

## Subject card

Subject name and code	Robotics and haptics systems, PG_00057036								
Field of study	Mechatronics								
Date of commencement of studies	February 2024		Academic year of realisation of subject			2024/2025			
Education level	second-cycle studies		Subject group			Obligatory subject group in the field of study Subject group related to scientific			
	F # 6					research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	2		Language of instruction			Polish			
Semester of study	3		ECTS credits			4.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Zakład Mechatroniki -> Institute of Mechanics and Machine Design -> Faculty of Mechanical Engineering and Ship Technology								
Name and surname	Subject supervisor	Subject supervisor dr inż. Michał Mazur							
of lecturer (lecturers)	Teachers				_				
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
of instruction	Number of study hours	15.0	0.0	30.0	0.0		0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	45		10.0		45.0		100	
Subject objectives	The aim of the subject is to familiarize students with the construction, application and principle of operation of haptic systems used in robotics.								
Learning outcomes	Course outcome		Subject outcome		Method of verification				
	[K7_W10] knows development trends and most important new achievements in technical sciences and science disciplines: Mechanical Engineering, Automation, Electronics and Electrical Engineering and related: Informatics and Materials Engineering		knows developmental trends and the most important new achievements in the field of hapting solutions			[SW1] Assessment of factual knowledge			
	[K7_U02] potrafi przygotować opracowanie naukowe w języku polskim i krótkie doniesienie naukowe w języku obcym dotyczące szczegółowych zagadnień z zakresu Mechatroniki, a także – dziedzin nauk technicznych i dyscyplin naukowych: Inżynieria Mechaniczna oraz Automatyka, Elektronika i Elektrotechnika, i pokrewnych, właściwych dla mechatroniki, przedstawiające wyniki własnych badań naukowych		is able to prepare a scientific study in Polish and a short scientific report in a foreign language regarding detailed issues related to haptics in use for control of robots			[SU5] Assessment of ability to present the results of task [SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject [SU2] Assessment of ability to analyse information [SU1] Assessment of task fulfilment			
[K7_W06] has detailed, suppor by the theory knowledge in terr of mechatronic design, mechatronic systems and machines, devices and process where they are used		edge in terms in, s and nd process	has theoretically included detailed knowledge related to the design issues of devices using haput solutions			[SW3] Assessment of knowledge contained in written work and projects [SW2] Assessment of knowledge contained in presentation			

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Subject contents	iect contents 1. Basic knowledge about haptics and robotics						
Subject contents	1. Dasic knowledge about naptics and robotics						
	2. Designing hapting systems						
	3. Software						
	Review of existing solutions						
	1. Terrori of ordering conditions						
Prerequisites	Knowledge in the field of mechatronic design, automation and robotics, programming and vibration analysis						
and co-requisites							
Assessment methods	Cubicat passing suitaria	Descine threehold	Daysaytaga of the final guade				
and criteria	Subject passing criteria Test	Passing threshold 50.0%	Percentage of the final grade 60.0%				
and ontona	Report	50.0%	40.0%				
5	Basic literature		1.0.0%				
Recommended reading	Basic literature	Janschek, Klaus. Mechatronic systems design: methods, models, concepts. Springer Science & Business Media, 2011.					
		Hatzfeld, Christian, and Thorsten A. Kern. <i>Engineering haptic devices</i> . Springer London Limited, 2016.					
	Supplementary literature	Kaltenbacher, Manfred. Numerical simulation of mechatronic sensors and actuators. Vol. 2. Berlin: Springer, 2007.					
		Eric Vezzoli, Chris Ullrich, Gijs den Butter, Rafal Pijewski. XR Haptics,					
		Implementation & Design Guidelines. 2022					
	eResources addresses Adresy na platformie eNauczanie:						
Example issues/	What is a haptic?2. What are the differences between the sense of touch and the sense of sight?3.  Discuss the differences between kinesthetic and tactile sensors.4. What is the difference between haptic.						
example questions/ tasks being completed	devices whose construction is based on impedance and those based on admittance?5. List the applications						
tasks being completed	of haptic systems.6. What frequency ranges can be used in haptic systems?7. Types of drives used in haptic systems.8. How is sliding control implemented?9. What is image segmentation.						
Work placement	Not applicable						
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