



Subject card

Subject name and code	Control and Decision Support Systems, PG_00057478						
Field of study	Automation, Robotics and Control Systems						
Date of commencement of studies	February 2023	Academic year of realisation of subject			2022/2023		
Education level	second-cycle studies	Subject group					
Mode of study	Full-time studies	Mode of delivery			at the university		
Year of study	1	Language of instruction			Polish		
Semester of study	1	ECTS credits			2.0		
Learning profile	general academic profile	Assessment form			assessment		
Conducting unit	Katedra Inteligentnych Systemów Sterowania i Wspomagania Decyzji -> Faculty of Electrical and Control Engineering						
Name and surname of lecturer (lecturers)	Subject supervisor		dr inż. Tomasz Rutkowski				
	Teachers		dr inż. Tomasz Rutkowski dr inż. Tomasz Zubowicz dr hab. inż. Kazimierz Duzinkiewicz				
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	0.0	15.0	0.0	30
E-learning hours included: 0.0							
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan	Participation in consultation hours		Self-study		SUM
	Number of study hours	30	4.0		16.0		50
Subject objectives	Introduction to advanced structures and algorithms of control systems that implement complex control objectives. Introduction to decision support systems and advanced optimisation methods as tools for their synthesis purposes.						
Learning outcomes	Course outcome	Subject outcome			Method of verification		
	K7_W02	Knowledge of the implementation of control algorithms. Knowledge of the decision support system implementation. Knowledge of the evaluation of the performance quality of the control systems.			[SW1] Assessment of factual knowledge		
	K7_U11	Knowledge of advanced control methods. Knowledge of advanced decision support methods.			[SU1] Assessment of task fulfilment [SU3] Assessment of ability to use knowledge gained from the subject [SU4] Assessment of ability to use methods and tools		

Subject contents	<p>LECTURES: Aspects of modelling dynamics systems: linear and nonlinear with distributed and concentrated dynamics, continuous and discrete, mixed and event dynamics. Uncertainty modelling methods: stochastic, interval deterministic and mixed. Control and decision support structures: centralized and decentralized, with information exchange, with negotiation and consensus mechanisms, hierarchical with coordination. Trajectory tracking control in the cascade control structure. Problems of direct adaptive control based on the DMRAC model (Direct Model Reference Adaptive Control). Decision support systems as control systems. Issues of decision support with multi-criteria decisions problems: multi-attribute and multi-objective. Problems of multi-criteria linear programming, Pareto optimality. Introduction to optimizing MPC (Model Predictive Control) control, aspects of taking into account changes in process operating conditions (soft switching), robustness's mechanisms. The classical genetic algorithm as a method for solving optimization problems.</p> <p>PROJECT: The project classes are based on the Matlab/Simulink software with prepared utility tools (scripts, models), and its scope includes the content presented during lectures such as:</p> <ul style="list-style-type: none"> - synthesis of a trajectory tracking cascade control system for the vertical inclination of the radar bowl, taking into account the presence of friction forces and measurement noise (LuGre friction model, PI regulator with adapted parameters: fuzzy logic, Mamdani inference), - synthesis of the oxygen concentration control system in a biological reactor using Direct Model Reference Adaptive Control (DMRAC), - synthesis of predictive control with a linear object model in a multivariate, nonlinear chemical reactor with a continuous flow of components (CSTR), - the classic Genetic Algorithm (GA) as a tool for solving optimization problems, - decision support problem based on the example of Portfolio optimization of the investment portfolio of an individual investor. 											
Prerequisites and co-requisites	Knowledge of the contents of the subjects related to control systems engineering, which were realized within the standard curriculum of a bachelor's degree in Automatics.											
Assessment methods and criteria	<table border="1" data-bbox="448 792 1498 898"> <thead> <tr> <th data-bbox="448 792 794 831">Subject passing criteria</th> <th data-bbox="794 792 1141 831">Passing threshold</th> <th data-bbox="1141 792 1498 831">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="448 831 794 869">Projects Reports</td> <td data-bbox="794 831 1141 869">50.0%</td> <td data-bbox="1141 831 1498 869">50.0%</td> </tr> <tr> <td data-bbox="448 869 794 898">Lecture Test</td> <td data-bbox="794 869 1141 898">50.0%</td> <td data-bbox="1141 869 1498 898">50.0%</td> </tr> </tbody> </table>			Subject passing criteria	Passing threshold	Percentage of the final grade	Projects Reports	50.0%	50.0%	Lecture Test	50.0%	50.0%
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Lecture Test	50.0%	50.0%										
Recommended reading	Basic literature	<ol style="list-style-type: none"> 1. Slotine Jean Jacques E., W. Li: Applied Nonlinear Control. Prentice Hall, Englewood Cliffs, New Jersey 07632, 1991. 2. Brdys Mietek A., P. Tatjewski: Iterative Algorithms for Multilayer Optimizing Control, Imperial College Press, World Scientific Publishing Co. Pte. Ltd., 2005. 3. Rawlings J.B., D.Q. Mayne: Model Predictive Control: Theory and Design. Nob-Hill Publishing, 1st edition, 2009. 4. A.P. Wierzbicki, M. Makowski, J. Wessels: Model-Based Decision Support Methodology with Environmental Applications, Series: Mathematical Modeling and Applications. Kluwer Academic, Dordrecht, 2000. 5. J. Branke, K. Deb, K. Miettinen, R. Slowinski: Multiobjective Optimization: Interactive and Evolutionary Approaches, 2008. 										
	Supplementary literature	<ol style="list-style-type: none"> 1. Hassan K. Khalil: Nonlinear Systems. Prentice Hall, Englewood Cliffs, New Jersey 07632, 2002. 2. J. M. Maciejowski: Multivariable Feedback Design. Addison Wesley, 1989 3. Byrski W.: Obserwacja i Sterowanie w Systemach Dynamicznych. Uczelniane Wydawnictwa Naukowo Dydaktyczne Akademii Górniczo Hutniczej w Krakowie, 2007 4. Tatjewski P.: Sterowanie Zaawansowane Obiektów Przemysłowych struktury i algorytmy. Warszawa, Akad. Oficyna Wyd. EXIT, 2002. 										
	eResources addresses	Adresy na platformie eNauczanie: SYSTEMY STEROWANIA I WSPOMAGANIA DECYZJI [2022/23] - Moodle ID: 28464 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=28464										
Example issues/ example questions/ tasks being completed	<ul style="list-style-type: none"> - Synthesis of a trajectory tracking cascade control system for the vertical inclination of the radar bowl, taking into account the presence of friction forces and measurement noise (LuGre friction model, PI regulator with adapted parameters: fuzzy logic, Mamdani inference) - Synthesis of the oxygen concentration control system in a biological reactor using Direct Model Reference Adaptive Control (DMRAC) - Synthesis of predictive control with a linear object model in a multivariate, nonlinear chemical reactor with a continuous flow of components (CSTR) - Classic Genetic Algorithm (GA) as a tool for solving optimization problems - Decision support problem based on the example of Portfolio optimization of the investment portfolio of an individual investor 											
Work placement	Not applicable											