

Subject card

Subject name and code	Automation and Robotics, PG_00060459								
Field of study	Mechanical and Naval Engineering								
Date of commencement of studies	October 2023		Academic year of realisation of subject			2024/2025			
Education level	first-cycle studies	irst-cycle studies		Subject group			Obligatory subject group in the field of study		
						Subject group related to scientific research in the field of study			
Mode of study	Part-time studies		Mode of delivery			blended-learning			
Year of study	2		Language of instruction			Polish			
Semester of study	3		ECTS credits			5.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Institute of Naval Architecture -> Faculty of Mechanical Engineering and Ship Technology								
Name and surname of lecturer (lecturers)	Subject supervisor	dr inż. Mohammad Ghaemi							
	Teachers		mgr inż. Jacek Frost						
			dr inż. Joanna Grochowalska						
			dr inż. Mohammad Ghaemi						
		di inz. Monaminad Ghaciili							
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	:t	Seminar	SUM	
	Number of study hours	18.0	9.0	9.0	0.0		0.0	36	
	E-learning hours included: 18.0								
Learning activity and number of study hours	Learning activity	Participation in classes include plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	36		8.0		81.0		125	
Subject objectives	The aim is to get acquainted with the basis of control theory and with the structures and elements of basic automation systems, as well as general information on the design of control systems.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	correct conclusions		The student is able to plan an experiment in the field of identification of basic control systems, using specialized equipment, conduct an interpretation of the results, and draw appropriate conclusions.			[SU4] Assessment of ability to use methods and tools			
	[K6_W06] possesses knowledge on automatics and robotics of mechanical systems					[SW1] Assessment of factual knowledge			

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Subject contents	1 Introduction and basic concents						
Subject contents	Introduction and basic concepts						
	2. Classification of control systems						
	2. Madaling of machanical dynamic	alamanta					
	 Modeling of mechanical dynamical systems and description of their elements Types of mathematical models of dynamical systems: differential equation, transfer function, block diagram, linearization Transition function and time characteristics Feedback closed-loop control system Analysis of control systems in the plot of time and in the plot of frequency Stability of linear control systems Controllers 						
Prerequisites	Prerequesties:						
and co-requisites							
	1. Mathematics						
	2. Physics						
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade				
	Laboratory	50.0%	25.0%				
	Lecture	50.0%	50.0%				
	Exercises	50.0%	25.0%				
Recommended reading	Basic literature	Nise N. S., Control System Engineering, 8th Edition, John Whiley &					
	0 1 1 1 1 1	Sons Inc., 2019.					
	Supplementary literature	- Friedland B., Control System Design, McGraw Hill Co., 1986.					
	- Ogata K., Modern Control Engineering, 4th edition, Prentice-Hall,						
	- Raven, F. H., Automatic control engineering, McGraw Hill Co., 1986.						
	eResources addresses Adresy na platformie eNauczanie:						
Example issues/							
example questions/							
tasks being completed Work placement	Not applicable						
Work placement	Not applicable						

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