

Subject card

Subject name and code	Identification methods in mechatronics, PG_00064796								
Field of study	Mechatronics								
Date of commencement of studies	February 2025		Academic year of realisation of subject			2025/2026			
Education level	second-cycle studies		Subject group			Specialty subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	1		Language of instruction			Polish			
Semester of study	2		ECTS credits			2.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Institute of Mechanics and Machine Design -> Faculty of Mechanical Engineering and Ship Technology					hnology			
Name and surname	Subject supervisor		dr inż. Michał Mazur						
of lecturer (lecturers)	Teachers								
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
of instruction	Number of study hours	15.0	0.0	0.0	15.0		0.0	30	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in classes include plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	30		4.0		16.0		50	
Subject objectives	Overview of stages a	nd selected me	thods of identi	fication, model	correla	tion, mo	odal updating.		
Learning outcomes	Course out	come	Subject outcome			Method of verification			
	[K7_U13] evaluates the feasibility and potential for utilizing new technical and technological achievements in accomplishing tasks characteristic for the field of study		Assesses the usefulness and possibility of using identification methods.			[SU4] Assessment of ability to use methods and tools [SU5] Assessment of ability to present the results of task			
	[K7_W02] demonstrates structured and theory supported knowledge encompassing key issues in the field of Mechatronics, enabling modeling and analysis of stationary and non-stationary mechatronic systems, devices, and processes with continuous and discrete operation		Has expanded and deepened knowledge of certain branches of mechatronics including elements of discrete mathematics and applied and optimization methods, including mathematical and numerical methods necessary for identification			[SW1] Assessment of factual knowledge [SW2] Assessment of knowledge contained in presentation			
	[K7_W04] demonstrates knowledge encompassing selected issues in the field of detailed knowledge, particularly in the scope of methods, techniques, tools, and algorithms specific to Mechatronics		Has a theoretical detailed knowledge of the methods of identification and signal processing.			[SW3] Assessment of knowledge contained in written work and projects			
	[K7_U02] formulates and tests hypotheses concerning problems od stationary and non-stationary mechatronic systems/processes, as well as simple research problems		Is able to verify the stationarity of the identified system.			[SU1] Assessment of task fulfilment [SU2] Assessment of ability to analyse information [SU3] Assessment of ability to use knowledge gained from the subject			

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Subject contents	Indirectmethods of identification in Methods ofidentification of one-de identificationin the frequency dometechniques inidentification of mechanalysis. Deeplearning and optimi implement a mechatronic project individual team members. The mashapes of vibrations) of the real of the correlation of the FEM model of	in goal of the project is to identify th	f identification in the time domain. Induncy domain. Indirect methods of in the frequency domain. Coupling modification. Operational modal id models.PROJECT The students with thedivision of competences into e modalparameters (poles and scaled an FEMmodel of the real object. Then, experiment is assessed. Additional		
Prerequisites and co-requisites	level).Knowledge and experience	t level).Knowledge on Theory and to in Informatics (I-st level).Knowledge Knowledge and experience inMecha	and experience in Modelling of		
Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade		
and criteria	Projekt	50.0%	40.0%		
	Colloquium	50.0%	60.0%		
Recommended reading	1. Uhl T.: Komputerowo wspomagana identyfikacja modeli konstrukcjimechanicznych. Warszawa: WNT 1997.2. Maia N. M. M., Silva J. M. M.: Theoretical and Experimental ModalAnalysis. Taunton, Somerset (England): Research Studies Press 1997.3. Heylen W., Lammens S., Sas P.: Modal Analysis Theory and Testing. Leuven: KU Leuven 2007.				
	Supplementary literature	(Red. T. Uhl). Kraków: Kated. Ří 2006,2008.2. Lisowski W.: Wybr eksperymentalnejanalizy modalr			
	Supplementary literature eResources addresses	(Red. T. Uhl). Kraków: Kated. Ko 2006,2008.2. Lisowski W.: Wybr eksperymentalnejanalizy modaln WydawnictwaNaukowoDydaktyc	obotyki i Mechatroniki AGH 2005, ane problemy automatyzacji nej. Kraków: AGH Uczelniane izne 2006. Rozprawy Monografie 158.		
Example issues/ example questions/ tasks being completed	eResources addresses 1. The ERA method 2. pLSCFd m H2estimator 7. Spectrum leak 8. C Analysis14. Dynamic stiffness, effi ofmeasurements 18. Correctness 21.Poles Determination from the c	ethod 3. Residues 4. LSFD method DMA 9. FBS 10. CMS 11. MAC 12. Gective mass 15. Modes scaling 16. For identification 19. Stages of identification 2.	bobotyki i Mechatroniki AGH 2005, ane problemy automatyzacji nej. Kraków: AGH Uczelniane izne 2006. Rozprawy Monografie 158. de: 5. Time windows 6. H1 and CMIF 13. Assumptions of Modal Frequency aliasing 17. Correctness		
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