



Subject card

Subject name and code	Theory of Marine Control Systems, PG_00060563						
Field of study	Naval Architecture and Offshore Structures						
Date of commencement of studies	October 2023		Academic year of realisation of subject		2025/2026		
Education level	first-cycle studies		Subject group		Optional subject group Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery		at the university		
Year of study	3		Language of instruction		Polish		
Semester of study	5		ECTS credits		4.0		
Learning profile	general academic profile		Assessment form		exam		
Conducting unit	Faculty of Mechanical Engineering and Ship Technology						
Name and surname of lecturer (lecturers)	Subject supervisor		dr inż. Mohammad Ghaemi				
	Teachers						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	30.0	15.0	15.0	0.0	0.0	60
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	60		6.0		34.0	100
Subject objectives	The aim of the course is to develop students skills and knowledge of basic concepts in the field of automation, methods of description and analysis of the behaviour of automatic control systems and their elements, as well as understanding the theory of control systems in ship technology.						
Learning outcomes	Course outcome		Subject outcome		Method of verification		
	[K6_W04] has knowledge in the field of computer science, electronics, electrical engineering, automation and control, information technology, computer graphics, useful for understanding the possibilities of their use in ocean engineering		The student has knowledge of the fundamentals of automatics and control systems and understands the possibilities of using control systems in ship systems.		[SW1] Assessment of factual knowledge		
	[K6_U03] can use computer-aided design, production and operation tools for ocean technology objects and systems		The student is able to use the basic methods of computer simulation in the field of linear control systems.		[SU1] Assessment of task fulfilment [SU4] Assessment of ability to use methods and tools		

Subject contents	1. Introduction and basic concepts		
	2. Classification of control systems on the example of selected ship control systems		
	3. Modeling of dynamic systems on the example of ship motion and propulsion models		
	4. Types of mathematical models of dynamical systems: differential equation, transfer function, block diagram, state space model; model transformations - in the context of ship motion and propulsion models		
	5. Transition function and time characteristics on the example of ship's course, trajectory and linear velocity		
	6. Application of feedback and feedforward concepts		
	7. Analysis of control systems in the frequency domain		
	8. Stability of control systems		
	9. Controllers and the principles of their design and selection for the chosen ship systems		
	10. Quality indexes of ship control systems		
Prerequisites and co-requisites	Mathematics I		
	Mathematics II		
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	Exam	56.0%	50.0%
	Test - tutorials	51.0%	25.0%
	Lab. reports	51.0%	25.0%
Recommended reading	Basic literature	1. Nise N. S., Control System Engineering, 8th Edition, John Wiley & Sons Inc., 2019.	
		2. Kaczorek T., Podstawy teorii sterowania, Wydawnictwo Naukowe PWN, Warszawa, 2020.	
		3. Domachowski Z., Automatyka i robotyka podstawy, Wydawnictwo PG, Gdańsk, 2003.	
		4. Domachowski Z., Ghaemi M. H., Okrętowe układy automatyki, Wydawnictwo Politechniki Gdańskiej, 2019.	
		5. Fossen T. I., Handbook of Marine Craft Hydrodynamics and Motion Control, John Wiley & Sons, 2011.	

	Supplementary literature	<p>1. Bubnicki Z., Teoria i algorytmy sterowania, Wydawnictwo Naukowe PWN, Warszawa, 2019.</p> <p>2. Ogata K., Modern Control Engineering, 4th edition, Prentice-Hall, 2009.</p> <p>3. Fossen T. I., Marine Control Systems, Marine Cybernetics AS, 2002.</p> <p>4. Gucma S., Inżynieria ruchu morskiego, Okrętownictwo i Żegluga Sp.z o.o., Gdańsk, 2001.</p> <p>5. Balicki, J., Małecki, Józef ; Żak, Bogdan, Automatyka okrętowa, Akademia Marynarki Wojennej im. Bohaterów Westerplatte, Gdynia, 1999.</p>
	eResources addresses	Adresy na platformie eNauczanie:
Example issues/ example questions/ tasks being completed		
Work placement	Not applicable	

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