



Subject card

Subject name and code	, PG_00061800						
Field of study	Automation, Robotics and Control Systems						
Date of commencement of studies	October 2021		Academic year of realisation of subject		2024/2025		
Education level	first-cycle studies		Subject group				
Mode of study	Full-time studies		Mode of delivery		at the university		
Year of study	4		Language of instruction		Polish		
Semester of study	7		ECTS credits		3.0		
Learning profile	general academic profile		Assessment form		assessment		
Conducting unit	Department of Controlled Electric Drives -> Faculty of Electrical and Control Engineering						
Name and surname of lecturer (lecturers)	Subject supervisor		dr inż. Mirosław Włas				
	Teachers						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	15.0	0.0	0.0	30
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	30		5.0		40.0	75
Subject objectives	The main content is the design, integration and visualization of industrial process control systems, constructed on the basis of CSCADA class visualization software. Types of industrial facilities with PLCs and converters. Types and methods of control of industrial automation systems. Principles of selection of conductors and apparatuses and protections for power electronic equipment. Selection of control and control apparatus. Machine safety. Methods of creating designs and drawing electrical diagrams. Hardware requirements for automatic control and regulation systems.						
Learning outcomes	Course outcome		Subject outcome		Method of verification		
Subject contents	LECTURE						
	The main content is the design, integration and visualization of industrial process control systems, constructed on the basis of CAD/CAD class design software and SCADA class visualization software. Types of industrial objects with PLCs and converters. Types and methods of control of industrial automation systems. Principles of selection of conductors and apparatuses and protection for power electronic equipment. Selection of control and control apparatus. Power supply and redundancy of industrial automation systems, PLCs and LCD touch panels. Machine safety - safety categories and stop categories. Methods of creating designs and drawing electrical diagrams. Hardware requirements for automatic control and regulation systems.						
	LABORATORY EXERCISES						
	During the course of the exercise, which is set for the whole semester, students will get acquainted with a wide range of tasks carried out by modern industrial automation systems, starting from the automation of the production process with the use of PLCs, frequency converters with induction motors, servo drives with PMSM motors, through the visualization and control of the process from the level of SCADA class control and supervision stations. The laboratory is equipped with PCs, software: iFIX 4.5, InTouch 10, Citec 6.1, Borland C, as well as drive systems, industrial automation systems and taskers that are models of real industrial objects.						

Prerequisites and co-requisites			
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	Report	60.0%	100.0%
Recommended reading	Basic literature	1. Niestępski S., Parol M. i In.: Instalacje Elektryczne Budowa, Projektowanie i Eksploatacja Oficyna Wydawnicza Politechniki Warszawskiej, Warszawa 2001 2. Wiatr J.: Poradnik Projektanta Elektryka Dom Wydawniczy Medium Warszawa 2006. 3. Jakuszewski R.: Programowanie systemów SCADA. WPK J. Skalmierskiego, Gliwice 2002	
	Supplementary literature	J. Szymański Co warto wiedzieć o napięciowych przemiennikach częstotliwości Rzeszów 2001	
	eResources addresses	Adresy na platformie eNauczanie:	
Example issues/ example questions/ tasks being completed	1. Design and construction of a conveyor belt drive model (Mitsubishi st. 9). 2. Stepper motor control using EtherCAT (Beckhoff st. 2). 3. Drive of a goods-person elevator with an induction motor.(st. 7 FCM 300 inverter, PLC - Moeller XC-200). 4. Pumping station model.(st. 3, ABB inverter, Siemens S1200 controller). 5. Control of a 3-axis milling plotter.(st. 1. servo drives and stepper motors and PLC from B&R).		
Work placement	Not applicable		