

Subject card

Subject name and code	, PG_00056288								
Field of study	Ocean Engineering								
Date of commencement of studies	October 2021		Academic year of realisation of subject			2023/2024			
Education level	first-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	5		ECTS credits			2.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Faculty of Ocean Engineering and Ship Technology								
Name and surname of lecturer (lecturers)	Subject supervisor	dr inż. Mohammad Ghaemi							
	Teachers	dr inż. Mohammad Ghaemi							
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	:t	Seminar	SUM	
	Number of study hours	30.0	0.0	0.0	0.0		0.0	30	
	E-learning hours inclu					1		1	
Learning activity and number of study hours	Learning activity Participation in classes include plan				Self-study SUM				
	Number of study hours			3.0		17.0 50		50	
Subject objectives	The main aim of the subject is education of students in the range of 3 fundamentals of marine control systems: course and trajectory control, ship propulsion system control and roll stabilisation systems.								
Learning outcomes	Course out	Course outcome Subject outcome					Method of verification		
	[K6_U05] can formulate a simple engineering task and its specification within the range of design, construction and operation of ocean technology objects and systems		The student is able to formulate a simple engineering task and its specification in the field of design and operation of three most important ship control systems, i.e. course and trajectory control systems, propulsion control system, and the ship's roll stabilization system.			[SU3] Assessment of ability to use knowledge gained from the subject			
	[K6_W08] has knowledge of the principles of sustainable development		The student has knowledge of the principles of sustainable development in the field of ship automation; including basic knowledge in the field of analyzing and designing automation systems used in ship technology for guidance and control of ocean engineering facilities, taking into account motion stability, propulsion, marine and maneuvering features. The student has a structured			[SW1] Assessment of factual knowledge			
	knowledge on engineering methods and design tools allowing the conducting of projects within the construction and operation of ocean technology objects and systems		knowledge of engineering design methods enabling the implementation of conceptual designs in the field of major ship control systems, including the course and trajectory control system, the propulsion control system, and the ship's roll stabilization system.			knowledge			

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Subject contents	1. The concept and introduction and principle definitions 2. Mathematical model of ship motion 3. Environmental disturbances: wind, wave and current 4. Ship manoeuvrability 5. Ship course control 6. Ship trajectory control 7. Ship roll control 8. Ship speed control 9. Ship motion model identification					
Prerequisites and co-requisites	Preceding subjects: 1. Fundamentals of ocean engineering 2. Mechanics I 3. Fundamentals of ship power plants, 2. Fundamentals of automatics.					
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade			
	1 colloquium, 100 points, duration: 1 hour	56.0%	96.0%			
	Presence and activity: 5 points	0.0%	4.0%			
Recommended reading	Basic literature	1. 2. Fossen T. I., Handbook of Marine Craft Hydrodynamics and Motion Control, John Wiley & Sons, 2011. 2. Thor I. Fosen: Marine Control Systems, Marine Cybernetics AS, 2002.				
	Supplementary literature	1. Thor I. Fossen: Guidance and Control of Ocean Vehicles. John Wiley and Sons, 1994.				
	eResources addresses	Adresy na platformie eNauczanie:				
Example issues/ example questions/ tasks being completed						
Work placement	Not applicable					

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