



Subject card

Subject name and code	, PG_00056120						
Field of study	Mechatronics						
Date of commencement of studies	October 2023		Academic year of realisation of subject		2025/2026		
Education level	first-cycle studies		Subject group				
Mode of study	Full-time studies		Mode of delivery		at the university		
Year of study	3		Language of instruction		Polish		
Semester of study	6		ECTS credits		2.0		
Learning profile	general academic profile		Assessment form		assessment		
Conducting unit	Institute of Mechanics and Machine Design -> Faculty of Mechanical Engineering and Ship Technology						
Name and surname of lecturer (lecturers)	Subject supervisor		dr inż. Paweł Załuski				
	Teachers						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	15.0	0.0	0.0	30
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	30		0.0		0.0	30
Subject objectives	The aim of the course is to familiarise students with the construction and operation of mechatronic elements and systems with electro-hydraulic and electro-pneumatic control, including programmable systems.						
Learning outcomes	Course outcome		Subject outcome		Method of verification		
	[K6_W10] has knowledge about development trends in the field of engineering and technology sciences and scientific disciplines: Mechanical Engineering, Automation, Electronics, Electrical Engineering and Space Technologies, adequate for Mechatronics curse		The student has basic knowledge of development trends in the field of technical sciences and scientific disciplines: hydrotronics and pneumotronics		[SW1] Assessment of factual knowledge [SW2] Assessment of knowledge contained in presentation		
	[K6_U05] is able to use properly chosen tools to compare design solutions of elements and mechatronics systems according to given application and economic criteria (e.g. power demand, speed, costs)		Students will be able to compare design solutions of hydrotronic and pneumotronic components and systems due to given application criteria, e.g. speed of operation, effect of load on speed, energy consumption, power.		[SU2] Assessment of ability to analyse information [SU3] Assessment of ability to use knowledge gained from the subject		
	[K6_U06] is able to identify and formulate specification of simple, practical engineering tasks, distinctive for mechatronics		The student is able to identify and formulate functions and methods of implementation for simple mechatronic engineering tasks in the field of electrohydraulic and electropneumatic drive and control.		[SU1] Assessment of task fulfilment [SU3] Assessment of ability to use knowledge gained from the subject [SU4] Assessment of ability to use methods and tools		
	[K6_W08] knows and understands design and production processes of elements and simple mechatronic devices		The student knows and understands the processes and issues related to the construction and operation of mechatronic elements and systems with electrohydraulic and electropneumatic control, including programmable ones.		[SW1] Assessment of factual knowledge		

Subject contents	Hydrotronics. Examples of application of hydraulic systems with electric and electronic control. Types of electrohydraulic control. Transducers. Switching control. Electromagnetically operated directional control valves. Systems with electromagnetically operated directional control valves. Proportional control. Proportional solenoids. Proportional directional valves. Servo-steering. Servo-valves with barometric, mechanical and electrical feedback. Static and dynamic characteristics of proportional valves and servo valves. Proportional control and servo control systems. Hydraulic amplifiers with electric stepper motors. Computer control systems for electrohydraulic servo drives. Hydraulic control systems for manipulators and robots. Pneumotronics. Application of pneumatic drives with electrical and programmable control. Types and control of compressors. Electropneumatic control. Types of electropneumatic control. Sensors used in pneumatics. Switchable electropneumatic valves. Relay technology. Electrical components used in electropneumatic control systems. Switching control systems. Digital electropneumatic control. Electropneumatic positioning systems. Pneumatic servo valves and servo drives. Programmable controls. Pneumatic systems with PLCs.		
Prerequisites and co-requisites	Knowledge of general mechanics, hydrostatics, hydraulics and pneumatics		
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	tests	56.0%	100.0%
Recommended reading	Basic literature	Pizoń A.: Hydrauliczne i elektrohydrauliczne układy sterowania i regulacji. WNT Warszawa 1987 Pizoń A.: Elektrohydrauliczne i analogowe i cyfrowe układy automatyki. WNT Warszawa 1995 Schmid D. i inni: Mechatronika. For the polish edition REA. Warszawa 2002	
	Supplementary literature	Katalogi firm: Bosch-Reroth, Moog, EATON, FESTO, SMC Vademecum Hydrauliki. Tom 2. Technika hydraulicznego steowania zaworami proporcjonalnymi i serwowaworami. Mannesman Rexroth Deppert W., Stoll K.: Pneumtische Steuerungen. Vogel Buchverlag. Würzburg 1994. Backe W., Goedecke W.-D.: Steuerungs- und Schaltungstechnik I. Institut für hydraulische und pneumatische Antriebe und Steuerungen RWTH Aachen. Backe W.: Steuerungs-und Schaltungstechnik II. Institut für hydraulische und pneumatische Antriebe und Steuerungen RWTH Aachen. Holejko D. i inni: Pneumatyczne urządzenia automatyki. Wydawnictwa PW. Warszawa 1986.	
	eResources addresses	Adresy na platformie eNauczanie:	
Example issues/ example questions/ tasks being completed	principle of operation of proportional solenoid effect of load on the movement of actuators in systems with proportional valves Load sensing systems principle of operation of hydraulic servo-valves stepping units in pneumatic systems		
Work placement	Not applicable		