

## § GDAŃSK UNIVERSITY § OF TECHNOLOGY

## Subject card

Subject name and code	Digital Control, PG_00047403								
Field of study	Automatic Control, Cybernetics and Robotics								
Date of commencement of studies	October 2022		Academic year of realisation of subject			2023/2024			
Education level	second-cycle studies		Subject group			Obligatory subject group in the field of study Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	2		Language of instruction			English			
Semester of study	3		ECTS credits			2.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Decision Systems and Robotics -> Faculty of Electronics, Telecommunications and Informatics						s and		
Name and surname of lecturer (lecturers)	Subject supervisor		prof. dr hab. inż. Zdzisław Kowalczuk						
	Teachers		prof. dr hab. inż. Zdzisław Kowalczu			lk			
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	:t	Seminar	SUM	
	Number of study hours	30.0	0.0	0.0	0.0		0.0	30	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study SUM		SUM	
	Number of study hours	30		2.0		18.0		50	
Subject objectives	The aim of the course is to master the knowledge of methods for modeling of dynamic processes as objects subject to automatic control and the control design methods, as well as complex (Z) transformations.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K7_W21] Knows and understands, to an advanced extent, methods and techniques of design and operation of automatic control systems, control and robotics systems, as well as the use of computers in the control and monitoring of dynamic objects		The student understands the methods and techniques of design and operation of automatic control systems and control and robotics, as well as the use of computers in the control and monitoring of dynamic objects			[SW1] Assessment of factual knowledge			
	[K7_U03] can design, according to required specifications, and make a complex device, facility, system or carry out a process, specific to the field of study, using suitable methods, techniques, tools and materials, following engineering standards and norms, applying technologies specific to the field of study and experience gained in the professional engineering environment [K7_U21] can individually carry out an in-depth analysis of controlling, diagnostics and signal processing problems; and, to an advanced extent, is able to individually design, tune and operate automatic regulation, control and robotics systems; and use computers to control and monitor dynamic systems		Student is able to design and make a device or system, using methods, techniques and tools and materials, using standards and norms, using appropriate technologies Student gets acquainted with the basic problems of modelling computer-controlled systems and designing systems of direct digital control.			[SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject [SU1] Assessment of task fulfilment [SW1] Assessment of factual knowledge			

Subject contents	Basics of matrix algeba. Vectors, vector spaces and transformations. Linear transformations: linear mappings, base change and others (projections, rotations). Solving systems of equations. Problems of analysis and synthesis of digital control systems: Discretization and analogization; continuous and discrete modeling. Signal processing. Synthesis and analysis of mathematical models of control objects: discrete-time surrogate models. Spatial-state models.						
Prerequisites and co-requisites	Fundamentals of higher mathematics						
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade				
and criteria	Written exam	50.0%	100.0%				
Recommended reading	Basic literature	W.L. Brogan: Modern control theory, Prentice Hall, Englewood Cliffs, 1974. K.J. Astrom, B Wittenmark: Computer-controlled systems. Prentice Hall, Upper Saddle River, 1997					
	Supplementary literature	There are no other literature requirements					
	eResources addresses	Adresy na platformie eNauczanie: DC-2024 - Moodle ID: 27216 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=27216					
Example issues/ example questions/ tasks being completed							
Work placement	Not applicable						