

Subject card

Subject name and code	Adaptive Control, PG_00048445									
Field of study	Automatic Control, Cybernetics and Robotics									
Date of commencement of studies	February 2023		Academic year of realisation of subject			2023/2024				
Education level	second-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study				
Mode of study	Full-time studies		Mode of delivery			at the university				
Year of study	1		Language of instruction			Polish				
Semester of study	2		ECTS credits			1.0				
Learning profile	general academic profile		Assessment form			assessment				
Conducting unit	Department of Autom	atic Control ->	> Faculty of Electronics, Telecommunications and Informatics				ics			
Name and surname	Subject supervisor		dr inż. Piotr Kaczmarek							
of lecturer (lecturers)	Teachers		dr inż. Piotr Kaczmarek							
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory Project		:t	Seminar	SUM		
of instruction	Number of study hours	15.0	0.0	0.0	0.0		0.0	15		
	E-learning hours inclu	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in classes include plan		Participation in consultation hours		Self-study		SUM		
	Number of study hours	15		2.0		8.0		25		
Subject objectives	Presentation of principles and basic techniques of adaptive control									
Learning outcomes	Course outcome		Subject outcome			Method of verification				
			Can implement a selected adaptive controller			[SU1] Assessment of task fulfilment				
	[K7_W06] Knows and understands, to an increased extent, the basic processes taking place in the life cycle of devices, facilities and technical systems.		Knows and understands the sources of changes in the linear model of the controlled plant			[SW1] Assessment of factual knowledge				
	operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum.					[SW2] Assessment of knowledge contained in presentation				
Subject contents	 Introduction System identification Adaptive pole placement controller Stochastic self-tuning regulators Dual control Adaptive feedforward controllers Analysis of adaptive systems Implementation of adaptive systems 									
Prerequisites and co-requisites	Knowledge of discrete-time control theory									

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Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade	
and criteria	Implementation of selected adaptive controller	60.0%	100.0%	
Recommended reading	Basic literature K. J. Astrom, B. Wittenmark, Adaptive Control, Addison-Weasley,			
	Supplementary literature	S. Sastry, M. Bodson, Adaptive Control: Stability, Convergence and Robustness, Prentice Hall 1994		
	eResources addresses	Adresy na platformie eNauczanie:		
Example issues/ example questions/ tasks being completed				
Work placement	Not applicable			

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