



Subject card

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|---|---|--|-------------------------------------|------------|--|---------|-----|
| Subject name and code | Fundamentals of Automatics, PG_00055288 | | | | | | |
| Field of study | Transport and Logistics | | | | | | |
| Date of commencement of studies | October 2021 | Academic year of realisation of subject | | | 2022/2023 | | |
| Education level | first-cycle studies | Subject group | | | Obligatory subject group in the field of study Subject group related to scientific research in the field of study | | |
| Mode of study | Full-time studies | Mode of delivery | | | at the university | | |
| Year of study | 2 | Language of instruction | | | Polish | | |
| Semester of study | 4 | ECTS credits | | | 4.0 | | |
| Learning profile | general academic profile | Assessment form | | | assessment | | |
| Conducting unit | Institute of Ocean Engineering and Ship Technology -> Faculty of Mechanical Engineering and Ship Technology | | | | | | |
| Name and surname of lecturer (lecturers) | Subject supervisor | dr inż. Mohammad Ghaemi | | | | | |
| | Teachers | dr inż. Mohammad Ghaemi mgr inż. Damian Jakowski | | | | | |
| Lesson types and methods of instruction | Lesson type | Lecture | Tutorial | Laboratory | Project | Seminar | SUM |
| | Number of study hours | 30.0 | 15.0 | 0.0 | 0.0 | 0.0 | 45 |
| | E-learning hours included: 0.0 | | | | | | |
| Learning activity and number of study hours | Learning activity | Participation in didactic classes included in study plan | Participation in consultation hours | | Self-study | | SUM |
| | Number of study hours | 45 | 10.0 | | 45.0 | | 100 |
| Subject objectives | The objective is to learn the fundamentals of control theory and the structures and elements of basic automation systems, as well as general information about control system design. | | | | | | |
| Learning outcomes | Course outcome | Subject outcome | | | Method of verification | | |
| | [K6_W04] has a basic knowledge in IT, electronics, automation and control, computer graphics useful to understand the possibilities of their application in transport | The student is able to assess usefulness of typical methods and tools applied in engineering to select the proper method and tool for solving the simple problems in the range of control system | | | [SW1] Assessment of factual knowledge [SW3] Assessment of knowledge contained in written work and projects | | |
| | [K6_U05] can formulate a simple engineering task and its specification within the range of design, construction and operation of means and systems of transport | The student is able to formulate simple engineering problems and its specification in the range of automatics and robotics | | | [SU1] Assessment of task fulfilment [SU3] Assessment of ability to use knowledge gained from the subject | | |

| Subject contents | 1. Introduction and basic concepts 2. Classification of control systems 3. Modeling of dynamic systems and description of elements of automatic control systems 4. Types of mathematical models of dynamic systems: differential equation, transmittance, block diagram, linearization 5. Transition function and time characteristics 6. Feedback 7. Analysis of time-domain and frequency-domain control systems 8. Stability of linear control systems 9. Controls | | | | | | | | | | | |
|--------------------------------------|---|-------------------------------|--|--------------------------|---|-------------------------------|--------------------------------------|---|-------|------------------------------------|---|-------|
| Prerequisites and co-requisites | Pre-requisite subjects: 1. Mathematics 2. Physics | | | | | | | | | | | |
| Assessment methods and criteria | <table border="1" data-bbox="448 1010 1497 1137"> <thead> <tr> <th data-bbox="448 1010 799 1043">Subject passing criteria</th> <th data-bbox="804 1010 1139 1043">Passing threshold</th> <th data-bbox="1144 1010 1497 1043">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="448 1050 799 1099">Colloquium for credit from exercises</td> <td data-bbox="804 1050 1139 1099">51.0%</td> <td data-bbox="1144 1050 1497 1099">34.0%</td> </tr> <tr> <td data-bbox="448 1106 799 1137">Colloquium for credit from lecture</td> <td data-bbox="804 1106 1139 1137">56.0%</td> <td data-bbox="1144 1106 1497 1137">66.0%</td> </tr> </tbody> </table> | | | Subject passing criteria | Passing threshold | Percentage of the final grade | Colloquium for credit from exercises | 51.0% | 34.0% | Colloquium for credit from lecture | 56.0% | 66.0% |
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| Colloquium for credit from exercises | 51.0% | 34.0% | | | | | | | | | | |
| Colloquium for credit from lecture | 56.0% | 66.0% | | | | | | | | | | |
| Recommended reading | <table border="1" data-bbox="448 1144 1497 2078"> <tbody> <tr> <td data-bbox="448 1144 799 1200">Basic literature</td> <td colspan="2" data-bbox="804 1144 1497 1200">Nise N. S., Control System Engineering, 8th Edition, John Wiley & Sons Inc., 2019.</td> </tr> <tr> <td data-bbox="448 1207 799 2007">Supplementary literature</td> <td colspan="2" data-bbox="804 1207 1497 2007"> - Bubnicki Z., Teoria i algorytmy sterowania, Wydawnictwo Naukowe PWN, Warszawa, 2019. - Domachowski Z., Automatyka i robotyka podstawy, Wydawnictwo PG, Gdańsk, 2003. - Friedland B., Control System Design, McGraw Hill Co., 1986. - Kaczorek T., Podstawy teorii sterowania, Wydawnictwo Naukowe PWN, Warszawa, 2020. - Ogata K., Modern Control Engineering, 4th edition, Prentice-Hall, 2009. - Perycz S., Podstawy automatyki, skrypt dla Instytutu Okrętowego PG, Gdańsk, 1983. - Próchnicki W., Dzida M., Zbiór zadań z podstaw automatyki, skrypt dla studentów Wydziału Oceanotechniki i Okrętownictwa PG, Gdańsk, 1993. - Raven, F. H., Automatic control engineering, McGraw Hill Co., 1986. </td> </tr> <tr> <td data-bbox="448 2013 799 2078">eResources addresses</td> <td colspan="2" data-bbox="804 2013 1497 2078">Uzupełniające Adresy na platformie eNauczanie:</td> </tr> </tbody> </table> | | | Basic literature | Nise N. S., Control System Engineering , 8th Edition, John Wiley & Sons Inc., 2019. | | Supplementary literature | - Bubnicki Z., Teoria i algorytmy sterowania , Wydawnictwo Naukowe PWN, Warszawa, 2019. - Domachowski Z., Automatyka i robotyka podstawy , Wydawnictwo PG, Gdańsk, 2003. - Friedland B., Control System Design , McGraw Hill Co., 1986. - Kaczorek T., Podstawy teorii sterowania , Wydawnictwo Naukowe PWN, Warszawa, 2020. - Ogata K., Modern Control Engineering , 4th edition, Prentice-Hall, 2009. - Perycz S., Podstawy automatyki , skrypt dla Instytutu Okrętowego PG, Gdańsk, 1983. - Próchnicki W., Dzida M., Zbiór zadań z podstaw automatyki , skrypt dla studentów Wydziału Oceanotechniki i Okrętownictwa PG, Gdańsk, 1993. - Raven, F. H., Automatic control engineering , McGraw Hill Co., 1986. | | eResources addresses | Uzupełniające Adresy na platformie eNauczanie: | |
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| Example issues/ example questions/ tasks being completed | |
| Work placement | Not applicable |