

## 表 GDAŃSK UNIVERSITY OF TECHNOLOGY

## Subject card

Subject name and code	Mathematics I, PG_00022416							
Field of study	Automation, Robotics and Control Systems							
Date of commencement of studies	October 2024		Academic year of realisation of subject			2024/2025		
Education level	first-cycle studies		Subject group			Obligatory subject group in the field of study		
Mode of study	Full-time studies		Mode of delivery			at the university		
Year of study	1		Language of instruction			Polish		
Semester of study	1		ECTS cred	ECTS credits		6.0		
Learning profile	general academic profile		Assessme	nt form		exam		
Conducting unit	Mathematics Center -> Vice-Rector for Education							
Name and surname of lecturer (lecturers)	Subject supervisor		dr Magdalena Musielak					
	Teachers		dr Magdalena Musielak					
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project		Seminar	SUM
	Number of study hours	30.0	30.0	0.0	0.0	0.0		60
	E-learning hours included: 0.0							
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study		SUM
	Number of study hours	60		10.0		80.0		150
Subject objectives	Students obtain competence in the range of using methods of mathematical analysis and linear algebra and knowledge to solve simple problems that can be found in the field of engineering.							

Learning outcomes	Course outcome	Subject outcome	Method of verification			
	[K6_K02] can work in a group taking on different roles in it	Student recognizes the importance of self-expanding knowledge and takes the challenge of working with a group to solve a problem. Student understands the need of lifelong learning. Student is able to inspire others and organize their learning process.	[SK2] Assessment of progress of work [SK1] Assessment of group work skills			
	[K6_W01] has basic knowledge in the field of mathematics including algebra, geometry, mathematical analysis, probabilistics, numerical methods - necessary to describe and analyze automation and robotics systems	Student defines the basic concepts of differential calculus of one variable function. Student uses the first and second derivatives of a function to analyze its properties. Student determines intervals of monotonicity of a given function and its extrema. Student applies the basic rules and techniques of integration to calculate indefinite integrals. Student lists geometrical applications of definite integrals. Student uses definite integral to solve geometrical problems. Student distinguishes between the types of improper integrals. Student explains the definition of the cross product. Student uses the triple scalar product to give the volume of solids.	[SW3] Assessment of knowledge contained in written work and projects [SW1] Assessment of factual knowledge			
	[K6_U01] can obtain information from literature, databases and other sources; integrate the information obtained, interpret it and draw conclusions, formulate and justify opinions	Student is able to process the acquired information, analyze and interpret it, draw conclusions and reason opinions. Student recognizes the importance of skillful use of basic mathematical apparatus in terms of study in the future. Student recognizes the importance of self-expanding knowledge.	[SU3] Assessment of ability to use knowledge gained from the subject [SU2] Assessment of ability to analyse information [SU1] Assessment of task fulfilment			
Subject contents	Definition of a first derivative. Derivatives of elementary functions. Applications of derivatives - Taylors theorem, de IHospitals theorem, monotonicity and local extrema, convexity, concavity and inflexion points of a function, asymptotes. Applications of differential calculus to studying the properties of one variable functions. The process of finding antiderivatives - integration formulas, integration by parts and the substitution method of integration. Integration of rational, trigonometric and irrational functions. Definite integrals in Riemanns sense - Newton-Leibniz theorem, improper integrals, applications to geometry. Vectors in 3-space. Dot product, cross product, triple scalar product.					
Prerequisites and co-requisites	- active participation in tutorial - passing written tests and colloquiums					
Assessment methods	Subject passing criteria	Dessing threshold	Borooptogo of the final grade			
and criteria	Subject passing criteria Written and oral exam	Passing threshold 50.0%	Percentage of the final grade 50.0%			
	Midterm written and oral colloquium	50.0%	50.0%			
Recommended reading	Basic literature	<ol> <li>Gewert M., Skoczylas Z.: Analiza matematyczna 1. GiS, Wrocław, 2004.</li> <li>Jurewicz T., Skoczylas Z.: Algebra liniowa 1. GiS, Wrocław, 2004.</li> <li>Krysicki W., Włodarski L.: Analiza matematyczna w zadaniach, cz.I. PWN, Warszawa 2006.</li> <li>Leksiński W., Nabiałek I., Żakowski W.: Matematyka. Definicje, twierdzenia, przykłady, zadania. WNT, Warszawa, 2003.</li> </ol>				
	Supplementary literature	<ol> <li>Jankowska K., Jankowski T.: Zbiór zadań z matematyki. Wyd. PG, Gdańsk, 1998.</li> <li>Praca zbiorowa pod redakcją Wikieł B.: Matematyka. Podstawy z elementami matematyki wyższej. Wyd. PG, Gdańsk, 2009.</li> <li>Żakowski W., Decewicz G.: Matematyka, cz.I. WNT, Warszawa, 1995.</li> </ol>				
	eResources addresses Adresy na platformie eNauczanie:					
Example issues/ example questions/ tasks being completed	<ol> <li>Using the rules of differentiation find the derivative of the following function f(x)= .</li> <li>Find local extremes and intervals of monotonicity of the following function f(x)= .</li> <li>Determine indefinite integrals of the following functions using methods of integration by parts or by substitution.</li> <li>Give three applications of the definite integral with appropriate rules.</li> <li>Find the area between the two curves y= and y= from x= to x=</li> </ol>					
Work placement	Not applicable					