



Subject card

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|---|---|--|------------------------------|-------------------------------------|------------------------|------------|-----|
| Subject name and code | Work placement, PG_00055406 | | | | | | |
| Field of study | Mechanical Engineering | | | | | | |
| Date of commencement of studies | October 2024 | Academic year of realisation of subject | | | 2027/2028 | | |
| Education level | first-cycle studies | Subject group | | | Optional subject group | | |
| Mode of study | Full-time studies | Mode of delivery | | | at the university | | |
| Year of study | 4 | Language of instruction | | | Polish | | |
| Semester of study | 7 | ECTS credits | | | 6.0 | | |
| Learning profile | general academic profile | Assessment form | | | assessment | | |
| Conducting unit | Institute of Mechanics and Machine Design -> Faculty of Mechanical Engineering and Ship Technology | | | | | | |
| Name and surname of lecturer (lecturers) | Subject supervisor | | dr hab. inż. Mirosław Gerigk | | | | |
| | Teachers | | | | | | |
| Lesson types and methods of instruction | Lesson type | Lecture | Tutorial | Laboratory | Project | Seminar | SUM |
| | Number of study hours | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0 |
| | E-learning hours included: 0.0 | | | | | | |
| Learning activity and number of study hours | Learning activity | Participation in didactic classes included in study plan | | Participation in consultation hours | | Self-study | SUM |
| | Number of study hours | 0 | | 4.0 | | 146.0 | 150 |
| Subject objectives | The aim of the lectures is to present to the students the basic technologies, research, design, construction and operation of the main technical objects particularly the unmanned objects. | | | | | | |

| Learning outcomes | Course outcome | Subject outcome | Method of verification |
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| | <p>[K6_K01] is aware of the need for complementing the knowledge throughout the whole life, is able to select proper methods of teaching and learning, critically assesses the possessed knowledge; is aware of the importance of professional conduct and following the rules of professional ethics; is able to show resourcefulness and innovation in the realisation of professional projects</p> | <p>A student has the basic knowledge on the life cycle of the unmanned vehicles including their mechatronic subsystems. A student has the basic knowledge on the structure, strength and motion of the unmanned vehicles. A student knows that it is necessary to update the knowledge and all the difficulties and tasks tries to overcome according to the scientific methodologies, professionally and ethic.</p> | <p>[SK2] Assessment of progress of work [SK1] Assessment of group work skills [SK5] Assessment of ability to solve problems that arise in practice [SK4] Assessment of communication skills, including language correctness [SK3] Assessment of ability to organize work</p> |
| | <p>[K6_U08] is able to design a technological manufacturing process for typical elements of machines or devices, using analytical and numerical calculating tools</p> | <p>A student is able to choose and use the tools including the methods, models and algorithms to perform the analysis concerning the implemented subsystems of the unmanned vehicles according to the operational criteria. A student is able to select the tools to analyze the strength of structure and mechanics of motion of the unmanned vehicles. A student is able to plan and perform the technological process.</p> | <p>[SU5] Assessment of ability to present the results of task [SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject [SU2] Assessment of ability to analyse information [SU1] Assessment of task fulfilment</p> |
| | <p>[K6_U03] is able to identify, formulate and develop the documentation of a simple design or technological task, including the description of the results of this task in Polish or in a foreign language and to present the results using computer software or other aiding tools</p> | <p>A student has an ability to analyze the basic technologies necessary to design and manufacture the elements and simple mechatronic subsystems for the data unmanned vehicle. A student has the basic abilities to analyze the structure, strength and motion of unamnned vehicles. A student is able to work out the project documentation and show the presentation.</p> | <p>[SU5] Assessment of ability to present the results of task [SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject [SU2] Assessment of ability to analyse information [SU1] Assessment of task fulfilment</p> |
| | <p>[K6_U05] is able to plant an experiment within the range of measuring the basic operating parameters of mechanical devices using a specialized equipment, interpret the results and reach the correct conclusions</p> | <p>A student is able to identify and formulate the simple tasks, concerning the structure, strength and mechanics of motion, and associated with implementations concerning the unmanned vehicles which are closely connected with mechatronics. A student is able to plan and perform the experiment including the set up the measuring system, conducting the experiment and analyzing the results.</p> | <p>[SU5] Assessment of ability to present the results of task [SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject [SU2] Assessment of ability to analyse information [SU1] Assessment of task fulfilment</p> |

| Subject contents | <p>The lectures concern, in turn the key technologies associated with the technics development:</p> <ul style="list-style-type: none"> - autonomous systems - sensors and effectors - materials (AI materials, nano-materials) - energy supply - innovative propulsion - IT technologies (communication, navigation, steering) - stealth - cosmic and satellite technologies and - others <p>During the lectures the following problems and design keydrivers should be discussed:</p> <ol style="list-style-type: none"> 1 hull form arrangement of internal spaces, distribution of masses, payload; 2 energy supply system; 3 propulsion system; 4 steering, communication, navigation system; 5 sensors and effectors; 6 dedicated system <p>but most the following:</p> <ul style="list-style-type: none"> - mechanics of motion and - strength of structure. | | | | | | |
|--|---|-------------------------------|-------------------|-------------------------------|--------------------------|-------|--------|
| Prerequisites and co-requisites | <p>The student should have basic information in the field of applied physics and mathematics, mathematical analysis, numerical methods, mechanics, including kinetics and dynamics, strength of structure, mechatronics and basics of programming.</p> | | | | | | |
| Assessment methods and criteria | <table border="1"> <thead> <tr> <th data-bbox="453 1917 794 1951">Subject passing criteria</th> <th data-bbox="799 1917 1141 1951">Passing threshold</th> <th data-bbox="1145 1917 1485 1951">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="453 1957 794 1989">Half-exam and final exam</td> <td data-bbox="799 1957 1141 1989">56.0%</td> <td data-bbox="1145 1957 1485 1989">100.0%</td> </tr> </tbody> </table> | Subject passing criteria | Passing threshold | Percentage of the final grade | Half-exam and final exam | 56.0% | 100.0% |
| Subject passing criteria | Passing threshold | Percentage of the final grade | | | | | |
| Half-exam and final exam | 56.0% | 100.0% | | | | | |

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| Recommended reading | Basic literature | <p>Brzezina J. M. Atak dronów. Wojskowy Instytut Wydawniczy, Warszawa 2013.</p> <p>Cwojdzński L. Bezzałogowe Systemy Walki - charakterystyka, wybrane problemy użycia i eksploatacji. Wojskowa Akademia Techniczna, Warszawa 2014.</p> <p>Dougherty M.J. Drony - ilustrowany przewodnik po bezzałogowych pojazdach powietrznych i podwodnych (Drones. An illustrated Guide to the Unmanned Aircraft That Filling Our Skies). Wydawnictwo BELLONAS.A., © 2015 Amber Books Ltd.</p> <p>Gerigk M.K. Modeling of performance and safety of a multi-task unmanned autonomous maritime vehicles (in Polish: Modelowanie ruchu i bezpieczeństwa wielozadaniowego bezzałogowego autonomicznego pojazdu wodnego). Journal of KONBIN, Safety and Reliability Systems, No. 1 (33), Warsaw 2015.</p> <p>Gerigk M.K., Wójtowicz S. An Integrated Model of Motion, Steering, Positioning and Stabilization of an Unmanned Autonomous Maritime Vehicle. TRANSNV the International Journal on Marine Navigation and Safety of Sea Transportation. Volume 9, Number 4, December 2015, DOI: 10.12716/1001.09.04.18.</p> <p>Gerigk M.K. Challenges associated with the design of a small unmanned autonomous maritime vehicle. Scientific Journals of the Maritime University of Szczecin, No. 46 (118) 2016, DOI: 10.17402/113, Published: 27.06.2016.</p> <p>Gerigk M.K. Modeling of combined phenomena affecting an AUV stealth vehicle. TRANSNV the International Journal on Marine Navigation and Safety of Sea Transportation, Vol. 10, No. 4, December 2016, DOI: 10.12716/1001.10.04.18.</p> <p>Gerigk M.K. Modeling of performance of a AUV vehicle towards limiting the hydro-acoustic field. TRANSNV the International Journal on Marine Navigation and Safety of Sea Transportation, Volume 12, Number 4, December 2018, DOI: 10.12716/1001.12.04.06.</p> <p>Gerigk M.K. Modeling of performance of an AUV stealth vehicle. Design for operation. Proceedings of IMAM 2017, 17th International Congress of the International Maritime Association of the Mediterranean, Lisbon, Portugal, 9-11 October 2017. Volume 1, @ 2018 Taylor & Francis Group, London. A Balkema Book, ISBN 978-0-8153-7993-5, pp. 365-369.</p> <p>Kalicka R. Podstawy automatyki i robotyki. Wydawnictwo Politechniki Gdańskiej, Gdańsk 2016.</p> <p>Ty Audronis. Drony- wprowadzenie, Technologia i rozwiązania (Building Multicopter Video Drones). Wydawnictwo HELION, © 2015 Helion S.A.</p> <p>Additional:</p> <ol style="list-style-type: none"> 1. Bąk R., Burczyński T.: Wytrzymałość materiałów z elementami ujęcia komputerowego. WNT, Warszawa 2013. 2. Bilewicz E. Wytrzymałość Materiałów. Wydawnictwo Politechniki Gdańskiej, Gdańsk 2013. 3, Case J., Chilver L., Ross C.T.F. Strength of materials and structures. Butterworth-Heinemann, ISBN 978-0-340-71920-6, https://doi.org/10.1016/B978-0-340-71920-6.X5000-6, Copyright ©1999 Elsevier Ltd. |
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| | | <p>All rights reserved.</p> <p>4. Dyląg Z., Jakubowicz A., Orłowski Z.: Wytrzymałość materiałów. WNT, Warszawa, t. I 1996, t. II 1997.</p> <p>5. Faltinsen O.M. Sea Loads on Ships and Offshore Structures. © Cambridge University Press 1990.</p> <p>6. Kaliński K. J.: Nadzorowanie procesów dynamicznych w układach mechanicznych. Gdańsk: Wydaw. PG 2012.</p> <p>7. Misiak J.: Mechanika techniczna. Statyka i wytrzymałość materiałów. WNT, Warszawa 1996.</p> |
| | Supplementary literature | <p>1. Gerigk M.K. Badania interdyscyplinarne i rozwój zaawansowanych technologii w projektowaniu innowacyjnych platform i obiektów pływających. PISMO PG, Politechnika Gdańska, Nr 2 (209) Rok XXIII, Luty 2016.</p> <p>2. Gerigk M.K. Technologie stealth w projektowaniu innowacyjnych obiektów pływających. PISMO PG, Politechnika Gdańska, Nr 4 (211) Rok XXIII, Kwiecień 2016.</p> <p>3. Gerigk M.K. Konstrukcje bliskiej przyszłości. "PREZENTUJ BRONĀ", 14th BALT-MILITARY-EXPO Baltic Military Fair, Gdańsk, June 20-22, 2016.</p> <p>4. Gerigk M.K. Pływające konstrukcje bliskiej przyszłości - badanie, projektowanie, budowa i wdrożenie (prezentacja, promocja projektu). II Forum Bezpieczeństwa Morskiego Państwa, Ministerstwo Obrony Narodowej, Akademia Marynarki Wojennej, Warszawa, 19 stycznia 2017 r.</p> <p>5. Gerigk M.K. Proponowane innowacyjne obiekty i systemy walki podwodnej opracowywane na Wydziale Mechanicznym i Politechnice Gdańskiej - (prezentacja, promocja projektu). Seminarium zamknięte, Wydział Mechaniczny PG, Gdańsk, 16 listopada 2017 r.</p> |
| | eResources addresses | Adresy na platformie eNauczenie: |

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| <p>Example issues/ example questions/ tasks being completed</p> | <p>Q No. 1 (no more than 1 A4 page):</p> <p>For the data object please describe the basic set of forces (loads) in operation:</p> <ul style="list-style-type: none"> - external forces (external loads) - internal forces (internal loads) <p>Q No. 2 (no more than 2 A4 pages):</p> <p>For the selected object please give the basic information (mathematical modelling) on the vehicle's motion:</p> <ul style="list-style-type: none"> - degrees of freedom, - phenomena, - hydrodynamic coefficients, forces, etc. - equations of motion, - states of equilibrium, - steering and control. <p>Q No. 3 (no more than 1 A4 page):</p> <p>For the data object please describe:</p> <ul style="list-style-type: none"> - design requirements (parameters, characteristics) and operational requirements, - assessment of performance, including the assessment of performance and safe operation, - system engineering including the tests, - operational requirements. <p>Q No. 4 (no more than 1 A4 page):</p> <ul style="list-style-type: none"> - key technologies for technology development - any new technologies coming. |
| <p>Work placement</p> | <p>Not applicable</p> |