



Subject card

Subject name and code	Modern Techniques in Control Theory, PG_00064102						
Field of study	Automatic Control, Cybernetics and Robotics						
Date of commencement of studies	February 2026	Academic year of realisation of subject			2025/2026		
Education level	second-cycle studies	Subject group			Obligatory subject group in the field of study Subject group related to scientific research in the field of study		
Mode of study	Full-time studies	Mode of delivery			at the university		
Year of study	1	Language of instruction			Polish		
Semester of study	1	ECTS credits			4.0		
Learning profile	general academic profile	Assessment form			exam		
Conducting unit	Department of Automatic Control -> Faculty of Electronics Telecommunications and Informatics -> Faculties of Gdańsk University of Technology						
Name and surname of lecturer (lecturers)	Subject supervisor	dr inż. Artur Gańcza					
	Teachers	dr inż. Artur Gańcza dr inż. Piotr Fiertek mgr inż. Krzysztof Dudziak					
Lesson types	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	30.0	15.0	0.0	0.0	0.0	45
	E-learning hours included: 0.0						
	eNauczanie source addresses: Moodle ID: 4551 26LATO Nowoczesne Metody Teorii Sterowania https://enauzanie.pg.edu.pl/2025/course/view.php?id=4551						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan	Participation in consultation hours		Self-study	SUM	
	Number of study hours	45	6.0		49.0	100	
Subject objectives	Advanced control methods, in particular for MIMO plants: state-space control, robust control. Know fundamental limitations of control systems.						

Learning outcomes	Course outcome	Subject outcome	Method of verification
	[K7_U12] is able, to an increased extent, to analyze the operation of components and systems related to the field of study, as well as to measure their parameters and study their technical characteristics, and to plan and carry out experiments related to the field of study, including computer simulations, interpret the obtained results and draw conclusions	The student understands the application areas, advantages and disadvantages of different control approaches discussed in the course. The student can model dynamic system using state space equations and transfer function matrices. The student knows the concepts of MIMO zeros, decoupling zeros, poles, directions. The student can specify uncertainty.	[SU1] Assessment of task fulfilment
	[K7_U01] can apply mathematical knowledge to formulate and solve complex and non-typical problems related to the field of study by: - appropriate selection of source information and its critical analysis, synthesis, creative interpretation and presentation, - application of appropriate methods and tools	The student can implement a simulated control system that employs advanced controllers discussed during the course.	[SU4] Assessment of ability to use methods and tools [SU3] Assessment of ability to use knowledge gained from the subject [SU1] Assessment of task fulfilment
	[K7_U02] can perform tasks related to the field of study as well as formulate and solve problems applying recent knowledge of physics and other areas of science	The student can model dynamic system using state space equations and transfer function matrices. The student knows the concepts of MIMO zeros, decoupling zeros, poles, directions. The student can specify uncertainty.	[SW1] Assessment of factual knowledge
[K7_W04] knows and understands, to an increased extent, the principles, methods and techniques of programming and the principles of computer software development or programming devices or controllers using microprocessors or other elements or programmable devices specific to the field of study, and organization of work of systems using computers or such devices	The student understands basics of modeling.	[SU3] Assessment of ability to use knowledge gained from the subject	
Subject contents	<p>Course content – lecture State-space control: modeling, controllability, observability, controller and observer design separation principle.</p> <p>Optimal control: LQR/LQG controllers, properties, loop transfer recovery method.</p> <p>System norms, zeros and poles in MIMO systems, performance specification, generalized plant.</p> <p>Limitations of control systems: Bode integral, nonminimumphase zeros, unstable poles, delay, uncertainty.</p> <p>Robust control: robust stability and performance. Synthesis of robust controllers, loop shaping.</p>		
Prerequisites and co-requisites	Principles of automatic control, Analog control, Algebra, Calulus, Complex calculus.		
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	Exam	61.0%	50.0%
	Exercises	61.0%	50.0%
Recommended reading	Basic literature	W.L. Brogan, Modern Control Theory, Prentice Hall, 1990. S. Skogestad, I. Postlethwaite, Multivariable Feedback Control: Analysis and Design, Wiley, 2005.	
	Supplementary literature	N.S. Nise, Control Systems Engineering, Wiley	

	eResources addresses	
Example issues/ example questions/ tasks being completed		
Practical activities within the subject	Not applicable	

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