

Subject card

| Subject name and code | Dynamic Signals and Systems, PG_00058787 | | | | | | | | |
|---|---|--|---|-------------------------------------|---|---------------------------------------|-----------------|-------------|--|
| Field of study | Electrical Engineering | | | | | | | | |
| Date of commencement of studies | October 2022 | | Academic year of realisation of subject | | | 2024/2025 | | | |
| Education level | first-cycle studies | | Subject group | | | | | | |
| Mode of study | Full-time studies | | Mode of delivery | | | at the university | | | |
| Year of study | 3 | | Language of instruction | | | Polish | | | |
| Semester of study | 5 | | ECTS credits | | | 3.0 | | | |
| Learning profile | general academic profile | | Assessment form | | | assessment | | | |
| Conducting unit | Katedra Inteligentnych Systemów Sterowania i Wspomagania Decyzji -> Faculty of Electrical and Control Engineering | | | | | | | and Control | |
| Name and surname | Subject supervisor | | dr inż. Bartosz Puchalski | | | | | | |
| of lecturer (lecturers) | Teachers | | dr inż. Bartosz Puchalski dr inż. Tomasz Rutkowski | | | | | | |
| Lesson types and methods | Lesson type | Lecture | Tutorial | Laboratory | Projec | t | Seminar | SUM | |
| of instruction | Number of study hours | 30.0 | 0.0 | 15.0 | 0.0 | | 0.0 | 45 | |
| | E-learning hours incli | uded: 0.0 | | | | | | | |
| Learning activity and number of study hours | Learning activity | Participation i classes including plan | | Participation in consultation hours | | Self-study | | SUM | |
| | Number of study hours | 45 | | 3.0 | | 27.0 | | 75 | |
| Subject objectives | The objective of the canalysis and process | | e student to acc | quire adequate | knowle | dge and | d skills in the | signal | |
| Learning outcomes | Course outcome | | Subject outcome | | | Method of verification | | | |
| | K6_W08 | | Performs frequency analysis of continuous and discrete signals. Determines relationships between spectra of sampled signals and analog originals. Models and analyzes linear continuous and discrete dynamic systems in the time and frequency domain. Determines relationships between spectra of analog reconstructions and discrete originals. | | | [SW1] Assessment of factual knowledge | | | |
| | K6_U04 | | Computes the discrete Fourier transform (DFT) for analyzing discrete signals and sampled continuous signals. Designs and implements digital filters. | | [SU1] Assessment of task fulfilment [SU4] Assessment of ability to use methods and tools [SU2] Assessment of ability to analyse information | | | | |
| Subject contents | LECTURE Continuous-time and discrete-time signals. Sampling. Frequency of discrete-time signals. Sampling theorem. Complex exponential signal. Fourier series of continuous-time signals. Fourier series of discrete-time signals. Fourier transform of continuous-time and discrete-time signals. Discrete Fourier transform. Z transform. Basic properties of systems. Representing linear dynamic systems: differential and difference equations, transfer function, frequency response, discrete convolution. Transmission of signals through linear systems. Basic structures of digital filters. Digital filter design by analog prototyping. Reconstruction of analog signals. Downsampling and upsampling. LABORATORY Fourier series. Implementation of discrete Fourier transform (DFT). Using sampling and DFT for the analysis of selected continuous-time signals (square wave, sawtooth etc.). Spectral analysis of distorted signals in three-phase systems. Computing the total harmonic distortion (THD) of these waveforms. Design, implementation and testing of selected digital filters. Implementation and analysis of the phase-locked loop (PLL) algorithm. | | | | | | | | |

Data wygenerowania: 21.11.2024 23:29 Strona 1 z 2

| Prerequisites and co-requisites | | | | | | |
|------------------------------------|---|---|-------------------------------|--|--|--|
| Assessment methods | Subject passing criteria | Passing threshold | Percentage of the final grade | | | |
| and criteria | Reports and tests related to laboratory exercises | 50.0% | 50.0% | | | |
| | Test of lecture-related knowledge | 50.0% | 50.0% | | | |
| Recommended reading | Basic literature | Śleszyński W.: Sygnały i systemy dynamiczne. Politechnika Gdańska, Wydział Elektrotechniki i Automatyki, Gdańsk 2010. | | | | |
| | | 2. Wojciechowski J. M.: Sygnały i systemy. WKŁ, Warszawa 2008. | | | | |
| | | 3. Zieliński T.P.: Cyfrowe przetwarzanie sygnałów. WKŁ, Warszawa 2007. | | | | |
| | | 4. Oppenheim A. V., Willsky A. S., Nawab S. H.: Signal and Systems. Prentice-Hall, 1997 | | | | |
| | | 5. Chen CT.: System and Signal Analysis. Saunders College Publishing, 1994 | | | | |
| | Supplementary literature | Szabatin J.: Podstawy teorii sygnałów. WKŁ, Warszawa 2000. | | | | |
| | | 2. Izydorczyk J., Płonka G., Tyma G.: Teoria sygnałów. Helion, Gliwice 1999. | | | | |
| | | 3. Gabel R., Roberts R. A.: Sygnały i systemy liniowe. WNT, Warszawa 1978 | | | | |
| | | 4. Lyons R.G.: Wprowadzenie do cyfrowego przetwarzania sygnałów. Warszawa: WKŁ 2000. | | | | |
| | | 5. Oppenheim A. V., Schafer R.W.: Cyfrowe przetwarzanie sygnałów. WKŁ, Warszawa 1979 | | | | |
| | | 6. Franklin G.F., Workman M.L., Powell D.: Digital Control of Dynamic Systems. Addison-Wesley, 1998. | | | | |
| | eResources addresses | Adresy na platformie eNauczanie: SYGNAŁY I SYSTEMY DYNAMICZNE [ET][2024/25] - Moodle ID: 39834 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=39834 | | | | |
| Example issues/ example questions/ | 1. A periodic sequence of period N is made of the following samples (per period): 4, 2, 0, 3, 0, -3, 2, 0. Find the Fourier series coefficient c2. 2. Draw a block schematic of the discrete-time system defined by a given transfer function. | | | | | |
| tasks being completed | 3. Find the difference equation of the dynamic system defined by a given transfer function. Compute the first 6 samples of the response of the system to a given input sequence. 4. Find the difference equation an transfer function of the filter defined by a given block schematic. Compute the filter gain for selected frequencies. 5. Using the "Euler backward" method (s = (1 - 1/z) / T), digitize the PI controller with the following transmittance: R(s) = Kp + Ki / s. Give the differential equation of the controller. Calculate the steady-state value of the impulse response and the starting value of the step response. | | | | | |
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| Work placement | Not applicable | | | | | |

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Data wygenerowania: 21.11.2024 23:29 Strona 2 z 2