GDAŃSK UNIVERSITY OF TECHNOLOGY

Subject card

Subject name and code	Mechanics, PG_00060473		
Field of study	Mechatronics		
Date of commencement of studies	October 2024	Academic year of realisation of subject	2024/2025
Education level	first-cycle studies	Subject group	Obligatory subject group in the field of study Subject group related to scientific research in the field of study
Mode of study	Full-time studies	Mode of delivery	at the university
Year of study	1	Language of instruction	Polish
Semester of study	2	ECTS credits	7.0
Learning profile	general academic profile	Assessment form	exam
Conducting unit	Department of Mechanics and Mechatronics -> Faculty of Mechanical Engineering and Ship Technology		
Name and surname of lecturer (lecturers)	Subject supervisor	prof. dr hab. inż. Marek Krawczuk	
	Teachers	Michał Formela mgr inż. Grzegorz Banaszek mgr inż. Kornel Piłat prof. dr hab. inż. Marek Krawczuk	

Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	45.0	30.0	15.0	0.0	0.0	90
	E-learning hours included: 0.0						

Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan	Participation in consultation hours	Self-study	SUM
	Number of study hours	90	11.0	74.0	175

Subject objectives	Theoretical and exercises in technical mechanics

Learning outcomes

Course outcome	Subject outcome	Method of verification
[K6_U01] is able to acquire information from literature, databases and other, properly chosen sources, integrate these information, interpret them, draw conclusions and formulate opinions	Has the ability to self-educate	[SU1] Assessment of task fulfilment
[K6_W04] has organized and theoretically supported, advanced knowledge in the field of general mechanics, strength of materials, theory of mechanisms and machine dynamics, fluid dynamics, hydraulics and pneumatics, machine construction and engineering graphics	Has knowledge of solid mechanics	[SW1] Assessment of factual knowledge
[K6_W02] has a knowledge in term of physics that includes mechanics, thermodynamics, optics, electricity, magnetism, atomic physics, nuclear physic, solid state physics, including the knowledge necessary to understand basic phenomena occurring in mechatronic elements and systems and its surroundings	Understands the basic laws of statics, kinematics and dynamics	[SW1] Assessment of factual knowledge
[K6_U03] has self-learning skills	Is able to acquire knowledge independently	[SU3] Assessment of ability to use knowledge gained from the subject

Subject contents	**Lectures/Tutorials** Modeling in mechanics: real system, physical and mathematical models, and also meanings of: ideal rigid body, dimension-less point, concentrated force. The basic Newtons principles, and primitive notions and axioms of mechanics. Equilibrant systems of forces. Resultant force of concurrent system of forces. Momentum of pair of forces. Resultant force and resultant momentum of spatial system of forces. Degrees of freedom, strains and their reaction forces. Statically determinate and in determinate systems. Conditions of equilibrium of system of forces, and particular systems: coplanar, concurrent, and parallel. Substitute conditions of equilibrium. Formulas of superposition, and independence of force acting. Forces, and their sources. Division of forces: reactive and active, external and internal. Gravity force and coordinates of centre of gravity. Friction forces, rolling resistance and belt drive friction. Analysis of forces in bars of truss. Basic meanings in kinematics of point: position coordinates, velocity, acceleration, and equations of motion. Description of motion of point in: vector, Cartesian, normal, and polar coordinates. Analysis of kinematics parameters of particular systems: linear track motion, circle and ellipse track motion, uniform and uniformly accelerated motion, harmonic motion, crank-shaft system motion. Kinematics of the rigid body. Basic definitions: angular coordinates, velocities and accelerations of the body, and linear velocity and acceleration of the point of the body. Dependency in-between velocities and accelerations of points of the body. Particular cases of the rigid body kinematics: transitional, rotational and coplanar motion. Description of coplanar motion as transitional and rotational motion superposition, and as rotational motion around contemporary center of velocity and center of acceleration. Analysis of kinematics parameters of planar and planetary toothed transmit boxes. Relative motion and Coriolis acceleration. Dynamics of inertial point in: Cartesian, polar, and normal coordinates. Particular cases of dynamics of point motion of: linear track motion, oblique projection motion, free motion in gravity field including resistance forces, harmonic motion, mathematical pendulum. Dynamics of the inertial points system. Dynamic analysis of the inertial point using principles of mechanics: dAlembert, conservation of energy, conservation of momentum and impulse, conservation of moment of momentum. Inertia parameters of the rigid body: mass, coordinates of centre of mass, mass moments of inertia. Parameters of the principal moments of inertia and principal axes of inertia of the body. Differential equation of motion and dynamic principles in analysis of transitional, rotational and coplanar motion of the body. The dAlembert principle in calculation of bearings reaction forces of rotor, and to balance it dynamically. Gyroscopes effect. Analysis of strait and diagonal central collision, and calculation of the centre of percussion. Basis principles of analytical mechanics in analysis of dynamics of inertial points and bodies systems. Virtual displacement. Principle of virtual work. Generalized coordinates and forces. The Lagrange equation of the second kind.
Prerequisites and co-requisites	Phisics and mathematics on the secondary level school, including in particular: geometry, thrigonometry, and also vector calculus.

Assessment methods and criteria

Subject passing criteria	Passing threshold	Percentage of the final grade
Practical exercise	56.0%	40.0%
Written exam	56.0%	40.0%
Laboratory	56.0%	20.0%

Recommended reading

Basic literature	Wittbrodt E., Sawiak S.: General Mechanics. Theory and exercises. Published by GUT 2020 (in Polish)
Supplementary literature	Osiński Z.: Mechanika ogólna. T. I i 2, PWN, Warszawa 1987 Nizioł J.: Metodyka rozwiązywania zadań z mechaniki. WNT, Warszawa 2002 Sawiak S., Wittbrodt E.: Mechanika. Wybrane zagadnienia. Teoria i zadania. Wyd. PG, Gdańsk 2007
eResources addresses	Adresy na platformie eNauczanie: Mechanika (PG_00060473) Mechatronika I stopnia, sem.2, lato 2024/2 5 - Moodle ID: 42908 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=42908 Mechanika, Ć, MTR, I st., sem. 02, letni 23/24, (PG_00060473) - Moodle ID: 44037 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=44037 Mechanika, L, Mechatronika, sem.02, letni 24/25, stacjonarne (PG_00060473) - Moodle ID: 45551 https://enauczanie.pg.edu.pl/moodle/course/view.php?id=45551

Example issues/ example questions/ tasks being completed	Principles of static Kinematics of plane motion Dynamics of a material point in polar coordinates
Work placement	Not applicable

Document generated electronically. Does not require a seal or signature.