

## Subject card

Subject name and code	, PG_00056312								
Field of study	Ocean Engineering								
Date of commencement of studies	October 2021		Academic year of realisation of subject			2023/2024			
Education level	first-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	5		ECTS credits			4.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Institute of Ocean Engineering and Ship Technology -> Faculty of Mechanical Engineering and Ship Technology								
Name and surname of lecturer (lecturers)	Subject supervisor		dr hab. inż. Marek Dzida						
	Teachers		dr hab. inż. Marek Dzida						
			dr inż. Mohammad Ghaemi						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
	Number of study hours	30.0	15.0	0.0	0.0		0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity Participation in classes including plan					Self-study SUM		SUM	
	Number of study hours	45		6.0		49.0		100	
Subject objectives	The objective is to learn the fundamentals of control theory and the structures and elements of basic automation systems, as well as general information about control system design.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_W05] has an organized knowledge on design, construction and operation of ocean technology objects and systems		The student is able to assess usefulness of typical methods and tools applied in engineering to select the proper method and tool for solving the simple problems			[SW3] Assessment of knowledge contained in written work and projects			
	[K6_W04] has a basic knowledge in IT, electronics, automation and control, computer graphics useful to understand the possibilities of their application in ocean technology		The student has the knowledge of methods and tools applied for design of control system			[SW1] Assessment of factual knowledge			
	[K6_U05] can formulate a simple engineering task and its specification within the range of design, construction and operation of ocean technology objects and systems					[SU3] Assessment of ability to use knowledge gained from the subject			

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2. Classification of control systems 3. Modeling of dynamic systems and description of elements of automatic control systems 4. Types of mathematical models of dynamic systems: differential equation, transmittance, block diagram, linearization 5. Transition function and time characteristics 6. Feedback 7. Analysis of time-domain and frequency-domain control systems 9. Controlls  Prerequisites and co-requisites 1. Mathematics 2. Physics  Assessment methods and criteria Colloquium for credit from lecture 50.0% 98.0% 40.0% Colloquium for credit from 50.0% 40.0% Colloquium for credit from secture 50.0% 98.0% 40.0% Colloquium for credit from 20.0% 90.0% 40.0% Colloquium for credit from 20.0% 20.0% 40.0% Colloquium for credit from 20.0% 20.0% 40.0% Colloquium for credit from 20.0% 20.0% 40.0% Colloquium for credit from 20.0% Colloquium for credit	Subject contents	Introduction and basic concepts							
4. Types of mathematical models of dynamic systems: differential equation, transmittance, block diagram, linearization  5. Transition function and time characteristics  6. Feedback  7. Analysis of time-domain and frequency-domain control systems  8. Stability of linear control systems  9. Controlls  Pre-requisites  1. Mathematics  2. Physics  Assessment methods and criteria  Colloquium for credit from lecture 1. Raven, F. H., Automatic control engineering, McGraw Hill Co., 1986.  Recommended reading  Basic literature  1. Raven, F. H., Automatic control engineering, John Whiley & Sons Inc., 2006. 3. Friedland B., Control system engineering, John Whiley & Sons Inc., 2006.  Supplementary literature  1. Ogata K., Modern Control Engineering, 4th edition, Prentice Hall, 2002.  Resources addresses  Adresy na platformie eNauczanie: Teoria saterovania okrętowych uki automatyki, PG_00086312 - Moodel ID-25059 https://enauczanie.pg.edu.pl/moodelcourserview.php?id=25059  Example issues/ example questions/ tasks being completed		2. Classification of control systems							
linearization		3. Modeling of dynamic systems and description of elements of automatic control systems							
6.Feedback 7.Analysis of time-domain and frequency-domain control systems 8.Stability of linear control systems 9. Controlls Prerequisites and co-requisites 1. Mathematics 2. Physics  Assessment methods and criteria  Subject passing criteria Colloquium for credit from lecture Colloquium for credit from lecture So.0% Colloquium for credit from lecture Colloquium for credit from lecture 1. Raven, F. H., Automatic control engineering, McGraw Hill Co., 1986.  Recommended reading  Basic literature  1. Raven, F. H., Automatic control engineering, John Whiley & Sons Inc., 2000. 3. Friedland B., Control system engineering, John Whiley & Sons Inc., 2000. 4. Nise N. S., Control system Design, McGraw Hill Co., 1986.  Supplementary literature  2. Nise N. S., Control system Design, McGraw Hill Co., 1986.  Supplementary literature  1. Ogata K., Modern Control Engineering, 4th edition, Prentice Hall, 2002.  Resources addresses Adresy na platformie eNauczanie: Teoria sterowania okrętowych ukł automatyki, PG_00056312 - Moodile ID-25059 https://enauczanie.pg.edu.pl/moodile/course/view.php?id=25059									
7. Analysis of time-domain and frequency-domain control systems 8. Stability of linear control systems 9. Controlls  Pre-requisites and co-requisites  1. Mathematics 2. Physics  Assessment methods and criteria Colloquium for credit from lecture 50.0% 60.0% Colloquium for credit from lecture 50.0% 40.0% Colloquium for credit from exercises  Recommended reading  Basic literature  1. Raven, F. H., Automatic control engineering, McGraw Hill Co., 1986. 2. Nise N. S., Control system engineering, John Whiley & Sons Inc., 2000. 3. Friedland B., Control System Design, McGraw Hill Co., 1986.  Supplementary literature  1. Ogata K., Modern Control Engineering, 4th edition, Prentice Hall, 2002.  eResources addresses  Adresy na platformie eNauczanie: Teoria sterowania okrętowych uki automatyki, PG_00056312 - Moodle ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059		5. Transition function and time characteristics							
8. Stability of linear control systems 9. Controlls  Pre-requisites and co-requisites 1. Mathematics 2. Physics  Assessment methods and criteria  Colloquium for credit from lecture 50.0% 60.0% 40.0% Colloquium for credit from exercises  Recommended reading  Basic literature  1. Raven, F. H., Automatic control engineering, McGraw Hill Co., 1986.  2. Nise N. S., Control system engineering, John Whiley & Sons Inc., 2000. 3. Friedland B., Control System Design, McGraw Hill Co., 1986.  Supplementary literature  1. Ogata K., Modern Control Engineering, 4th edition, Prentice Hall, 2002.  eResources addresses  Adresy na platformie eNauczanie: Teoria sterowania okrętowych ukł automatyki, PG_00056312 - Moodie ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059		6.Feedback							
Prerequisites and co-requisites  Pre-requisite subjects:  1. Mathematics 2. Physics  Assessment methods and criteria  Subject passing criteria Colloquium for credit from lecture Colloquium for credit from lecture Exercises  Passing threshold Percentage of the final grade 60.0% Colloquium for credit from lecture 10.0% Percentage of the final grade 10.0%									
Pre-requisites and co-requisites  1. Mathematics 2. Physics    Subject passing criteria									
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2. Physics    Subject passing criteria		Pre-requisite subjects:							
Assessment methods and criteria    Subject passing criteria   Passing threshold   Percentage of the final grade		1. Mathematics							
and criteria    Colloquium for credit from lecture   50.0%   60.0%   40.0%		2. Physics							
Colloquium for credit from exercises    Solution   Solu	Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade					
Recommended reading  Basic literature  1. Raven, F. H., Automatic control engineering, McGraw Hill Co., 1986.  2. Nise N. S., Control system engineering, John Whiley & Sons Inc., 2000.  3. Friedland B., Control System Design, McGraw Hill Co., 1986.  Supplementary literature  1 Ogata K., Modern Control Engineering, 4th edition, Prentice Hall, 2002.  eResources addresses  Adresy na platformie eNauczanie: Teoria sterowania okrętowych ukł automatyki, PG_00056312 - Moodle ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059  Example issues/ example questions/ tasks being completed	and criteria			60.0%					
2. Nise N. S., Control system engineering, John Whiley & Sons Inc., 2000.  3. Friedland B., Control System Design, McGraw Hill Co., 1986.  Supplementary literature  1 Ogata K., Modern Control Engineering, 4th edition, Prentice Hall, 2002.  eResources addresses  Adresy na platformie eNauczanie: Teoria sterowania okrętowych ukł automatyki, PG_00056312 - Moodle ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059  Example issues/ example questions/ tasks being completed			50.0%	40.0%					
2000.  3. Friedland B., Control System Design, McGraw Hill Co., 1986.  Supplementary literature  1 Ogata K., Modern Control Engineering, 4th edition, Prentice Hall, 2002.  eResources addresses  Adresy na platformie eNauczanie: Teoria sterowania okrętowych ukł automatyki, PG_00056312 - Moodle ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059  Example issues/ example questions/ tasks being completed	Recommended reading	Basic literature	1. Raven, F. H., Automatic control engineering, McGraw Hill						
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eResources addresses  Adresy na platformie eNauczanie: Teoria sterowania okrętowych ukł automatyki, PG_00056312 - Moodle ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059  Example issues/ example questions/ tasks being completed		Supplementary literature	5. Friedrand B., Control Cystem Design, Wechaw Till Co., 1966.						
Teoria sterowania okrętowych ukł automatyki, PG_00056312 - Moodle ID: 25059 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=25059  Example issues/ example questions/ tasks being completed									
example questions/ tasks being completed		kł automatyki, PG_00056312 - Moodle							
	example questions/								
Work placement Not applicable	-	Not applicable							

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