



Subject card

Subject name and code	PROGRAMMABLE CONTROLLERS, PG_00053202						
Field of study	Automation, Robotics and Control Systems						
Date of commencement of studies	October 2022	Academic year of realisation of subject				2024/2025	
Education level	first-cycle studies	Subject group				Obligatory subject group in the field of study Subject group related to scientific research in the field of study	
Mode of study	Full-time studies	Mode of delivery				at the university	
Year of study	3	Language of instruction				Polish	
Semester of study	5	ECTS credits				4.0	
Learning profile	general academic profile	Assessment form				assessment	
Conducting unit	Department of Intelligent and Decision Support Systems -> Faculty of Electrical and Control Engineering						
Name and surname of lecturer (lecturers)	Subject supervisor	dr inż. Jarosław Tarnawski					
	Teachers	dr inż. Jarosław Tarnawski dr inż. Bartosz Puchalski dr inż. Tomasz Rutkowski					
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	30.0	0.0	30.0	0.0	0.0	60
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	60		6.0		34.0	100
Subject objectives	Understanding of the tasks, functions and location of PLC in the control system. Knowledge of PLC programming methods. Practical programming skills in ladder language and structured text. Ability to implement basic control algorithms in PLC. Understanding the principles of implementing more complex control algorithms. Ability to design and implement PLC cooperation with the SCADA system using dedicated and unified OPC communication servers. Using PLC to work in the loop (Hardware-in-the-loop), including connecting a physical object or real-time system.						
Learning outcomes	Course outcome	Subject outcome			Method of verification		
	[K6_U05] can use analytical and simulation methods to solve tasks in the field of automation and robotics and use various techniques to carry out engineering tasks related to automation and robotics devices and systems	The student is able to build a control system in the so-called hardware loop with the simulated object, PLC and SCADA system.			[SU1] Assessment of task fulfilment		
	[K6_K02] can work in a group taking on different roles in it	Working in a group, students acquire leader and subordinate skills.			[SK1] Assessment of group work skills		
	[K6_W06] knows the structure of computers and microprocessors and the tasks of operating systems, has basic knowledge of the basics of computer software, drivers, microprocessor technology, design of simple algorithms and the operation of information networks	The student knows the structure of a PLC and is able to select the right PLC for the automation task. The student is able to include this device in the control system, configure and program it.			[SW3] Assessment of knowledge contained in written work and projects		

Subject contents	<p>Control structures and the place of PLC in these structures. Historical outline of the creation of PLCs replacing contactor-relay control systems. Main features and requirements for PLC: reliability, flexibility, ease and programming capabilities, scalability, communication capabilities. IEC-1131 and EN61131 standards. Principle of operation of PLC. Duty cycle. PLC as devices that meet the real-time requirement. Issues in the selection of PLC for the task of automating the technological process. PLC programming methods, languages: ladder, instruction list, sequential function diagrams, function block diagrams, structured text. Control and regulation algorithms in PLC. Embedded algorithms, methods of program implementation of simple control and regulation methods. Methods of implementing selected discrete control algorithms. Communication issues in PLC: data exchange between controllers, data exchange with other elements of the control structure. Limitations on the applicability of PLC. PLC cooperation with supervisory control systems, SCADA data acquisition systems and databases using the universal OPC data exchange method.</p>		
Prerequisites and co-requisites	Completed courses: Real-time systems, Industrial IT networks		
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	Laboratory assessment	50.0%	50.0%
	Oral theoretical examination	50.0%	50.0%
Recommended reading	Basic literature	1. Legierski T., Kasprzyk J., Wyrwał J., Hajda J.: Programowanie sterowników PLC, Wydawnictwo Pracowni Komputerowej Jacka Skalmierskiego, Gliwice, 1998 2. Kwaśniewski J.: Programowalne sterowniki przemysłowe w systemach sterowania, ZP Roma-Pol, 1999 3. Pasierbński J., Legierski T.: Programowanie sterowników PLC, Wydawnictwo Pracowni Komputerowej Jacka Skalmierskiego, 1998 4. Kasprzyk J.: Programowanie sterowników przemysłowych, WNT, 2013	
	Supplementary literature	5. Tatjewski P.: Sterowanie zaawansowane obiektów przemysłowych, Akademicka Oficyna Wydawnicza EXIT, 2002 6. Grega W., Metody i algorytmy sterowania cyfrowego w układach scentralizowanych i rozproszonych, Wydawnictwo AGH, 2004 7. Broel-Plater Bogdan, Układy wykorzystujące sterowniki PLC, PWN, 2015 8. Kwaśniewski J., Sterowniki PLC w praktyce inżynierskiej, btc, 2008	
	eResources addresses	Adresy na platformie eNauczenie: STEROWNIKI PROGRAMOWALNE [ARiSS][2024/25] - Moodle ID: 39785 https://enauczenie.pg.edu.pl/moodle/course/view.php?id=39785	
Example issues/ example questions/ tasks being completed	Design and build a control system using PLC for a selected laboratory facility		
Work placement	Not applicable		

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