

Subject card

Subject name and code	Computer Control Systems, PG_00038129							
Field of study	Automation, Robotics and Control Systems							
Date of commencement of studies	October 2024		Academic year of realisation of subject			2026/2027		
Education level	first-cycle studies		Subject group			Optional subject group Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery			at the university		
Year of study	3		Language of instruction			Polish		
Semester of study	6		ECTS credits			5.0		
Learning profile	general academic profile		Assessment form			exam		
Conducting unit	Faculty of Electrical and Control Engineering							
Name and surname	Subject supervisor		dr inż. Jarosław Tarnawski					
of lecturer (lecturers)	Teachers							
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM
	Number of study hours	30.0	0.0	30.0	0.0		0.0	60
	E-learning hours inclu	ıded: 0.0						i
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study		SUM
	Number of study hours	60		8.0		57.0		125
Subject objectives	Presentation of centralized and distributed / decentralized control structures. The introduction of advanced adaptive, predictive control methods. Acquainted with the infrastructure of computer control systems - DCS and SCADA / PLC systems. The integration of knowledge from different fields to the needs of a computer control system synthesis. Introduction to methods of decision support - multi-purpose and multi-attribute-approach.							
Learning outcomes	Course outcome		Subject outcome			Method of verification		
	[K6_U07] can build and analyze models of systems and systems in the field related to control systems and automation		The student is able to build an advanced computer-controlled control system			[SU5] Assessment of ability to present the results of task		
	[K6_K02] can work in a group taking on different roles in it		The student during laboratory classes on the synthesis of advanced control system performs tasks in groups by changing roles within the team.			[SK2] Assessment of progress of work		
	[K6_W07] has basic knowledge related to control and automation systems		The student is able to define the role of all necessary elements and build a control system			[SW1] Assessment of factual knowledge		
Subject contents	Control systems structures: classical, centralized, multilayer, decentralized, distributed. Implementation of centralized/decentralized with/without data exchange with communication aspects (time relationships, data loss, stability). Multilayer and distributed control systems based on real large scale systems: drinking water distribution systems, sewer system, oil refinery. Requirements for computer controlled systems. Information structure of CCS. Software and hardware selection for practical implementation of CCS. Implementation of selected complex control algorithms in computer-like devices: microcontrollers, PLCs, PACs and industrial computers. SCADA system realization—supervisory control with coordination among all control layers. Process data acquisition and archivisation. Realization of optimization layer. Solver selection for optimization purposes.							

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Prerequisites	Finished courses:								
and co-requisites									
	- Dynamic Systems								
	- Real Time Systems								
	- Programmable Logic Controllers								
	Industrial Communication Naturalys								
	- Industrial Communication Networks								
A			1						
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade						
and Citteria	Practical exercise	50.0%	30.0%						
	Midterm colloquium	50.0%	30.0%						
	Written exam	50.0%	40.0%						
Recommended reading	Basic literature	Korbicz J., Kościelny J., Modelowanie, diagnostyka i sterowanie							
		nadrzędne procesami Implementacja w systemie DiaSter, WNT, 2009							
		Tatjewski P. Sterowanie zaawanso	tjewski P. Sterowanie zaawansowane obiektów przemysłowych,						
		Akademicka Oficyna Wydawnicza EXIT, 2002							
		Grega W. Metody i algorytmy sterowania cyfrowego w układach							
		scentralizowanych i rozproszonych, Wydawnictwo AGH, 2004							
	Niederliński A. Systemy komputerowe automatyki przemysłowe								
		1, Sprzęt i oprogramowanie, WNT, 1984.							
		Niederliński A. Systemy komputerowe automatyki przemysłowej, tom 2, Zastosowania, WNT, 1985.							
	Supplementary literature	Trybus L. Regulatory wielofunkcyjne, WNT, 1992							
		Astrom K., Wittenmark B., Computer-Controlled Systems: Theory and Design (3rd Edition), Prentice Hall, 1996							
	eResources addresses	Adresy na platformie eNauczanie:							
Example issues/		1,							
example questions/									
tasks being completed									
ě i	What are the differences between centralized and distributed control systemOutline the main features and								
	benefits of predictive controlEnter the difference between direct and indirect adaptive controlIntroduce hierarchicynego structure of the control system and specify the tasks of each layerWhat is the method of AHP?What are the principles of the design of the control system								
Monte placement	Not applicable								
Work placement	тчог аррисаріе								

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