

Subject card

Subject name and code	, PG_00056120								
Field of study	Mechatronics								
Date of commencement of studies	October 2022		Academic year of realisation of subject			2024/2025			
Education level	first-cycle studies		Subject group						
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	6		ECTS credits			2.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Institute of Mechanics	Design -> Faculty of Mechanical Eng			ineering and Ship Technology				
Name and surname	Subject supervisor	dr inż. Paweł Załuski							
of lecturer (lecturers)	Teachers		dr inż. Paweł Załuski						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
	Number of study hours	15.0	0.0	15.0 0.0			0.0	30	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in classes include plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	30		0.0		0.0		30	
Subject objectives	The aim of the course is to familiarise students with the construction and operation of mechatronic elements and systems with electro-hydraulic and electro-pneumatic control, including programmable systems.								
Learning outcomes	Course outcome Subject outcome Method of verification					fication			
	[K6_W08] knows and understands design and production processes of elements and simple mechatronic devices		The student knows and understands the processes and issues related to the construction and operation of mechatronic elements and systems with electrohydraulic and electropneumatic control, including programmable ones.			[SW1] Assessment of factual knowledge			
	[K6_U06] is able to identify and formulate specification of simple, practical engineering tasks, distinctive for mechatronics		The student is able to identify and formulate functions and methods of implementation for simple mechatronic engineering tasks in the field of electrohydraulic and electropneumatic drive and control.			[SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject [SU1] Assessment of task fulfilment			
	[K6_W10] has a basic knowledge about development trends in terms of engineering and technical sciences and scientific disciplines: Mechanical Engineering, Automation, Electronics and Electrical Engineering, adequate for Mechatronics curse		The student has basic knowledge of development trends in the field of technical sciences and scientific disciplines: hydrotronics and pneumotronics			[SW2] Assessment of knowledge contained in presentation [SW1] Assessment of factual knowledge			
	[K6_U05] is able to use properly choosen tools to compare design solutions of elements and mechatronics systems according to given application and economic crtierions (e.g. power demand, speed, costs)		Students will be able to compare design solutions of hydrotronic and pneumotronic components and systems due to given application criteria, e.g. speed of operation, effect of load on speed, energy consumption, power.			[SU3] Assessment of ability to use knowledge gained from the subject [SU2] Assessment of ability to analyse information			

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Subject contents								
	Hydrotronics. Examples of application of hydraulic systems with electric and electronic control. Types of electrohydraulic control. Transducers. Switching control. Electromagnetically operated directional control valves. Systems with electromagnetically operated directional control valves. Proportional control. Proportional solenoids. Proportional directional valves. Servo-steering. Servo-valves with barometric, mechanical and electrical feedback. Static and dynamic characteristics of proportional valves and servo valves. Proportional control and servo control systems. Hydraulic amplifiers with electric stepper motors. Computer control systems for electrohydraulic servo drives. Hydraulic control systems for manipulators and robots. Pneumotronics. Application of pneumatic drives with electrical and programmable control. Types and control of compressors. Electropneumatic control. Types of electropneumatic control. Sensors used in pneumatics. Switchable electropneumatic valves. Relay technology. Electrical components used in electropneumatic control systems. Switching control systems. Digital electropneumatic control. Electropneumatic positioning systems. Pneumatic servo valves and servo drives. Programmable controls. Pneumatic systems with PLCs.							
Prerequisites and co-requisites	Knowledge of general mechanics, hydrostatics, hydraulics and pneumatics							
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade					
and criteria	tests	56.0%	100.0%					
Recommended reading	Basic literature	Pizoń A.: Hydrauliczne i elektrohydrauliczne układy sterowania i regulacji. WNT Warszawa 1987 Pizoń A.: Elektrohydrauliczne ianalogowe i cyfrowe układy automatyki. WNT Warszawa 1995 Schmid D. i inni: Mechatronika. For the polish edition REA. Warszawa 2002						
	Supplementary literature	Vademecum Hydrauliki. Tom 2. Technika hydraulicznego steowania zaworami proporcjonalnymi i serwozaworami. Mannesman Rexroth Deppert W., Stoll K.: Pneumtische Steuerungen. Vogel Buchverlag. Würzburg 1994.						
		Backe W., Goedecke WD.: Steurungs- und Schaltungstechnik I. Institut für hydraulische und pneumatische Antriebe und Steuerungen RWTH Aachen. Backe W.: Steurungs-und Schaltungtechnik II. Institut für hydraulische und pneumatische Antriebe und Steuerungen RWTH Aachen. Holejko D. i inni: Pneumatyczne urządzenia automatyki. Wydawnictwa PW. Warszawa 1986.						
	eResources addresses	dresy na platformie eNauczanie: ydrotronika i Pneumotronika, W/L, MTR, sem. 6, letni, 2024/25 - loodle ID: 44229 ttps://enauczanie.pg.edu.pl/moodle/course/view.php?id=44229						
Example issues/ example questions/ tasks being completed	principle of operation of proportional solenoideffect of load on the movement of actuators in systems with proportional valvesLoad sensing systemsprinciple of operation of hydraulic servo-valvesstepping units in pneumatic systems							
Work placement	Not applicable							

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