

## Subject card

	Description and Hardward to the Astronomy Co. 1.1. I.D. 1.5. DO 00017001								
	Pneumatics and Hydraulics in Automatic Control and Robotics, PG_00047601								
r rera er eraay	Automatic Control, Cybernetics and Robotics								
Date of commencement of studies	October 2024		Academic year of realisation of subject			2026/2027			
Education level	first-cycle studies		Subject group		Optional subject group Subject group related to scientific research in the field of study				
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	5		ECTS credits			4.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Mechanics and Mechatronics -> Faculty of Mechanical Engineering and Ship Technolog						echnology		
Name and surname	Subject supervisor	Subject supervisor dr hab. inż. Ryszard Jasiński							
of lecturer (lecturers)	Teachers		dr hab. inż. Ryszard Jasiński						
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
of instruction	Number of study hours	15.0	0.0	30.0	30.0 0.0		0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in classes include plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	45	4.0			51.0		100	
	electrohydraulic, pneumatic, electropneumatic control used in automation and robotics. Student sele basic components to hydraulic, electrohydraulic, pneumatic, electropneumatic drive and control syste Student builds basic hydraulic, pneumatic systems. Student takes measurements. Student analyzes of measurements.						l systems.		
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_U06] can analyse the operation of components, circuits and systems related to the field of study, measure their parameters and examine technical specifications		Student selects the basic elements for hydraulic, electrohydraulic, pneumatic and electropneumatic drive and control systems. Student builds basic hydraulic and pneumatic systems. Student takes measurements. Student analyzes the results of the measurements.			[SU2] Assessment of ability to analyse information [SU1] Assessment of task fulfilment			
	[K6_W02] knows and understands, to an advanced extent, selected laws of physics and physical phenomena as well as methods and theories explaining the complex relationships between them, constituting the basic general knowledge in the field of technical sciences related to the field of study		Student knows and understands at an advanced level selected physical laws and phenomena as well as methods and theories explaining the operation of hydraulic, electrohydraulic, pneumatic and electropneumatic elements and systems of drive and control systems used in automation and robotics.			[SW1] Assessment of factual knowledge			
	[K6_W03] knows and understands, to an advanced extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum		Student describes the structure and principle of operation of hydraulic, electrohydraulic, pneumatic and electropneumatic elements and systems of drive and control systems used in automation and robotics.			[SW1] Assessment of factual knowledge			

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Subject contents	Lecture: General information about pneumatic and hydraulic drives. Hydrostatics. Fluid dynamics. Flow equations. Development and applications of pneumatic systems in modern technology. Development and applications of hydraulic systems in modern technology. Basic elements and units of hydraulic drive and control. Applications of electrohydraulics and electronics in hydraulic drive and control systems. Generation of compressed air. Modern control systems of compressors. Basic pneumatic elements and basic pneumatic drive and control systems. Units of compressed air preparation. Elements and units converting energy of compressed air into mechanical energy. Elements controlling air flow and pressure. Comparison of pneumatic switching devices with electric and electronic devices. 6. Basic systems of pneumatic drive and control. Automation of pneumatic systems cycle. Measurements and control in laboratory of hydraulics and pneumatics. Automation of technologic and transport systems by applying pneumatics and hydraulics. Positioning of pneumatic and hydraulic driving systems. Pneumatic cylinders and step motors. Control of pneumatic systems of sequence operation. Hydraulic control, speed stabilization. Control systems with hydraulic proportional and hydraulic servo valves. Characteristics of servo valves. Examples of applications of proportional and servo.						
Prerequisites and co-requisites							
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade				
and criteria	Midterm colloquium	56.0%	60.0%				
	Practical exercise	56.0%	40.0%				
Recommended reading	Basic literature	A. Morecki. Podstawy robotyki. M. Olszewski: Manipulatory i roboty przemysłowe  A. Osiecki: Hydrostatyczny napęd maszyn  A. Pizoń: Elementy i układy hydrauliczne w automatyce  A. Pizoń: Elektrohydrauliczne analogowe i cyfrowe układy automatyki  W. Szenajch: Napędy i sterownie pneumatyczne  W. Szenajch. Przyrządy, uchwyty i sterowanie pneumatyczne  Czasopisma: Hydraulika i Pneumatyka, Pneumatyka  J.Lipski, E.Zwolak, W.Balas: Hydrauliczne urządzenia środków transportu					
	Supplementary literature	No requirements					
	eResources addresses	Adresy na platformie eNauczanie:					
Example issues/ example questions/ tasks being completed	-						
Work placement	Not applicable						

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