

Subject card

Subject name and code	Fundamentals of Control, PG_00056914								
Field of study	Electrical Engineering								
Date of commencement of studies	October 2021		Academic year of realisation of subject			2022/2023			
Education level	first-cycle studies		Subject group						
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	2		Language of instruction			Polish			
Semester of study	4		ECTS credits			4.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Controlled Electric Drives -> Faculty of Electrical and Control Engineering								
Name and surname	Subject supervisor dr hab. inż. Arkadiusz Lewicki								
of lecturer (lecturers)	Teachers	dr inż. Daniel Wachowiak							
			dr hab. inż. Marek Adamowicz						
			dr hab. inż. Arkadiusz Lewicki						
	ar hab. mz. Amadiusz Edwich					,			
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Project		Seminar	SUM	
of instruction	Number of study hours	30.0	30.0	0.0	0.0		0.0	60	
	E-learning hours included: 0.0								
	Address on the e-learning platform: https://enauczanie.pg.edu.pl/moodle/course/view.php?id=11155								
Learning activity and number of study hours	Learning activity Participation in classes include plan				Self-study SUM				
	Number of study hours	60		5.0		35.0		100	
Subject objectives	The student learns structure and function of automatic control systems. Learns the methods of automatic control system descibing and methods of linear system analisys of automatic control. Learn how to determine the dynamic characteristics of linear systems and to determine the dynamic properties of system on the basis of its characteristic. Scores based on the ability to identify the characteristics of the dynamic properties of systems and analysis of automatic control systems. He learns the ways and transform block diagrams, is gaining the ability to study the stability								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
			Ability to analyze linear automation systems. Ability to determine static and dynamic characteristics. Ability to stability testing. Knowledge of structures of basic types of controllers, selection of gains and synthesis of a closed control system. Knowledge of basic automation blocks.			[SW3] Assessment of knowledge contained in written work and projects			
	K6_U07		Student can design a closed control system, select regulators and analyze the stability and dynamic properties of the system			[SU1] Assessment of task fulfilment [SU3] Assessment of ability to use knowledge gained from the subject [SU4] Assessment of ability to use methods and tools			
Subject contents	The control system and its components, positive and negative feedback. Laplace transformation, transfer function. Block diagrams. Response in time domain: measurement and calculation for a given transmittance. Frequency response: measurement and calculation for a given transmittance. Automation components: proportional, inertial, derivative, oscillating, delay. The characteristics of typical controllers: P, I, PI, PD, PID. Dynamic of control system. The stability of linear control systems, stability criteria. Sets of controller parameters. Examples of typical control systems.								
Prerequisites and co-requisites									

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Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade				
and criteria	Studies prepared by students	60.0%	50.0%				
	Midterm colloquium	60.0% 50.0%					
Recommended reading	Basic literature Supplementary literature						
		D. Horla Podstawy Automatyki, ćwiczenia labolatoryjne, Poznań 2003					
	eResources addresses	Adresy na platformie eNauczanie:					
Example issues/	Determine the stability of the system,						
example questions/ tasks being completed	Determine the transmittance of the system, Convert the block diagram of the control system, Sketch and analyze the Bode / Nyquist characteristics. for the layout. Select the settings of regulators for which the system will be stable						
Work placement	Determine the stability margin Not applicable						
Tront placement							

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