

GDAŃSK UNIVERSITY

Subject card

Subject name and code	Drive Automatics and Servomechanisms, PG_00038107								
Field of study	Automation, Robotics and Control Systems								
Date of commencement of studies	October 2021		Academic year of realisation of subject			2023/2024			
Education level	first-cycle studies		Subject group						
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	5		ECTS credits			5.0			
Learning profile	general academic profile		Assessment form			exam			
Conducting unit	Department of Controlled Electric Drives -> Faculty of Electrical and Control Engineering								
Name and surname	Subject supervisor dr inż. Mirosław Włas								
of lecturer (lecturers)	Teachers		dr inż. Mirosław Włas						
			dr hab. inż. Elżbieta Bogalecka						
			dr hab. inż. Arkadiusz Lewicki						
			prof. dr hab. inż. Marcin Morawiec						
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
of instruction	Number of study	30.0	0.0	30.0	0.0		0.0	60	
	hours								
Learning activity and number of study hours	E-learning hours included: 0.0 Learning activity Participation in didactic Participation in Self-study §					CLIM			
	Learning activity	classes include plan				Self-study SUM			
	Number of study hours	60		8.0		57.0		125	
Subject objectives	The aims of the course are: to show the principles and applications of industrial controlled electrical drives, including the principles of operation of electrical machines, introduction to the physics of motion control and energy conversion., to learn methods of controlling servodrives.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_U05] can use analytical and simulation methods to solve tasks in the field of automation and robotics and use various techniques to carry out engineering tasks related to automation and robotics devices and systems		ability to prepare a reliable laboratory test report. the student is able to configure and select controller parameters on a real object			[SU3] Assessment of ability to use knowledge gained from the subject [SU5] Assessment of ability to present the results of task			
	[K6_W08] knows the basics of equipment selection and control of electrical machines and servos		the student is able to configure and select controller parameters on a real object the student is able to select the parameters of the drive system components for the application			[SW1] Assessment of factual knowledge			
	[K6_K05] can think and act in an entrepreneurial way		ability to organize work in a laboratory group to complete a given task. ability to select tools, measurement methods and sequence to perform a complex task.			[SK1] Assessment of group work skills [SK5] Assessment of ability to solve problems that arise in practice			
Subject contents	Machine as an actuator in the control system, the rules of position, speed and torque control of electrical machines, equations of motion. Types of electrical machines, load characteristics, operating point of the drive, mechanical characteristics . Types of electrical machines and their properties. The structure of control system. Selection of control variables and parameters, measurement of electrical and mechanical variables. Energy Recovery during braking . Influence of limitations to the quality of control. Terms of scalar and vector control of AC machine. Servomechanism: control structures, distortions, effect of friction, gravity, moment of inertia and the load on quality control. Analysis of selected industrial applications: lift, winch, winder, the drive traction, a robot arm.								

Prerequisites and co-requisites	Knowledge of the basics of power electronics, electrical engineering, including transients in electrical circuits, mechanics and control theory					
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade			
and criteria	Laboratory reports	60.0%	50.0%			
	Exam	50.0%	50.0%			
Recommended reading	Basic literature	 Laboratory instructions and lectures reported in www.ely.pg.gda.pl/ KANE Zawirski K, Deskur J.: Automatyka napędu elektrycznego, 2012. Bielawski C.: Automatyka napędu elektrycznego, WNT, 1980. 				
	Supplementary literature	 Krzemiński Z.: Cyfrowe sterowanie maszynami asynchronicznymi, Gdańsk, Wydawnictwo PG, 2003. Orłowska-Kowalska T.: Bezczujnikowe układy napędowe z maszynami asynchronicznymi, Oficyna Wydawnicza politechniki Wrocławskiej, 2005. Zawirski K.: Układy napędowe z maszynami synchronicznymi, Wydawnictwo Politechniki Poznańskiej, Poznań, 2005. 				
	eResources addresses	lle/course/view.php?id=16839 - structions OMECHANIZMY [2023/24] - Moodle lle/course/view.php?id=32142				
Example issues/ example questions/ tasks being completed	 Equation of motion Mathematical model of DC machine The rules of the controller parameters setting Servodrive control system structure V/f control of induction machine 					
Work placement	Not applicable					