

## 。 GDAŃSK UNIVERSITY OF TECHNOLOGY

## Subject card

Subject name and code	Basics of Robotics and Mechatronics, PG_00038092								
Field of study	Automation, Robotics and Control Systems								
Date of commencement of studies	October 2022		Academic year of realisation of subject			2023/2024			
Education level	first-cycle studies		Subject group			Obligatory subject group in the field of study Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	2		Language of instruction			Polish			
Semester of study	3		ECTS credits			5.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Mechatronics and High Voltage Engineering -> Faculty of Electrical and Control Engineering						ol Engineering		
Name and surname of lecturer (lecturers)	Subject supervisor	prof. dr hab. inż. Grzegorz Redlarski							
	Teachers		dr inż. Mariusz Dąbkowski						
			prof. dr hab. inż. Grzegorz Redlarski						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
	Number of study hours	30.0	0.0	15.0	0.0		0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	45		4.0		76.0		125	
Subject objectives	The aim of the course is introduction into the basic issues concerning stationary industrial robots such as: various divisions of robots, their tasks, construction, safety issues, methods of their study, tasks of control systems, Denavit-Hartenberg notation, and basic information about robot power supplies and mechatronic design.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_W08] knows the basics of equipment selection and control of electrical machines and servos		The student knows the rules of selecting and configuring basic control systems used in automation and robotics			[SW1] Assessment of factual knowledge			
	[K6_U07] can build and analyze models of systems and systems in the field related to control systems and automation		The student has knowledge and skills in the field of modeling and designing of professional automation and robotics systems			[SU1] Assessment of task fulfilment			
	[K6_K04] can react in abnormal and emergency situations, threats to health and life when using automation and robotics components and systems		The student has the knowledge and skills of safe use of automation and robotics elements and systems			[SK2] Assessment of progress of work			

Subject contents	Introduction to robotics: robotics and its scope, basic concepts, sectionsof robotics, systematization, robotics in the twenty-first century, historical development of robotics and the current situation, the scope and problems of robotics research, laws of robotics. Industrial robots as a tool: the interpretation of different forms of human work, technical examples, reasons and stages of development of robots, definitions and classification of industrial robots. Introduction to the theory of machines and mechanisms: 2D mechanisms and manipulators. Construction of industrial robots: the basic units of industrial robots and systems, monolithic robots with serial kinematic structure, modular construction and a serial kinematic structure, robots and manipulators of parallel structures, robots and manipulators of hybrid structures, mobile robots. Drives of industrial robots: Optimes and heads of industrial robots: general characteristics, design, examples of grippers and tools. Control and programming of robots: manipulator trajectory planning - basic concepts, tasks, control systems, computer numerical control, programming of robots by learning. Some aspects of the introduction of industrial robots to the industry: an overview of the methodology of introduction robots to industry. The characteristics of industrial robots and their study: movement, accuracy and repeatability, durability and resistance to environmental exposure - control tests at the factory. Safety on robotics converters and limiters of robot coordinates and manipulated objects. Examples of the use of robots in system, methods of securing robotic systems. Basic knowledge of sensory robots: converters and limiters of robot coordinates and manipulated objects. Examples of the use of robots in industry: robotic workstation - welding, laser and plasma cutting, handling and palletizing, machining, robotics. Industrial robots of mechatronic construction, the general concept of mechatronics: what is mechatronics, example of mechatronic construction, the ge						
Prerequisites and co-requisites							
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade				
and criteria	Lecture reports	60.0%	60.0%				
	Laboratory reports	60.0%	40.0%				
Recommended reading	Basic literature Supplementary literature	<ol> <li>Craig J.: Wprowadzenie do robotyki. Mechanika i sterowanie. Wydawnictwa Naukowo-Techniczne. Warszawa: 1993.</li> <li>Spong. M. W., Vidyasagar M.: Dynamika i sterowanie robotów. Wydawnictwa Naukowo-Techniczne. Warszawa: 1997.</li> <li>Morecki A, Knapczyk J.: Podstawy robotyki. Warszawa: WNT 1999.</li> <li>Niederliński A.: Roboty przemysłowe. Warszawa: WSiP 1981.</li> <li>Honczarenko J.: Roboty przemysłowe. Budowa i zastosowanie. WNT Warszawa, 2004.</li> <li>Grono A: Podstawy Robotyki - Laboratorium. Skrypt Politechniki Gdańskiej: 2001. 2. Morecki A., Knapczyk. J.: Podstawy robotyki. Teoria i elementy manipulatorów i robotów. Wydawnictwa Naukowo-Techniczne. Warszawa: 1999.</li> </ol>					
		2. Dąbkowski M. Podstawy robotyki - Laboratorium. Skrypt					
	eResources addresses	Politechniki Gdańskiej: 2012. Adresy na platformie eNauczanie: PODSTAWY ROBOTYKI I MECHATRONIKI [2023/24] - Moodle ID: 32101 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=32101					
Example issues/ example questions/ tasks being completed	<ol> <li>Architecture and organization in mechatronics systems</li> <li>The problem of simple and inverse kinematics</li> </ol>						
	3. The essence of the state detection and control in mechatronics systems						
	<ul><li>4. The essence of power systems in robotics and mechatronics systems</li><li>5. Management in distributed systems - systems and devices of mechatronics and robotics</li></ul>						
Work placement	Not applicable	Not applicable					

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