

Subject card

Subject name and code	, PG_00056312								
Field of study	Ocean Engineering								
Date of commencement of studies	October 2021		Academic year of realisation of subject			2023/2024			
Education level	first-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	5		ECTS credits			4.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Institute of Ocean Engineering and Ship Technology -> Faculty of Mechanical Engineering and Ship Technology								
Name and surname of lecturer (lecturers)	Subject supervisor		dr hab. inż. Marek Dzida						
	Teachers		dr hab. inż. Marek Dzida						
			dr inż. Mohammad Ghaemi						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
	Number of study hours	30.0	15.0	0.0	0.0		0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity Participation in classes including plan				Self-study		SUM		
	Number of study hours	45		6.0		49.0		100	
Subject objectives	The objective is to learn the fundamentals of control theory and the structures and elements of basic automation systems, as well as general information about control system design.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_W05] has an organized knowledge on design, construction and operation of ocean technology objects and systems		The student is able to assess usefulness of typical methods and tools applied in engineering to select the proper method and tool for solving the simple problems			[SW3] Assessment of knowledge contained in written work and projects			
	[K6_W04] has a basic knowledge in IT, electronics, automation and control, computer graphics useful to understand the possibilities of their application in ocean technology		The student has the knowledge of methods and tools applied for design of control system			[SW1] Assessment of factual knowledge			
	[K6_U05] can formulate a simple engineering task and its specification within the range of design, construction and operation of ocean technology objects and systems		Able to formulate a simple task, and its specification engineering of automation of technological process			[SU3] Assessment of ability to use knowledge gained from the subject			

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 Classification of control systems Modeling of dynamic systems and description of elements of automatic control systems Types of mathematical models of dynamic systems: differential equation, transmittance, block dilinearization Transition function and time characteristics 	agram,							
Types of mathematical models of dynamic systems: differential equation, transmittance, block dilinearization	agram,							
linearization	agram,							
5. Transition function and time characteristics	4. Types of mathematical models of dynamic systems: differential equation, transmittance, block diagram, linearization							
	5. Transition function and time characteristics							
6.Feedback								
7.Analysis of time-domain and frequency-domain control systems								
8.Stability of linear control systems								
9. Controlls								
Prerequisites and co-requisites Pre-requisite subjects:	Pre-requisite subjects:							
1. Mathematics								
2. Physics	2. Physics							
Assessment methods Subject passing criteria Passing threshold Percentage of the final	l grade							
and criteria Colloquium for credit from lecture 50.0% 60.0%								
Colloquium for credit from exercises 50.0% 40.0%								
Recommended reading Basic literature 1. Raven, F. H., Automatic control engineering, McGraw Hill C	o., 1986.							
2. Nise N. S., Control system engineering, John Whiley & Son 2000.	ıs Inc.,							
3. Friedland B., Control System Design, McGraw Hill Co., 198	6.							
Supplementary literature								
1 Ogata K., Modern Control Engineering, 4th edition, Prentic 2002.	e Hall,							
eResources addresses Adresy na platformie eNauczanie: Teoria sterowania okrętowych ukł automatyki, PG_00056312	- Moodle							
ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=250	159							
	059							

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