

GDAŃSK UNIVERSITY

Subject card

Subject name and code	Team Project, PG_00033399							
Field of study	Automation, Robotics and Control Systems							
Date of commencement of studies	February 2023		Academic year of realisation of subject			2023/2024		
Education level	second-cycle studies		Subject group		Optional subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university		
Year of study	1		Language of instruction			Polish		
Semester of study	2		ECTS credits			4.0		
Learning profile	general academic profile		Assessment form			assessment		
Conducting unit	c		-> Faculty of Electrical and Control Engineering				ing	
Name and surname	Subject supervisor		prof. dr hab. ir	nż. Roman Śm	ierzchal	ski		
of lecturer (lecturers)	Teachers		prof. dr hab. inż. Roman Śmierzcha					
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM
of instruction	Number of study hours	0.0	0.0	0.0	60.0		0.0	60
	E-learning hours included: 0.0							
Learning activity and number of study hours	Learning activity	Participation i classes incluc plan		Participation in consultation hours		Self-study		SUM
	Number of study hours	60		15.0		25.0		100
Subject objectives	Student develops a p necessary to comple areas. Accept work ir	te the project, c						
	Course outcome							
Learning outcomes	Course out		Subj	ect outcome			Method of ve	erification
Learning outcomes	Course out K7_W14		The student a describes the control objects implements a	ect outcome nalyses, mode operation of re s and designs dvanced contro industrial syste	eal and bl	[SW2]		of knowledge
Learning outcomes			The student a describes the control object implements a algorithms in The student k understands t teamwork, rai personal and is aware of th his or her owr has the ability	nalyses, mode operation of re s and designs dvanced contro industrial syste	eal and ol ms. f hal, ences, for team,	[SW2] contair [SU5] /	Assessment	of knowledge ntation of ability to
Learning outcomes	K7_W14		The student a describes the control object: implements a algorithms in The student k understands t teamwork, rai personal and is aware of th- his or her owr has the ability results of task The student, v teamwork, de systems, usin techniques, e	nalyses, mode operation of re s and designs dvanced contro industrial syste nows and he principles o sing professior social compet- e responsibility n work and in a to present the c implementatic working alone o signs control	eal and bl ms. f hal, for team, on. or in a cope	[SW2] contair [SU5] / presen	Assessment ned in preser Assessment at the results Assessment	of knowledge Itation of ability to of task
Learning outcomes	K7_W14 K7_U13	of automation and implementatives with automation automation and implementatives with automation automati	The student a describes the control object: implements a algorithms in The student k understands t teamwork, rai personal and is aware of thi- his or her own has the ability results of task The student, v teamwork, de systems, usin techniques, e and time need project.	nalyses, mode operation of re s and designs a dvanced contro industrial syste nows and he principles o sing professior social compete e responsibility n work and in a to present the c implementatic working alone of signs control g dedicated stimates the so ded to complete s. Depending o ted system auti	eal and bl ms. f fal, ences, for team, on. or in a cope e the n your ta tomatior	[SW2] contair [SU5] / presen [SU1] / fulfilme	Assessment ned in preser Assessment at the results Assessment ent	of knowledge Itation of ability to of task of task
	K7_W14 K7_U13 K7_U13 K7_U02 Solving the problem of algorithms, design ar solving technical issu	of automation and implementatives with automation automation and implementatives with automation automati	The student a describes the control object: implements a algorithms in The student k understands t teamwork, rai personal and is aware of thi- his or her own has the ability results of task The student, v teamwork, de systems, usin techniques, e and time need project.	nalyses, mode operation of re s and designs a dvanced contro industrial syste nows and he principles o sing professior social compete e responsibility n work and in a to present the c implementatic working alone of signs control g dedicated stimates the so ded to complete s. Depending o ted system auti	eal and bl ms. f fal, ences, for team, on. or in a cope e the n your ta tomatior	[SW2] contair [SU5] / presen [SU1] / fulfilme	Assessment ned in preser Assessment at the results Assessment ent	of knowledge Itation of ability to of task of task
Subject contents Prerequisites	K7_W14 K7_U13 K7_U13 K7_U02 Solving the problem of algorithms, design ar solving technical issu	of automation and implementaties with automatic	The student a describes the control object: implements a algorithms in The student k understands t teamwork, rai personal and is aware of th- his or her owr has the ability results of task The student, v teamwork, de systems, usin techniques, e and time need project.	nalyses, mode operation of re s and designs a dvanced contro industrial syste nows and he principles o sing professior social compete e responsibility n work and in a to present the c implementatic working alone of signs control g dedicated stimates the so ded to complete s. Depending o ted system auti	eal and bl ms. f fal, ences, for team, on. or in a cope e the n your ta tomatior	[SW2] contair [SU5] / presen [SU1] / fulfilme	Assessment hed in preser Assessment it the results Assessment ent o develop co obotics, cons id controls, ir centage of th	of knowledge Itation of ability to of task of task
Subject contents Prerequisites and co-requisites Assessment methods and criteria	K7_W14 K7_U13 K7_U13 K7_U02 Solving the problem of algorithms, design ar solving technical issu systems and security Subject passir	of automation and implementaties with automatic	The student a describes the control object: implements a algorithms in The student k understands t teamwork, rai personal and is aware of the his or her own has the ability results of task The student, v teamwork, de systems, usin techniques, e and time need project. Ind / or robotics ion of the select ation and roboti	nalyses, mode operation of re s and designs of dvanced control industrial syste nows and he principles of sing profession social competent e responsibility n work and in a to present the c implementatic working alone of signs control g dedicated stimates the so ded to complete s. Depending o ted system aution cs, control system ing threshold	eal and bl ms. f hal, ences, for team, or in a cope e the tomatior tems de	[SW2] contair [SU5] / presen [SU1] / fulfilme ask is to n and ro sign an Per 100.0%	Assessment ned in preser Assessment at the results Assessment ent o develop co obotics, cons ad controls, ir centage of th 6	of knowledge Itation of ability to of task of task of task
Subject contents Prerequisites and co-requisites Assessment methods	K7_W14 K7_U13 K7_U13 K7_U02 Solving the problem of algorithms, design ar solving technical issu systems and security Subject passir project evaluation	of automation and implementaties with automatic	The student a describes the control object implements a algorithms in The student k understands t teamwork, rai personal and is aware of thhis or her owr has the ability results of task. The student, v teamwork, de systems, usin techniques, e and time need project.	nalyses, mode operation of re s and designs i dvanced contro industrial syste nows and he principles o sing professior social compete e responsibility n work and in a t to present the c implementatic working alone of signs control g dedicated stimates the so ded to complete s. Depending o ted system autics, control system	eal and bl ms. f f al, ences, for team, br team, br in a cope e the comation tems de	[SW2] contair [SU5] / presen [SU1] / fulfilme ask is to n and ro sign an Per 100.0%	Assessment ned in preser Assessment at the results Assessment ent o develop co obotics, cons ad controls, ir centage of th 6	of knowledge Itation of ability to of task of task of task

	The current implementation of the project and the implementation phase. The final presentation of the project.
Work placement	Not applicable