

Subject card

Subject name and code	Mechatronic design, PG_00033865							
Field of study	Nanotechnology							
Date of commencement of studies	October 2022		Academic year of realisation of subject			2024/2025		
Education level	first-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery			at the university		
Year of study	3		Language of instruction			Polish		
Semester of study	5		ECTS credits			2.0		
Learning profile	general academic profile		Assessment form			assessment		
Conducting unit	Department of Mechanics and Mechatronics -> Faculty of Mechanical Engineering and Ship Technology							
Name and surname of lecturer (lecturers)	Subject supervisor	prof. dr hab. inż. Krzysztof Kaliński						
	Teachers		dr inż. Tomasz Fąs					
		prof. dr hab. inż. Krzysztof Kaliński						
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM
of instruction	Number of study hours	15.0	0.0	0.0	15.0		0.0	30
	E-learning hours included: 0.0							
Learning activity and number of study hours	Learning activity Participation in classes include plan				Self-study SUM			
	Number of study hours 30			1.0		19.0		50
Subject objectives	Acquiring basic knowledge and skills in scope of modelling of mechatronic systems and mechatronic design.							
Learning outcomes	Course out	Subject outcome			Method of verification			
	K6_W09					[SW1] Assessment of factual knowledge		
	K6_U07		design methods mechatronic systems			[SU3] Assessment of ability to use knowledge gained from the subject [SU4] Assessment of ability to use methods and tools		
	K6_U04		related to functioning			[SU2] Assessment of ability to analyse information [SU4] Assessment of ability to use methods and tools		
Subject contents	LECTURES. Basic terms and features of mechatronic design. Modeling in mechatronics. Models of elements of mechatronic systems. Analogies between physical environments. Equations of dynamics in generalized coordinates. Transfer function. Static characteristics. Mechatronic design issues. Methods of implementing mechatronic projects. Modeling of multibody systems. Natural vibrations of systems with a finite number of degrees of freedom. Multidimensional control systems. LABORATORY. Identification of mechatronic component in the projects. Propositions of mechatronic solutions and concept of their performance.							

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Prerequisites and co-requisites							
	Introduction to electronics and electrical engineering.						
	Fundamentals of automatic control						
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade				
	Project	100.0%	50.0%				
	Passing colloquium	50.0%	50.0%				
Recommended reading	Basic literature	 Gawrysiak M.: Mechatronics and mechatronic design. Białystok: The Publication of BUT 1997 (accessible in internet). Heimann B., Gerth W., Popp K.: Mechatronics. Components methods examples. Warszawa: Scientific Publication PWN 2001. Mechatronic design. Chosen problems. (Ed. T. Uhl). Kraków: Chair of Robotics and Mechatronics AGH, every year since 2006. Cannon R. H.: Dynamics of physical systems. Warszawa: WNT 1973. 					
	Supplementary literature	Kaczorek T.: Control and systems theory. Warszawa: Scientific Publication PWN 1993. Kaliński K.: A surveillance of dynamic processes in mechanical systems. Gdańsk: The Publication of GUT 2012. Grzegożek W., Adamiec-Wójcik I., Wojciech S.: Computer modelling of the car vehicles dynamics. Kraków: The T. Kościuszko Cracow University of Technology 2003.					
	eResources addresses	Adresy na platformie eNauczanie:					
		Projektowanie mechatroniczne, W, Nano, Ist, sem. 05, zima, 2024/25, (PG_00033865) - Moodle ID: 40910 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=40910					
Example issues/ example questions/ tasks being completed	Development of functional systems design. The tasks of mechatronic design. The dissipating energy components of mechatronic systems. 2-wheeled mobile robot as example of original mechatronic device. Example of mechatronic design on a basis about the only systems knowledge. Modelling of multi-body systems. Dynamic equations.						
Work placement	Not applicable						

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