

Subject card

| Subject name and code | Numerical Optimization Algorithms, PG_00047436 | | | | | | | |
|---|---|-----------------------------------|---|-------------------------------------|------------|--|---------|-----|
| Field of study | Automatic Control, Cybernetics and Robotics | | | | | | | |
| Date of commencement of studies | October 2022 | | Academic year of realisation of subject | | 2023/2024 | | | |
| Education level | second-cycle studies | | Subject group | | | Obligatory subject group in the field of study Subject group related to scientific | | |
| | | | | | | research in the field of study | | |
| Mode of study | Full-time studies | | Mode of delivery | | | at the university | | |
| Year of study | 2 | | Language of instruction | | English | | | |
| Semester of study | 3 | | ECTS credits | | 2.0 | | | |
| Learning profile | general academic profile | | Assessment form | | assessment | | | |
| Conducting unit | Department of Decision Systems and Robotics -> Faculty of Electronics, Telecommunications and Informatics | | | | | | | |
| Name and surname of lecturer (lecturers) | Subject supervisor | | dr inż. Krystyna Rudzińska-Kormańska | | | | | |
| | Teachers | | dr inż. Krystyna Rudzińska-Kormańska | | | | | |
| Lesson types and methods of instruction | Lesson type | Lecture | Tutorial | Laboratory | Projec | t | Seminar | SUM |
| | Number of study hours | 0.0 | 0.0 | 30.0 | 0.0 | | 0.0 | 30 |
| | E-learning hours included: 0.0 | | | | | | | |
| Learning activity and number of study hours | Learning activity | Participation i classes including | | Participation in consultation hours | | Self-study | | SUM |
| | Number of study hours | 30 | | 2.0 | | 18.0 | | 50 |
| Subject objectives | Practical familiarization with static optimization algorithms and their application in automation. | | | | | | | |

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| Learning outcomes | Course outcome | Subject outcome | Method of verification | | | |
|---|--|--|--|--|--|--|
| | [K7_U21] can individually carry out an in-depth analysis of controlling, diagnostics and signal processing problems; and, to an advanced extent, is able to individually design, tune and operate automatic regulation, control and robotics systems; and use computers to control and monitor dynamic systems | Solves numerical methods optimization tasks. | [SU4] Assessment of ability to use methods and tools | | | |
| | [K7_U03] can design, according to required specifications, and make a complex device, facility, system or carry out a process, specific to the field of study, using suitable methods, techniques, tools and materials, following engineering standards and norms, applying technologies specific to the field of study and experience gained in the professional engineering environment | Is able to use optimization methods when solving problems in various fields. | [SU3] Assessment of ability to use knowledge gained from the subject | | | |
| | [K7_U01] can apply mathematical knowledge to formulate and solve complex and non-typical problems related to the field of study by:n-appropriate selection of source information and its critical analysis, synthesis, creative interpretation and presentation,n-application of appropriate methods and toolsn | Can formulate the problem of optimization in mathematical form. | [SU2] Assessment of ability to analyse information | | | |
| [K7_U05] can plan and conduct experiments related to the field of study, including computer simulations and measurements; interpret obtained results and draw conclusions | | Uses optimization methods to identify models. | [SU4] Assessment of ability to use methods and tools | | | |
| | 1. Introduction to OPTIMUM – specialized software for SO problem solving and SO algorithm properties studying. 2. Introduction to VISUAL - specialized software for graphical representation (2D, 3D) of objective functions, equality and inequality constraints and SO algorithm steps. 3. Comparative study of numerical SO algorithms without constraints – properties and indices: D) one-dimensional search methods; E) simple search methods (Rosenbrock, Hook-Jeeves, Nelder-Mead algorithms); F) methods with directional search (Powell's conjugate directions method); G) gradient SO methods (steepest descent, conjugate gradient and quasi-Newton methods). 8. Study of properties of numerical SO algorithms with constraints (internal, external and shifted penalty functions). 9. Solving optimal control problems for static physical systems (OPTIMUM software). 10. Solving optimal control problems for dynamical systems (OPTIMUM software). 11. Development of an algorithm for specified problem of continuous optimization. Physical system model. 12. Implementation and testing of the developed algorithm. Presentation of modeled system and optimum solution. 13. Discussion on presented methods and obtained solutions. | | | | | |
| Prerequisites and co-requisites | | | | | | |
| Assessment methods and criteria | Subject passing criteria laboratory grade | Passing threshold 50.0% | Percentage of the final grade 100.0% | | | |
| Recommended reading | induction grade 65.676 165.676 | | | | | |
| | Supplementary literature P.E.Gill, W.Murray, M.H.Wright, "Practical Optimization". | | | | | |
| | eResources addresses | Adresy na platformie eNauczanie: | | | | |

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| Example issues/ example questions/ tasks being completed | |
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| Work placement | Not applicable |

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