



## Subject card

Subject name and code	Computer Control Systems, PG_00038129						
Field of study	Automation, Robotics and Control Systems						
Date of commencement of studies	October 2023	Academic year of realisation of subject			2025/2026		
Education level	first-cycle studies	Subject group			Optional subject group Subject group related to scientific research in the field of study		
Mode of study	Full-time studies	Mode of delivery			at the university		
Year of study	3	Language of instruction			Polish		
Semester of study	6	ECTS credits			5.0		
Learning profile	general academic profile	Assessment form			exam		
Conducting unit	Faculty of Electrical and Control Engineering						
Name and surname of lecturer (lecturers)	Subject supervisor	dr inż. Jarosław Tarnawski					
	Teachers						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	30.0	0.0	30.0	0.0	0.0	60
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan	Participation in consultation hours		Self-study	SUM	
	Number of study hours	60	8.0		57.0	125	
Subject objectives	Presentation of centralized and distributed / decentralized control structures. The introduction of advanced adaptive, predictive control methods. Acquainted with the infrastructure of computer control systems - DCS and SCADA / PLC systems. The integration of knowledge from different fields to the needs of a computer control system synthesis. Introduction to methods of decision support - multi-purpose and multi-attribute-approach.						
Learning outcomes	Course outcome	Subject outcome			Method of verification		
	[K6_W07] has basic knowledge related to control and automation systems	The student is able to define the role of all necessary elements and build a control system			[SW1] Assessment of factual knowledge		
	[K6_K02] can work in a group taking on different roles in it	The student during laboratory classes on the synthesis of advanced control system performs tasks in groups by changing roles within the team.			[SK2] Assessment of progress of work		
	[K6_U07] can build and analyze models of systems and systems in the field related to control systems and automation	The student is able to build an advanced computer-controlled control system			[SU5] Assessment of ability to present the results of task		
Subject contents	Control systems structures: classical, centralized, multilayer, decentralized, distributed. Implementation of centralized/decentralized with/without data exchange with communication aspects (time relationships, data loss, stability). Multilayer and distributed control systems based on real large scale systems: drinking water distribution systems, sewer system, oil refinery. Requirements for computer controlled systems. Information structure of CCS. Software and hardware selection for practical implementation of CCS. Implementation of selected complex control algorithms in computer-like devices: microcontrollers, PLCs, PACs and industrial computers. SCADA system realization supervisory control with coordination among all control layers. Process data acquisition and archivisation. Realization of optimization layer. Solver selection for optimization purposes.						

Prerequisites and co-requisites	Finished courses:  - Dynamic Systems  - Real Time Systems  - Programmable Logic Controllers  - Industrial Communication Networks														
Assessment methods and criteria	<table border="1"> <thead> <tr> <th data-bbox="453 479 794 506">Subject passing criteria</th> <th data-bbox="799 479 1141 506">Passing threshold</th> <th data-bbox="1145 479 1485 506">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="453 512 794 539">Written exam</td> <td data-bbox="799 512 1141 539">50.0%</td> <td data-bbox="1145 512 1485 539">40.0%</td> </tr> <tr> <td data-bbox="453 546 794 573">Midterm colloquium</td> <td data-bbox="799 546 1141 573">50.0%</td> <td data-bbox="1145 546 1485 573">30.0%</td> </tr> <tr> <td data-bbox="453 580 794 607">Practical exercise</td> <td data-bbox="799 580 1141 607">50.0%</td> <td data-bbox="1145 580 1485 607">30.0%</td> </tr> </tbody> </table>			Subject passing criteria	Passing threshold	Percentage of the final grade	Written exam	50.0%	40.0%	Midterm colloquium	50.0%	30.0%	Practical exercise	50.0%	30.0%
Subject passing criteria	Passing threshold	Percentage of the final grade													
Written exam	50.0%	40.0%													
Midterm colloquium	50.0%	30.0%													
Practical exercise	50.0%	30.0%													
Recommended reading	<table border="1"> <tbody> <tr> <td data-bbox="453 620 794 1160">Basic literature</td> <td colspan="2" data-bbox="799 620 1485 1160">           Korbicz J., Kościelny J., Modelowanie, diagnostyka i sterowanie nadrzędne procesami            Implementacja w systemie DiaSter, WNT, 2009             Tatjewski P. Sterowanie zaawansowane obiektów przemysłowych, Akademyka Oficyna Wydawnicza EXIT, 2002             Grega W. Metody i algorytmy sterowania cyfrowego w układach scentralizowanych i rozproszonych, Wydawnictwo AGH, 2004             Niederliński A. Systemy komputerowe automatyki przemysłowej, tom 1, Sprzęt i oprogramowanie, WNT, 1984.             Niederliński A. Systemy komputerowe automatyki przemysłowej, tom 2, Zastosowania, WNT, 1985.         </td> </tr> <tr> <td data-bbox="453 1167 794 1377">Supplementary literature</td> <td colspan="2" data-bbox="799 1167 1485 1377">           Trybus L. Regulatory wielofunkcyjne, WNT, 1992             Astrom K., Wittenmark B., Computer-Controlled Systems: Theory and Design (3rd Edition), Prentice Hall, 1996         </td> </tr> <tr> <td data-bbox="453 1384 794 1384">eResources addresses</td> <td colspan="2" data-bbox="799 1384 1485 1384">Adresy na platformie eNauczanie:</td> </tr> </tbody> </table>			Basic literature	Korbicz J., Kościelny J., Modelowanie, diagnostyka i sterowanie nadrzędne procesami Implementacja w systemie DiaSter, WNT, 2009  Tatjewski P. Sterowanie zaawansowane obiektów przemysłowych, Akademyka Oficyna Wydawnicza EXIT, 2002  Grega W. Metody i algorytmy sterowania cyfrowego w układach scentralizowanych i rozproszonych, Wydawnictwo AGH, 2004  Niederliński A. Systemy komputerowe automatyki przemysłowej, tom 1, Sprzęt i oprogramowanie, WNT, 1984.  Niederliński A. Systemy komputerowe automatyki przemysłowej, tom 2, Zastosowania, WNT, 1985.		Supplementary literature	Trybus L. Regulatory wielofunkcyjne, WNT, 1992  Astrom K., Wittenmark B., Computer-Controlled Systems: Theory and Design (3rd Edition), Prentice Hall, 1996		eResources addresses	Adresy na platformie eNauczanie:				
Basic literature	Korbicz J., Kościelny J., Modelowanie, diagnostyka i sterowanie nadrzędne procesami Implementacja w systemie DiaSter, WNT, 2009  Tatjewski P. Sterowanie zaawansowane obiektów przemysłowych, Akademyka Oficyna Wydawnicza EXIT, 2002  Grega W. Metody i algorytmy sterowania cyfrowego w układach scentralizowanych i rozproszonych, Wydawnictwo AGH, 2004  Niederliński A. Systemy komputerowe automatyki przemysłowej, tom 1, Sprzęt i oprogramowanie, WNT, 1984.  Niederliński A. Systemy komputerowe automatyki przemysłowej, tom 2, Zastosowania, WNT, 1985.														
Supplementary literature	Trybus L. Regulatory wielofunkcyjne, WNT, 1992  Astrom K., Wittenmark B., Computer-Controlled Systems: Theory and Design (3rd Edition), Prentice Hall, 1996														
eResources addresses	Adresy na platformie eNauczanie:														
Example issues/ example questions/ tasks being completed	<p>What are the differences between centralized and distributed control system          Outline the main features and benefits of predictive control          Enter the difference between direct and indirect adaptive control          Introduce hierarchicznego structure of the control system and specify the tasks of each layer          What is the method of AHP?          What are the principles of the design of the control system</p>														
Work placement	Not applicable														