

## Subject card

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Subject name and code	, PG_00053425								
Field of study	Automation, Robotics and Control Systems								
Date of commencement of studies	October 2020		Academic year of realisation of subject			2023/2024			
Education level	first-cycle studies		Subject group						
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	4		Language of instruction			Polish			
Semester of study	7		ECTS credits			3.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Power	d Electrical Machines -> Faculty of Electrical and Control Engineering							
Name and surname	Subject supervisor		dr hab. inż. Jarosław Łuszcz						
of lecturer (lecturers)	Teachers								
Lesson types and methods	Lesson type	Lecture	Tutorial Laboratory Project		:t	Seminar	SUM		
of instruction	Number of study hours	15.0	0.0 15.0 0.0			0.0	30		
	E-learning hours inclu			<u> </u>		0 15 1		lour.	
Learning activity and number of study hours	Learning activity	Participation in classes include plan		Participation i consultation h			udy	SUM	
	Number of study hours	30		5.0		40.0		75	
Subject objectives	Understanding the basic physical phenomena related to the disturbances in the control and automation systems.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_W06] knows the structure of computers and microprocessors and the tasks of operating systems, has basic knowledge of the basics of computer software, drivers, microprocessor technology, design of simple algorithms and the operation of information networks		knows the causes of interference in control systems			[SW2] Assessment of knowledge contained in presentation			
	[K6_W10] has basic knowledge related to mechatronics and robotics systems		has basic knowledge in the field ofdevice interference			[SW1] Assessment of factual knowledge			
	[K6_U01] can obtain information from literature, databases and other sources; integrate the information obtained, interpret it and draw conclusions, formulate and justify opinions		is able to use literature sources to solve interference problems			[SU1] Assessment of task fulfilment			
	a presentation on the problems		is able to prepare and present studies on issues related to interference			[SU5] Assessment of ability to present the results of task			
Subject contents	Sources and propagation of conducted and radiated disturbances. Electromagnetic emission and immunity of automation systems. Inductive and capacitive parasitic couplings. Characteristics of power and signal circuits in the field of EMC. Interference protection in analog, digital and mixed circuits. Typical causes of disturbances in control and automation systems. Interference reduction methods (filtration, decoupling, shielding). The role of grounding, shielding and equipotentialization in reducing interference. Crosstalk in signal transmission paths. Attenuation of interference in analog signal transmission paths (0-10V, 4-20mA). Attenuation of interference in digital signal transmission paths (RS232, RS485, Ethernet)								
Prerequisites and co-requisites									
Assessment methods and criteria	Subject passing criteria		Passing threshold			Percentage of the final grade			
	Task report		50.0%		50.0%				
	Lecture reports		50.0%			50.0%			

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Recommended reading	Basic literature	Spiralski L., Kołodziejski J., Konczakowska A., Hasse L. Zakłócenia w aparaturze elektronicznej. Charoy A.: Electromagnetic compatibility. Interference in electronic devices. Volume 1-4. Bogtin E.: Signal and Power Integrity - Simplified.				
	Supplementary literature	Ott H. W. Metody redukcji zakłóceń i szumów w układach elektronicznych. Howard W. Johnson, Martin Graham: High-speed Signal Propagation: Advanced Black Magic.				
	eResources addresses	Adresy na platformie eNauczanie:				
Example issues/ example questions/ tasks being completed	Analysis of digital signal transmission interference in serial interfaces. Analysis of the transmission interference of 20 mA analog signals.					
Work placement	Not applicable					

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