

。 GDAŃSK UNIVERSITY OF TECHNOLOGY

Subject card

Subject name and code	Technology of Marine Control Systems, PG_00061843								
Field of study	Design and Construction of Yachts								
Date of commencement of studies	October 2023		Academic year of realisation of subject			2025/2026			
Education level	first-cycle studies		Subject group						
Mode of study			Mode of delivery			at the	at the university		
Year of study	3		Language of instruction			Polish	Polish		
Semester of study	6		ECTS credits			5.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Division of Automation and Marine Energy -> Institute of Naval Architecture -> Faculty of Mechanical Engineering and Ship Technology								
Name and surname	Subject supervisor		dr inż. Mohammad Ghaemi						
of lecturer (lecturers)	Teachers								
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
	Number of study hours	30.0	15.0	0.0	15.0	0.0		60	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity Participation in classes include plan				Self-study SUM		SUM		
	Number of study hours	60		0.0		0.0		60	
Subject objectives	The aim of the course is to familiarize students with the basic and most important technologies applied in the regulation, control and monitoring of ship systems, mainly applied for yachts.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_K03] is aware of the impact of non-technical aspects on the engineer's work and the impact of engineering activities on the natural environment								
	[K6_U02] can work individually and in a team, communicate through various techniques in professional environment and also record, analyse, and present the results of work, can estimate the time needed to complete a given task		The student can communicate with professionals using various techniques (including simulation) used in the analysis and synthesis of the structure, elements and modules implemented in marine control systems (particularly in yachts) as well as document, analyze and present the results of his/her work related to the tasks performed in the field of the initial design of control systems of selected systems ships.			[SU1] Assessment of task fulfilment			
	field of computer science, electronics, electrical engineering, automation and control, information technology, computer graphics, useful for understanding		The student has knowledge in the field of technology of automation and control systems of major marine systems, particularly applied in yachts, useful for analyzing their application in marine technology.			[SW1] Assessment of factual knowledge			

 Overview of the process of designing the control system by taking into account the aspects - example Measuring elements, sensors, transducers and transformers - types and classificat measuring elements (including: sensors and transducers/transformers of position, and force, pressure, temperature, flow, liquid level and sensors used in underwate Servomechanisms and actuators used in control systems - types and characterist servomechanisms and hydraulic and pneumatic actuators, as well as control valve Modeling, simulation and control of the yacht's propulsion system, including angular remote control of the propulsion system, control of multi-propeller and/or multi-eng 	e technological ation, characteristics of , angular velocity, load er technology). iics, including:							
 Overview of the process of designing the control system by taking into account the aspects - example Measuring elements, sensors, transducers and transformers - types and classificar measuring elements (including: sensors and transducers/transformers of position, and force, pressure, temperature, flow, liquid level and sensors used in underwate Servomechanisms and actuators used in control systems - types and characterist servomechanisms and hydraulic and pneumatic actuators, as well as control valve Modeling, simulation and control of the yacht's propulsion system, including angular remote control of the propulsion system, control of multi-propeller and/or multi-enge 	e technological ation, characteristics of , angular velocity, load er technology). iics, including:							
6. Logic and sequence control, including relays and switching, Boolean algebra, gate	 Overview of the process of designing the control system by taking into account the technological aspects - example Measuring elements, sensors, transducers and transformers - types and classification, characteristics of measuring elements (including: sensors and transducers/transformers of position, angular velocity, load and force, pressure, temperature, flow, liquid level and sensors used in underwater technology). Servomechanisms and actuators used in control systems - types and characteristics, including: servomechanisms and hydraulic and pneumatic actuators, as well as control valves. Modeling, simulation and control of the yacht's propulsion system, including angular speed control, remote control of the propulsion system, control of multi-propeller and/or multi-engine propulsion systems Logic and sequence control, including relays and switching, Boolean algebra, gate logic, ladder diagrams, logic components, programmable logic controllers and their programming. Automatic control of the selected yacht's systems SCADA, OPC, HMI, IoT, and communication standards and protocols 							
Prerequisites Theory of Marine Control Systems and co-requisites Theory of Marine Control Systems	Theory of Marine Control Systems							
Assessment methods Subject passing criteria Passing threshold Percenta	ge of the final grade							
and criteria Tutorials 51.0% 25.0%	<u>v</u>							
Lecture 56.0% 45.0%								
Project 51.0% 30.0%								
Recommended reading Basic literature 1. Hugh J., Integration and Automation of Manufa (Robots, PLC, CNC), 2001. 2. Shell R. L., Hall E. L., Handbook of Industrial A University of Cincinnati, Ohio, Marcel Dekker Inc.	Automation, ed.,							
Supplementary literature 1. Kank C., Diesel Motor Ships' Engines and Mac Marine Engineering, London, 1990.	1. Kank C., Diesel Motor Ships' Engines and Machinery, Institute of Marine Engineering, London, 1990.							
eResources addresses Adresy na platformie eNauczanie:	Adresy na platformie eNauczanie:							
Example issues/ example questions/ tasks being completed								
Work placement Not applicable								

Document generated electronically. Does not require a seal or signature.