



Subject card

Subject name and code	Artificial Intelligence Methods, PG_00065723						
Field of study	Automation, Robotics and Control Systems						
Date of commencement of studies	February 2025	Academic year of realisation of subject				2024/2025	
Education level	second-cycle studies	Subject group					
Mode of study	Full-time studies	Mode of delivery				at the university	
Year of study	1	Language of instruction				Polish	
Semester of study	1	ECTS credits				4.0	
Learning profile	general academic profile	Assessment form				assessment	
Conducting unit	Department of Control Engineering -> Faculty of Electrical and Control Engineering						
Name and surname of lecturer (lecturers)	Subject supervisor	prof. dr hab. inż. Roman Śmierzchalski					
	Teachers	dr hab. inż. Michał Grochowski prof. dr hab. inż. Roman Śmierzchalski					
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	30.0	0.0	15.0	15.0	0.0	60
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	60		5.0		35.0	100
Subject objectives	The aim of the course is to introduce students to basic notions and concepts from the field of artificial intelligence.						
Learning outcomes	Course outcome		Subject outcome			Method of verification	
	[K7_U08] has the necessary preparation to work in an industrial environment, carry out research, apply principles of health and safety at work		The student learns the basic computational techniques of artificial Intelligence (methods of inference, learning and search for solutions) in an algorithmic approach, selects an algorithm AI to solve a specific practical technical task technical task, implements SI algorithm in a selected programming language programming language (Matlab or C++) to solve issues of decision-making processes, such as forecasting, planning, diagnostics, control, optimization.			[SU1] Assessment of task fulfilment	
	[K7_W05] has knowledge of artificial intelligence computing techniques, inference, learning and solution-finding methods in algorithmic terms applied to automation and robotics systems		The student learns the basic principles of conducting work and research in an industrial environment, application of safety and occupational health and safety.			[SW1] Assessment of factual knowledge	

Subject contents	<p>LECTURE Basic definitions of intelligence, artificial intelligences, scope of research on artificial intelligence. Tasks of artificial intelligence formal and approximate inference, information-based learning, solution space search, - overview of intelligent computing techniques. Examples of tasks solved by artificial intelligence methods. Formal inference, task formulation, syntax and semantics of the language of logic, construction of an automatic inference system. Approximate inference, fuzzy logic - representation and processing of qualitative knowledge, fuzzy sets, operations on sets, fuzzy inference, fuzzy regulator, fuzzy rule bases on numerical data. Design of fuzzy autopilot for ship heading control. Neural networks, multilayer perceptron learning, reinforcement learning - task formulation, value function, reinforcement learning as a value function approximation method 4. Solution space search methods, evaluation function, heuristic evaluation methods. Random methods - climbing and random straying algorithm, simulated annealing algorithm. 5. solution space search with genetic algorithm (AG). Scheme and operation of AG, population representation, initial population, adaptation function, genetic operators, algorithm parameters. Theoretical basis of AG. Computer implementation of classical AG. Genetic techniques. Representation and structure of populations. AG solving optimization problems. Multicriteria optimization problem in AG. Example evolutionary route planning of an autonomous robot in an environment, trajectory determination of a ship in a collision situation at sea. Hybrid methods - techniques of combining fuzzy-neural systems (fuzzy neural networks), use of genetic algorithms for parameter tuning of fuzzy and neural models.</p> <p>LABORATORY EXERCISES Fuzzy controller - evaluation of control system properties, resistance to disturbances. Synthesis of fuzzy controller - techniques of creating P, PI, PID fuzzy controller. Neural network learning test with teacher. Modeling of continuous industrial process using SN. Study of properties of genetic algorithm depending on selection method, coding method and operators used. Solving an optimization task with constraints using evolutionary method. Optimization of a robot's path in an environment using evolutionary method.</p> <p>PROJECT Design of a selected control system using artificial intelligence.</p>														
Prerequisites and co-requisites	Knowledge from the course Fundamentals of Automatics														
Assessment methods and criteria	<table border="1" data-bbox="451 904 1487 1039"> <thead> <tr> <th data-bbox="451 904 794 938">Subject passing criteria</th> <th data-bbox="794 904 1137 938">Passing threshold</th> <th data-bbox="1137 904 1487 938">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="451 938 794 972">Report on the exercises</td> <td data-bbox="794 938 1137 972">100.0%</td> <td data-bbox="1137 938 1487 972">30.0%</td> </tr> <tr> <td data-bbox="451 972 794 1005">Project documentation</td> <td data-bbox="794 972 1137 1005">100.0%</td> <td data-bbox="1137 972 1487 1005">20.0%</td> </tr> <tr> <td data-bbox="451 1005 794 1039">Colloquium</td> <td data-bbox="794 1005 1137 1039">50.0%</td> <td data-bbox="1137 1005 1487 1039">50.0%</td> </tr> </tbody> </table>			Subject passing criteria	Passing threshold	Percentage of the final grade	Report on the exercises	100.0%	30.0%	Project documentation	100.0%	20.0%	Colloquium	50.0%	50.0%
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Example issues/ example questions/ tasks being completed	<p>Artificial intelligence tasks - formal and approximate inference, information-based learning, solution space search.</p> <p>Fuzzy sets, operations on sets, fuzzy inference, fuzzy controller.</p> <p>Neural networks, multilayer perceptron learning, reinforcement learning.</p> <p>AG scheme and operation, population representation, initial population, adaptation function, genetic operators, algorithm parameters.</p>														
Work placement	Not applicable														

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