

GDAŃSK UNIVERSITY

Subject card

Subject name and code	Concurrent programming and real time systems, PG_00064786								
Field of study	Mechatronics								
Date of commencement of studies	February 2025		Academic year of realisation of subject			2024/	2024/2025		
Education level	second-cycle studies		Subject group			Obligatory subject group in the field of study			
						Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	1		Language of instruction			Polish			
Semester of study	1		ECTS credits			3.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department of Marine	Department of Marine Electronic Systems -> Faculty of Electronics, Telecommunications and Informatics							
Name and surname	Subject supervisor		dr hab. inż. Iwona Kochańska						
of lecturer (lecturers)	Teachers								
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
of instruction	Number of study hours	30.0	0.0	0.0	15.0		0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in classes includ		Participation in consultation hours		Self-study		SUM	
	Number of study hours	45		8.0		22.0		75	
	and issues related to the mechanisms of re computers of industria	source sharing	in real-time sy	stems the spe	cificity c				
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K7_U13] evaluates the feasibility and potential for utilizing new technical and technological achievements in accomplishing tasks characteristic for the field of study		The student knows the techniques of concurrent programming of embedded systems working with different operating systems, especially real-time systems.			[SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject			
	[K7_W04] demonstrates knowledge encompassing selected issues in the field of detailed knowledge, particularly in the scope of methods, techniques, tools, and algorithms specific to Mechatronics		The student knows the basic architectures of embedded systems, especially multiprocessor systems, and understands the basic problems associated with the software of such systems and ways to solve them.			[SW1] Assessment of factual knowledge			
			multithreaded real-time systems			[SU1] Assessment of task fulfilment [SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject			
	[K7_K11] is aware of importance of professional acting, the need for critical verification of acquired knowledge and consulting experts opinion in case of facing difficulties with individual problem solving		The student knows the standards of programming real-time systems and understands the need to comply with them.			[SK5] Assessment of ability to solve problems that arise in practice			

Subject contents	 Review of real-time operating systems Concepts and elements of real-time systems Kernel and its environment in RT operating systems Process manager, resource manager, namespace management Memory management in RT systems. Processes and threads. Thread scheduling in RT systems. Thread synchronization methods in RT systems. Implementation of thread and process support in POSIX standard Implementation of thread support in the C ++ 11 language standard Basic problems of concurrent programming and ways of solving them 						
Prerequisites and co-requisites	Basics of programming in C or C ++						
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade				
and criteria		50.0%	50.0%				
		50.0%	50.0%				
Recommended reading	 Basic literature M. Ben-Ari, Principles of Concurrent and Distributed Programmi Addison Wessley, 2005 Andrew S. Tanenbaum, Herbert Bos, Modern Operating System (4th Edition), Pearson Prentice Hall, 2016 						
	Supplementary literature	 R. Love, Linux system programming", O'Reilly Media, 2013 J. Corbet, A. Rubini, G. Kroah-Hartman, Linux Device Drivers, Third Edition, OReilly 					
	eResources addresses	ses Adresy na platformie eNauczanie:					
Example issues/ example questions/ tasks being completed	Describe rigorous real-time systems. Describe the classical architecture of a real-time system. Advantages and disadvantages of a microkernel operating system architecture. What is priority inversion? Explain the race condition. Describe fork() and wait() functions in Linux. Describe the basic mechanisms for synchronizing threads in a concurrent program. Describe the basic problems of concurrent programming.						
Work placement	Not applicable						

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