

Subject card

Subject name and code	Identification of Changes in Signals, PG_00048474							
Field of study	Automatic Control, Cybernetics and Robotics							
Date of commencement of studies	February 2023		Academic year of realisation of subject			2023/2024		
Education level	second-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery			at the university		
Year of study	1		Language of instruction			Polish		
Semester of study	2		ECTS credits			1.0		
Learning profile	general academic pro	ofile	Assessme	nt form		assessment		
Conducting unit	Department of Decision Systems and Robotics -> Faculty of Electronics, Telecommunications and Informatics							
Name and surname	Subject supervisor		dr inż. Janusz Kozłowski					
of lecturer (lecturers)	Teachers		dr inż. Janusz Kozłowski					
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM
	Number of study hours	0.0	15.0	0.0	0.0		0.0	15
	E-learning hours incl	uded: 0.0						
Learning activity and number of study hours	Learning activity	rning activity Participation in didactic classes included in study consulting plan		Participation in consultation hours		Self-study		SUM
	Number of study hours	15	5		2.0			25
Subject objectives	Expanding knowledge on change detection and parameter identification algorithms. Practical implementations of selected procedures. Application of different methods of mathematical modelling of systems.							

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Learning outcomes	Course outcome	Subject outcome	Method of verification
	[K7_U01] can apply mathematical knowledge to formulate and solve complex and non-typical problems related to the field of study by:n-appropriate selection of source information and its critical analysis, synthesis, creative interpretation and presentation,n-application of appropriate methods and toolsn	Student got expert knowledge on mathematical modelling of automation systems. Student implemented the parameter identification procedures with utility weighting mechanisms (i.e. with simple and directional forgetting).	[SU4] Assessment of ability to use methods and tools
	[K7_W01] Knows and understands, to an increased extent, mathematics to the extent necessary to formulate and solve complex issues related to the field of study.	Student got engineering knowledge on implementation of mathematical methods of multiple integration. Student applied suitable methods for numerical approximation of continuous models.	[SW1] Assessment of factual knowledge
	[K7_U21] can individually carry out an in-depth analysis of controlling, diagnostics and signal processing problems; and, to an advanced extent, is able to individually design, tune and operate automatic regulation, control and robotics systems; and use computers to control and monitor dynamic systems	Student got general knowledge on digital processing of measurement signals. Student applied the identification algorithms to monitor the dynamics of automation systems.	[SU4] Assessment of ability to use methods and tools
	[K7_W03] Knows and understands, to an increased extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum.	Student got practical knowledge on applications of the on-line detection and identification algorithms. Student got familiar with analytical methods for examination of algorithms.	[SW1] Assessment of factual knowledge
	[K7_W21] Knows and understands, to an advanced extent, methods and techniques of design and operation of automatic control systems, control and robotics systems, as well as the use of computers in the control and monitoring of dynamic objects	Student got fundamental knowledge on diagnostics of automation systems. Student got prepared to practically apply the robust to outliers identification methods in diagnostic procedures.	[SW1] Assessment of factual knowledge
Subject contents	Determination of basic characteristic	s of stochastic processes.	

Discrete-time approximation of continuous-time representations. Numerical integration of signals using splines.

The least-squares method – transformation of continuous-time and discrete-time formulae.

Examination of asymptotic properties of the least-squares method. Practical implementation.

Modification of the least-squares method using a vector of instrumental variables.

Examination of asymptotic properties of the instrumental variable method. Comparison of different realizations of instrumental variables.

Implementation of algorithms with an adaptive weighting mechanism.

Implementation of robust to measurement outliers algorithms. Numerical examples.

Transformation of continuous-time models using linear integrating filters and Poisson moment functionals. Simulation tests.

Direct and indirect identification of continuous-time models. Numerical comparison of estimation quality.

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Deterministic and stochastic modeling, frequency domain representations and state-space de Methods of discretization of continuous-time models using linear integrating filters and Poisso functionals in discrete-time approximations of continuous systems. Recursive least-squares method, its implementation and practical applications.	·						
Methods of discretization of continuous-time models using linear integrating filters and Poisso functionals in discrete-time approximations of continuous systems.	·						
functionals in discrete-time approximations of continuous systems.	n moment						
Recursive least-squares method, its implementation and practical applications.	Methods of discretization of continuous-time models using linear integrating filters and Poisson moment functionals in discrete-time approximations of continuous systems.						
	Recursive least-squares method, its implementation and practical applications.						
Robust to measurement faults parameter identification algorithms derived from minimization of quadratic criteria and their applications in diagnostic procedures.	Robust to measurement faults parameter identification algorithms derived from minimization of non-quadratic criteria and their applications in diagnostic procedures.						
Direct method of continuous-time system identification and its application in identification of dispersion of dispersion in identification in identification of dispersion in identification in identification of dispersion in identification in identification of dispersion in identification in identifi	Direct method of continuous-time system identification and its application in identification of delay systems, systems with nonlinearities and distributed parameter systems.						
The lecture on Detection of Changes in Signals in the preceding semester must be accomplis successfully.	The lecture on Detection of Changes in Signals in the preceding semester must be accomplished successfully.						
Assessment methods Subject passing criteria Passing threshold Percentage of the	e final grade						
and criteria Colloquiums. It is necessary to score at least 10 out of total amount of 20 pts. for each colloquium. Number of colloquiums: 1.	e iiiai grade						
	Basseville M., Nikiforov I.V.: Detection of abrupt changes: theory and application. Prentice-Hall Inc., 1993.						
Ljung L.: System identification. Theory for the user. Prer 1987.	Ljung L.: System identification. Theory for the user. Prentice-Hall Inc., 1987.						
	Korbicz J., Kościelny J.M., Kowalczuk Z., Cholewa W. (Editors): Fault diagnosis: models, artificial intelligence, applications. Springer, Berlin New York, 2004.						
Supplementary literature Anderson B.D.O., Moore J.B.: Optimal filtering. Information Sciences Series. Prentice-Hall Inc., 1979.	Anderson B.D.O., Moore J.B.: Optimal filtering. Information and System Sciences Series. Prentice-Hall Inc., 1979.						
eResources addresses Adresy na platformie eNauczanie:							
Example issues/ according to the state of th	Enumerate and describe in brief common performance indices used for evaluation of quality of change detection.						
Compare the Kalman approach and the Wiener approach to optimal filtering. Indicate situal Kalman filter demonstrates its supremacy.	Compare the Kalman approach and the Wiener approach to optimal filtering. Indicate situations where Kalman filter demonstrates its supremacy.						
Compare the so-called direct and indirect approaches to identification of continuous-time syllaborate the benefits and drawbacks of both concepts.	Compare the so-called direct and indirect approaches to identification of continuous-time systems. Enumerate the benefits and drawbacks of both concepts.						
integral filtering (LIF). Introduce the transfer function of the LIF operator and derive the ultimate	4. Describe the direct method of identification of continuous-time systems based on the method of linear integral filtering (LIF). Introduce the transfer function of the LIF operator and derive the ultimate formula for the numerical LIF realization using the bilinear operator. Formulate and justify the rule of thumb for proper selection of the integration horizon.						
5. Specify in brief possible applications of change detection algorithms. Explain why abrupt changes large in magnitude.	nanges do not						
Work placement Not applicable							

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