0	50
	E-learning hours included: 0.0							
	Adresy na platformie eNauczanie:							
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study		SUM
	Number of study hours	50		6.0		69.0		125
Subject objectives	Familiarize students with the elements used in mechatronic devices							

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Lagratina automosa			
Learning outcomes	Course outcome	Subject outcome	Method of verification
	K6_U10	Student describes the structure and principle of operation of control elements, actuators and sensors in mechatronic systems. Student selects the basic elements for the mechatronic system. When formulating and solving mechatronics engineering tasks, the student is able to see their systemic and non-technical aspects.	[SU1] Assessment of task fulfilment [SU2] Assessment of ability to analyse information
	K6_W03	Student builds hydraulic and pneumatic systems. Student takes measurements. Student analyzes the results of the measurements. Student calculates measurement errors.	[SW3] Assessment of knowledge contained in written work and projects
	K6_U07	Student builds hydraulic and pneumatic systems. Student takes measurements. Student analyzes the results measurements. Student calculates measurement errors.	[SU2] Assessment of ability to analyse information [SU1] Assessment of task fulfilment
	K6_U06	Student describes the structure and principle of operation of control elements, actuators and sensors in mechatronic systems. Student selects the basic elements for the mechatronic system. Student is able to identify and formulate the specification of simple engineering tasks of a practical nature, characteristic of mechatronics.	[SU3] Assessment of ability to use knowledge gained from the subject [SU4] Assessment of ability to use methods and tools

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Subject contents					
	Lecture:Pneumatic, electric and hydraulic elements and sensors in mechatronic systems. Construction operation of actuators. Signal analysis and processing. Electromagnetic actuators. New kind of actuato Servo drives, stepper motors and their comparison. Hydraulic actuators. Classification of members of hydraulic systems. Pneumatic actuators. Control elements of mechatronic systems: electric, pneumatic hydraulic and their comparison. Sensors. Requirements for sensors.				
	Laboratory:				
	Sequential systems with pneumatic actuators. Pneumatic systems with time relays. Electropneumatic control. Construction and selection of a pneumatic actuator. Pneumatic systems with counters. Getting to know the elements of the mechatronic system MAS 200. Functional analysis of the MAS 200 system. Pneumatic analysis of the mechatronic system MAS 200. Electrical analysis of the mechatronic system MAS 200. Construction, operation and control of electric stepper motors. Hydraulic systems with accumulator. Sequential systems with hydraulic actuators. Testing the hydrostatic transmission.				
	Construction, operation, determination of the characteristics of control units for classic and proportional valves.				
Prerequisites and co-requisites					
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade		
		56.0%	60.0%		
		56.0%	40.0%		

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D	Dania litaratura	Hairran D. Conth W. Dann K. Machatranika matady and the the
Recommended reading	Basic literature	Heiman B., Gerth W., Popp K.: Mechatronika, metody, przykłady, tł. Gawrysiak M., Wydawnictwo Naukowe PWN, Warszawa, 2001
		Gawrysiak M.: Mechatronika i projektowanie mechatroniczne, Polit.
		Białostocka, Białystok, 1997
		Giergiel J., Uhl T.: Identyfikacja układów mechatronicznych, PWN,
		Warszawa, 1990
		Afanin A. Commonale D. Manhatunnilla. Clement Delita abmilisi
		Afonin A., Szymczak P.: Mechatronika, Skrypt Politechniki Szczecińskiej, Szczecin, 2001
		, , , , , , , , , , , , , , , , , , ,
		Cohorid D. Machataurilla, Dadasaurilla dia comitto taradaish i
		Schmid D.: Mechatronika. Podręcznik dla uczniów średnich i zawodowych szkół technicznych. Rok wydania 2002, wydawnictwo:
		REA
		Osiecki A.: Hydrostatyczny napęd maszyn. WNT, Warszawa 1998
		Totoota / tt. Tryarostaty 52-ty happy maszym. 1111, 1111 zawa 1666
		Stryczek S.: Napęd hydrostatyczny. Tom 1 i 2. WNT, Warszawa 1992
		Szenajch W.: Napęd i sterowanie pneumatyczne, PWN, Warszawa,
		2016
		Niegoda J., Pomierski W., Sterowanie pneumatyczne. Ćwiczenia
		laboratoryjne, Wydawnictwo Politechniki Gdańskiej, Gdańsk 1998
		Vademecum Hydrauliki, wyd. Bosch Rexroth
	Supplementary literature	-
	eResources addresses	
Example issues/		
example questions/		
tasks being completed		
Work placement	Not applicable	
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