



Subject card

Subject name and code	, PG_00056123						
Field of study	Mechatronics						
Date of commencement of studies	October 2022	Academic year of realisation of subject			2024/2025		
Education level	first-cycle studies	Subject group					
Mode of study	Full-time studies	Mode of delivery			at the university		
Year of study	3	Language of instruction			Polish		
Semester of study	6	ECTS credits			2.0		
Learning profile	general academic profile	Assessment form			assessment		
Conducting unit	Institute of Mechanics and Machine Design -> Faculty of Mechanical Engineering and Ship Technology						
Name and surname of lecturer (lecturers)	Subject supervisor	dr hab. inż. Ryszard Jasiński					
	Teachers						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	15.0	0.0	0.0	30
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan	Participation in consultation hours	Self-study	SUM		
	Number of study hours	30	0.0	0.0	30		
Subject objectives	To acquaint students with the structure and principle of operation of mechatronic devices in medicine						
Learning outcomes	Course outcome	Subject outcome			Method of verification		
	[K6_W08] knows and understands design and production processes of elements and simple mechatronic devices	Student understands the processes of designing and manufacturing elements and simple mechatronic devices used in medicine.			[SW3] Assessment of knowledge contained in written work and projects [SW2] Assessment of knowledge contained in presentation		
	[K6_W10] has a basic knowledge about development trends in terms of engineering and technical sciences and scientific disciplines: Mechanical Engineering, Automation, Electronics and Electrical Engineering, adequate for Mechatronics course	Student has a basic knowledge of development trends in the field technical sciences and scientific disciplines: Mechanical Engineering and Automation, Electronics and Electrical Engineering, appropriate for the field of Mechatronics studies. Student explains the structure and principle of operation of mechatronic devices in medicine.			[SW3] Assessment of knowledge contained in written work and projects		
	[K6_U05] is able to use properly chosen tools to compare design solutions of elements and mechatronics systems according to given application and economic criterions (e.g. power demand, speed, costs)	Student is able to use properly selected tools in the basic scope in order to compare the design solutions of mechatronic elements and systems used in medicine, due to the set operational and economic criteria.			[SU1] Assessment of task fulfilment		
	[K6_U06] is able to identify and formulate specification of simple, practical engineering tasks, distinctive for mechatronics	Student is able to identify and formulate the specification of simple engineering tasks of a practical nature, characteristic of mechatronic devices used in medicine.			[SU2] Assessment of ability to analyse information		

Subject contents	<p>Construction and operation of respirators. Transport devices (transport trolleys, stair climbers, transport vehicles). Upper limb and torso braces. Finger, upper and lower limb prostheses. Designing a bionic arm (pneumatic muscles, equation of motion, kinematic diagram). Units (elements and equipment, pneumatic diagrams). Dental compressors. Devices for supporting blood circulation (human heart, cardiovascular support, counterpulsation methods, peristaltic pumps, artificial hearts). Kidney dialysis devices (kidney function, hemodialysis, artificial kidney functional system, semi-permeable membrane, peritoneal dialysis). Construction and operation of endoscopes. X-ray machine (construction of the X-ray apparatus, power supply system, construction of the X-ray tube, X-ray machines). Medical robots (classification of medical robots, assistant robots, precise positioning and displacement systems, manipulators and diagnostic cameras). Surgical robots (telem manipulators, ZEUS and Robin Heart surgical robots, surgical materials and tools). Urology robot (construction of the MrBot robot, construction and control of the PneuStep motor).</p>											
Prerequisites and co-requisites	<p>Basics of automations</p> <p>Basics of hydraulics and pneumatics</p> <p>Components of mechatronic systems</p>											
Assessment methods and criteria	<table border="1"> <thead> <tr> <th data-bbox="453 878 794 907">Subject passing criteria</th> <th data-bbox="794 878 1139 907">Passing threshold</th> <th data-bbox="1139 878 1482 907">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="453 907 794 936">Laboratory</td> <td data-bbox="794 907 1139 936">56.0%</td> <td data-bbox="1139 907 1482 936">50.0%</td> </tr> <tr> <td data-bbox="453 936 794 965">Midterm colloquium</td> <td data-bbox="794 936 1139 965">56.0%</td> <td data-bbox="1139 936 1482 965">50.0%</td> </tr> </tbody> </table>			Subject passing criteria	Passing threshold	Percentage of the final grade	Laboratory	56.0%	50.0%	Midterm colloquium	56.0%	50.0%
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Example issues/ example questions/ tasks being completed	-											
Work placement	Not applicable											

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