



Subject card

Subject name and code	Change Detection in Signals, PG_00048470						
Field of study	Automatic Control, Cybernetics and Robotics						
Date of commencement of studies	February 2024	Academic year of realisation of subject			2023/2024		
Education level	second-cycle studies	Subject group			Optional subject group Subject group related to scientific research in the field of study		
Mode of study	Full-time studies	Mode of delivery			at the university		
Year of study	1	Language of instruction			Polish		
Semester of study	1	ECTS credits			1.0		
Learning profile	general academic profile	Assessment form			assessment		
Conducting unit	Department of Decision Systems and Robotics -> Faculty of Electronics, Telecommunications and Informatics						
Name and surname of lecturer (lecturers)	Subject supervisor	dr inż. Janusz Kozłowski					
	Teachers	dr inż. Janusz Kozłowski					
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	0.0	0.0	0.0	15
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan	Participation in consultation hours		Self-study	SUM	
	Number of study hours	15	2.0		8.0	25	
Subject objectives	<p>Assimilation of principles of mathematical modelling of dynamic systems.</p> <p>Expanding knowledge on parameter identification and change detection algorithms.</p> <p>Practical implementations of algorithms.</p>						
Learning outcomes	Course outcome	Subject outcome			Method of verification		
	[K7_U03] can design, according to required specifications, and make a complex device, facility, system or carry out a process, specific to the field of study, using suitable methods, techniques, tools and materials, following engineering standards and norms, applying technologies specific to the field of study and experience gained in the professional engineering environment	Student got practical knowledge on mathematical modelling of control systems, learned the identification methods of deterministic and stochastic models.			[SU4] Assessment of ability to use methods and tools		
	[K7_W03] Knows and understands, to an increased extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum.	Student got practical knowledge on applications of the on-line detection and identification procedures. Student got familiar with analytical methods for examination of algorithms.			[SW1] Assessment of factual knowledge		
	K7_K02	Student solved practical problems using expert knowledge on system identification and rationally compares different approaches.			[SK2] Assessment of progress of work		

Subject contents	<p>Selected applications of detection methods.</p> <p>Deterministic and stochastic models. Linear integrating filters and Poisson moment functionals in discrete-time approximations of continuous systems.</p> <p>Estimation of process parameters and detection of parameter variations using parameter identification methods: properties of algorithms.</p> <p>Least-squares method: recursive and non-recursive algorithms.</p> <p>Instrumental-variable method, properties of the method and selection of instrumental variables.</p> <p>Tracking the evolution of process parameters with the aid of error weighting mechanism.</p> <p>Robust to measurement faults parameter identification algorithms derived from minimization of non-quadratic criteria. Applications of robust algorithms in diagnostics.</p> <p>Minimization of non-quadratic criteria: simplex method and recursively-iterative method.</p> <p>Direct method of continuous-time system identification.</p> <p>Identification of delay systems, systems with nonlinearities and distributed parameter systems.</p>								
Prerequisites and co-requisites									
Assessment methods and criteria	<table border="1"> <thead> <tr> <th data-bbox="453 1099 798 1128">Subject passing criteria</th> <th data-bbox="801 1099 1142 1128">Passing threshold</th> <th data-bbox="1145 1099 1485 1128">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="453 1133 798 1227">Final test on theory. It is necessary to score at least 13 out of total amount of 25 pts. Time for the test: 60 minutes.</td> <td data-bbox="801 1133 1142 1227">50.0%</td> <td data-bbox="1145 1133 1485 1227">100.0%</td> </tr> </tbody> </table>	Subject passing criteria	Passing threshold	Percentage of the final grade	Final test on theory. It is necessary to score at least 13 out of total amount of 25 pts. Time for the test: 60 minutes.	50.0%	100.0%		
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Recommended reading	<p>Basic literature</p> <p>Supplementary literature</p> <p>eResources addresses</p>	<p>Basseville M., Nikiforov I.V.: Detection of abrupt changes: theory and application. Prentice-Hall Inc., 1993.</p> <p>Ljung L.: System identification. Theory for the user. Prentice-Hall Inc., 1987.</p> <p>Korbicz J., Kościelny J.M., Kowalczyk Z., Cholewa W. (Editors): Fault diagnosis: models, artificial intelligence, applications. Springer, Berlin New York, 2004.</p> <p>Anderson B.D.O., Moore J.B.: Optimal filtering. Information and System Sciences Series. Prentice-Hall Inc., 1979.</p> <p>Adresy na platformie eNauczanie:</p>							

<p>Example issues/ example questions/ tasks being completed</p>	<ol style="list-style-type: none"> 1. Specify in brief possible applications of change detection algorithms. Explain why abrupt changes do not necessarily mean changes large in magnitude. 2. Enumerate and describe in brief common performance indices used for evaluation of quality of change detection. 3. Compare the Kalman approach and the Wiener approach to optimal filtering. Indicate situations where Kalman filter demonstrates its supremacy. 4. Compare the so-called direct and indirect approaches to identification of continuous-time systems. Enumerate the benefits and drawbacks of both concepts. 5. Describe the direct method of identification of continuous-time systems based on the method of linear integral filtering (LIF). Introduce the transfer function of the LIF operator and derive the ultimate formula for the numerical LIF realization using the bilinear operator. Formulate and justify the rule of thumb for proper selection of the integration horizon.
<p>Work placement</p>	<p>Not applicable</p>