

Subject card

Subject name and code	Numerical Methods in Automatic Control - laboratory, PG_00047694								
Field of study	Automatic Control, Cybernetics and Robotics								
Date of commencement of studies	October 2023		Academic year of realisation of subject			2025/2026			
Education level	first-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	6		ECTS credits			2.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Decision Systems and Robotics -> Faculty of Electronics, Telecommunications and Informatics						and		
Name and surname	Subject supervisor		mgr inż. Sebastian Dziedziewicz						
of lecturer (lecturers)	Teachers		mgr inż. Seba	ewicz					
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
of instruction	Number of study hours	0.0	0.0	30.0	0.0		0.0	30	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation ir classes includ plan				Self-study SUM		SUM	
	Number of study hours	30		2.0		18.0		50	
Subject objectives	Learning and mastering the practice of modern numerical algorithms required to solve number of engineering problems.								
Learning outcomes	Course outcome		Subject outcome		Method of verification				
	[K6_U01] can apply knowledge to formula complex and non-typ related to the field of perform tasks, in an way, in not entirely p conditions, by:n- app selection of sources information obtained assessment, critical a synthesis of this information and application appropriate methods	Student is able to analyze mathematical problems and choose appropriate numerical methods to solve them. Student is able to use external sources when solving numerical problems.			[SU2] Assessment of ability to analyse information [SU3] Assessment of ability to use knowledge gained from the subject				
	[K6_U04] can apply knowledge of programming methods and techniques as well as select and apply appropriate programming methods and tools in computer software development or programming devices or controllers using microprocessors or programmable elements or systems specific to the field of study		Student is able to implement numerical methods algorithms. Student is able to assess the correctness of numerical algorithms.			[SU1] Assessment of task fulfilment [SU4] Assessment of ability to use methods and tools			

Data wydruku: 19.05.2024 14:43 Strona 1 z 2

Subject contents	 Numbers representation, errors, numerical stability. Solution of linear algebraic equations: Gauss elimination. LU factorization, the matrix inverse, vector and matrix norms, matrix condition number. Solution of systems of nonlinear equations: Newton-Raphson method. LQR optimal control. Approximation. Nonlinear regression. Least squares method. Kalman filtering. Interpolation. Newton polynomials. Splines and piecewise interpolation. Numerical integration of functions. Romberg method. Gauss quadrature. Solution of ordinary differential equations: Euler's method, Heun's method, midpoint method. Solution of systems of ordinary differential equations: Runge-Kutta method. Equations and systems of differential equations: boundary-value problems. Finite-difference method. 					
Prerequisites and co-requisites						
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade			
and criteria	Programming excercises	50.0%	100.0%			
Recommended reading	Basic literature	Lecture notes in Numerical Methods in Automation and Robotics.				
G The state of the	Supplementary literature • Anthony Ralston, A First Course in Numerical Analysis, 2nd edition, Dover Publications, 2001. • Numerical Recipes in C, Second Edition (1992), http://http://www.nrbook.com/a/bookcpdf.php. • Steven C. Chapra, Applied Numerical Methods with MATLAB for Engineers and Scientists, 2nd edition, McGraw-Hill, 2006.					
	eResources addresses	Adresy na platformie eNauczanie:				
Example issues/ example questions/ tasks being completed	The least squares method in identifying the transmittance of a dynamic linear object. Implementation of the Kalman filter for a discrete system. Solving ordinary differential equations using Runge-Kutta methods. Solving partial differential equations using the finite difference method.					
Work placement	Not applicable					

Data wydruku: 19.05.2024 14:43 Strona 2 z 2