



Subject card

|   |  |  |          |                                     |  |            |     |
|---|--|--|----------|-------------------------------------|--|------------|-----|
| Subject name and code                       | Production Process Planning, PG_00047704   |  |          |                                     |  |            |     |
| Field of study                              | Automatic Control, Cybernetics and Robotics  |  |          |                                     |  |            |     |
| Date of commencement of studies             | October 2024   | Academic year of realisation of subject                  |          |                                     | 2027/2028  |            |     |
| Education level                             | first-cycle studies  | Subject group  |          |                                     | Optional subject group<br>Subject group related to scientific research in the field of study |            |     |
| Mode of study                               | Full-time studies  | Mode of delivery   |          |                                     | at the university  |            |     |
| Year of study                               | 4  | Language of instruction                                  |          |                                     | Polish   |            |     |
| Semester of study                           | 7  | ECTS credits   |          |                                     | 4.0  |            |     |
| Learning profile                            | general academic profile   | Assessment form  |          |                                     | exam   |            |     |
| Conducting unit                             | Department of Decision Systems and Robotics -> Faculty of Electronics, Telecommunications and Informatics  |  |          |                                     |  |            |     |
| Name and surname of lecturer (lecturers)    | Subject supervisor   | dr inż. Krystyna Rudzińska-Kormańska                     |          |                                     |  |            |     |
|   | Teachers   |  |          |                                     |  |            |     |
| Lesson types and methods of instruction     | Lesson type  | Lecture  | Tutorial | Laboratory                          | Project  | Seminar    | SUM |
|   | Number of study hours  | 30.0   | 15.0     | 0.0                                 | 0.0  | 0.0        | 45  |
|   | E-learning hours included: 0.0   |  |          |                                     |  |            |     |
| Learning activity and number of study hours | Learning activity  | Participation in didactic classes included in study plan |          | Participation in consultation hours |  | Self-study | SUM |
|   | Number of study hours  | 45   |          | 4.0                                 |  | 51.0       | 100 |
| Subject objectives                          | Learning methods of production planning, transportation and management in flexible manufacturing systems. The acquisition of skills in operations research algorithms production planning. |  |          |                                     |  |            |     |

|   |  |   |   |
|---|--|---|---|
| Learning outcomes   | Course outcome   | Subject outcome   | Method of verification  |
|   | [K6_U01] can apply mathematical knowledge to formulate and solve complex and non-typical problems related to the field of study and perform tasks, in an innovative way, in not entirely predictable conditions, by:n- appropriate selection of sources and information obtained from them, assessment, critical analysis and synthesis of this information,n- selection and application of appropriate methods and toolsn   | Uses numerical methods in solving engineering tasks.  | [SU4] Assessment of ability to use methods and tools  |
|   | [K6_U03] can design, according to required specifications, and make a simple device, facility, system or carry out a process, specific to the field of study, using suitable methods, techniques, tools and materials, following engineering standards and norms, applying technologies specific to the field of study and experience gained in the professional engineering environment   | Creates navigation algorithms for mobile robots; creates a decision support system.                   | [SU4] Assessment of ability to use methods and tools<br>[SU1] Assessment of task fulfilment |
|   | [K6_W03] knows and understands, to an advanced extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum   | He knows the methods of production planning, transport and management in flexible production systems. | [SW1] Assessment of factual knowledge   |
| [K6_W01] knows and understands, to an advanced extent, mathematics necessary to formulate and solve simple issues related to the field of study | Has knowledge in the field of operational research.  | [SW1] Assessment of factual knowledge   |   |
| Subject contents  | <ol style="list-style-type: none"> <li>1. Introduction. Basic definitions. Examples of production processes.</li> <li>2. Computer Integrated Manufacturing (CIM system). Flexible Manufacturing Systems (FMS) – a structural approach.</li> <li>3. Architecture of FMS and control systems.</li> <li>4. Hierarchical planning methods (strategical, tactical and operational planning).</li> <li>5. Classification of scheduling problems. Sequencing tasks for different FMS structures. Serial and parallel processes.</li> <li>6. Job sequencing for a production line.</li> <li>7. Time criteria in one machine scheduling. SPT, EDD and Smith's rules.</li> <li>8. Johnson's algorithm for the two- and three machines job-shop.</li> <li>9. Graph data representation in operation research. Construction of operation precedence.</li> <li>10. Minimum tardiness problems with precedence constraints. Lawler's technique.</li> <li>11. Sequencing problems in FSM with parallel machines.</li> <li>12. Zero-one variable programming. Problems:</li> <li>13. <ul style="list-style-type: none"> <li>- optimal job assignment to parallel processors;</li> <li>- optimal allocation of multiple resources.</li> </ul> </li> <li>14. Balanced and unbalanced assignment problems. Hungarian algorithm.</li> <li>15. Network models in production planning.</li> <li>16. Technological path determination for production lines with parallel machines.</li> <li>17. Optimization of FMS – transport system. Free-collision path finding for automated vehicles (AGV, MP).</li> <li>18. Application of visibility graph and Dijkstra's algorithm for determining the collision-free trajectory of the AGV with a minimum travel time</li> <li>19. Strategic production planning by using Linear Programming.</li> <li>20. Matrix forms of Linear Programming (LP). Simplex algorithm.</li> <li>21. Starting basic solution. LP – optimal solutions (single, alternative degenerated).</li> <li>22. Inventory and transportation problems.</li> <li>23. Transportation algorithm (TA) for balanced problems.</li> </ol> |   |   |
| Prerequisites and co-requisites   |  |   |   |
| Assessment methods and criteria   | Subject passing criteria   | Passing threshold   | Percentage of the final grade   |
|   | two tests (40+40 points), activity (20 points)   | 50.0%   | 100.0%  |

|  |                          |  |
|--|--------------------------|--|
| Recommended reading  | Basic literature         | <ol style="list-style-type: none"> <li>1. T. Sawik, "Optymalizacja dyskretna w elastycznych systemach produkcyjnych".</li> <li>2. H.A. Taho, "Operations Research".</li> <li>3.</li> </ol> |
|  | Supplementary literature | <ol style="list-style-type: none"> <li>1. K. Santarek, S. Strzelczak, "Elastyczne Systemy Produkcyjne".</li> <li>2. W. Grabowski, "Programowanie matematyczne".</li> <li>3.</li> </ol>     |
|  | eResources addresses     | Adresy na platformie eNauczenie:   |
| Example issues/<br>example questions/<br>tasks being completed |                          |  |
| Work placement   | Not applicable           |  |