

## Subject card

Subject name and code	Data Processing Methods in Automation, PG_00064526								
Field of study	Automatic Control, Cybernetics and Robotics								
Date of commencement of studies	February 2026		Academic year of realisation of subject			2025/2026			
Education level	second-cycle studies		Subject group			Optional subject group Specialty subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	1		Language of instruction		Polish				
Semester of study	1		ECTS credits		2.0				
Learning profile	general academic profile		Assessmer	Assessment form		asses	assessment		
Conducting unit	Department Of Signals And Systems -> Faculty Of Electronics Telecommunications And Informatics -> Wydziały Politechniki Gdańskiej						matics ->		
Name and surname	Subject supervisor		dr inż. Kamil S	dr inż. Kamil Stawiarski					
of lecturer (lecturers)	Teachers		dr inż. Kamil	Stawiarski	iarski				
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
	Number of study hours	15.0	0.0	15.0	0.0		0.0	30	
	E-learning hours inclu	ided: 0.0							
Learning activity and number of study hours	Learning activity Participation in classes include plan			Participation in consultation hours		Self-study		SUM	
	Number of study hours	30		4.0		16.0		50	
Subject objectives	The purpose of the le practical methods used Part 1: Students will gain known and IQ modulation methods for context of signal at theory, correlation, and televity correlation and televity correlations are successful to the practical state of the	ed in signal and owledge of signathods. In lines invalue issues, and image proud adaptive filte communication an understand in transmit and in methods, such CFAR algorithing object parallated to estiment will be able ues and apply	alysis and processal analysis using a ralgebra topic diagonalization cessing. In addiering with its prons channel equiling of the designeceive paths, as matched coms. Within the frameters such a ation accuracy to analyze come the acquired ki	ng complex nu s, he will learn, s, VD decomp ition, the stude actical applicat alization. In and operation and how radar or Doppler filter framework of ea s distance, rad (MSE, CRLB)	mbers, the apposition, not will letions, income of rad signals ring, as estimation ial velociand means accessing	differen differen lication and Po- earn the cluding dar syst are pro- well as n issue sity or s asurem	ems, conside cody advanced de se, the student ignal receptic ent ambiguity ns, use advars, and a set a	nplex functions, as linear especially in ndom signal tracking, echo ering the or she will learn etection t will learn on angle, taking the or she will searn expected to the control of th	

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Learning outcomes	Course outcome	Subject outcome	Method of verification
	[K7_W04] knows and understands, to an increased extent, the principles, methods and techniques of programming and the principles of computer software development or programming devices or controllers using microprocessors or other elements or programmable devices specific to the field of study, and organization of work of systems using computers or such devices	Upon completion of the course, the student knows and understands to an in-depth degree the principles, methods and techniques of programming signal processing systems and devices using microprocessors and programmable circuits. He can design and implement algorithms for signal analysis, filtering, detection and estimation, taking into account the specifics of radar and telecommunications systems. Understands the organization of computer systems and control devices, as well as the impact of the programming methods used on the efficiency and reliability of system operation.	[SW3] Assessment of knowledge contained in written work and projects
	[K7_W03] knows and understands, to an increased extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum	Upon completion of the course, the student knows and understands to an in-depth degree the construction and operating principles of components and systems related to signal analysis and processing and radar technology. He can apply advanced mathematical methods and algorithms for data analysis, signal filtering, detection and estimation of object parameters. Understands the complex interrelationship between theory and practice and the impact of system parameters on the accuracy and reliability of technical systems.	[SW3] Assessment of knowledge contained in written work and projects
	[K7_U07] can apply advanced methods of process and function support, specific to the field of study	Upon completion of the course, the student is able to use advanced methods to support the analysis and processing of signals and data detection, estimation and filtering functions in radar and telecommunications systems. He knows how to apply mathematical techniques, numerical algorithms and software tools to optimize the performance of technical systems. Demonstrates the ability to integrate various methods to increase the efficiency and accuracy of implemented processes.	[SU4] Assessment of ability to use methods and tools

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Subject contents	Part 1:
	W1:
	-composite numbers,
	-complex sine,
	-IQ modulation,
	-differentiation of composite functions
	W2:
	-basic operations on matrices,
	-matrices as linear transformations,
	-linear spaces,
	-base and kernel transformations,
	-reference to state models
	W3:
	-Eigenvalues, eigenvectors,
	-decomposition of matrices (diagonalization, SVD), PCA analysis
	W4:
	-Applications of diagonalization, SVD, PCA in signal processing, image processing and automation
	W5,6:
	-basic information about random signals,
	-correlation of signals,
	-basics of adaptive filtering,
	W7:
	-application of adaptive filtering: for state vector tracking (moving object tracking issues), in echo and vibration suppression tasks, telecommunication channel equalization
	Visitation suppression tasks, tolescrimationation charmer equalization
	Part 2:
	w1:
	- Construction of radar, antenna
	- Description of the transmitting / receiving part
	- Use of signals in the form of complex numbers
	- Signal flow, mixer operation, reduction to baseband
	- Concept of data cube
	- Pulse radar vs. FMCW
	W2:
	- Matched filtering - explanation of the issue
	- Different types of waveforms
	- Relationship between bandwidth and duration and sidelobe level, gain
	- Differences in pulse radar vs. FMCW
	- Expanding the topic to communication issues, looking at it in terms of object identification
	W3:
	- Beamforming - purpose of application, antenna characteristics

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- Effect of antenna array, discussion of sparse arrays - Effect of taper on beamforming, purpose of using them W4: - Doppler filtering - Description of the Doppler effect itself - Purpose of application - Unambiguity of radial velocity measurement W5: - Detection - purpose, examples of signals - CFAR - description of the algorithm, its different variants - Dependence of probability of detection and false alarm on SNR - Detection of several objects in its environment, introduction to OS CFAR, its alarm of the several objects in its environment, introduction to OS CFAR, its alarm on SIR introduction to the issue as an estimator of object parameters - Distance estimation, variant with non-uniform measurement - Radial velocity estimation, ambiguous measurement	advantages					
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- Radial velocity estimation, ambiguous measurement	- Distance estimation, variant with non-uniform measurement					
W7						
- Estimation of the angle of signal reception - physical description						
	- Exact signal model, approximate model  - Frequency dependence					
	- Non-parametric model using monoimpulse as an example					
- Non-parametric model using monoimpulse as an example						
- MSE - maximum likelihood estimator	- MSE - maximum likelihood estimator					
- CRLB - estimation of the minimum variance of the unloaded estimator	- CRLB - estimation of the minimum variance of the unloaded estimator					
Prerequisites Knowledge of linear algebra, fundamentals of filtering and signal processing.						
and co-requisites						
and seitaria	ercentage of the final grade					
Work during labs 50.0% 50.0% 50.0% 50.0%						
Recommended reading  Basic literature  S. Haykin, "Adaptive Filter Theory", Pears	son					
M. I. Skolnik, "Introduction to Radar Syste	M. I. Śkolnik, "Introduction to Radar Systems", McGraw-Hill S. Mallat, "A Wavelet Tour of Signal Processing", Academic Press					
Supplementary literature No guidelines	No guidelines					
raissy na piateimie oradozanie.						
Example issues/ Analysis of the effect of covariance matrix parameters on the effectiveness of a tracking systems.  tasks being completed	radar signal detection algorithm using the CFAR method and evaluation of its effectiveness					
Design of a radar signal detection algorithm using the CFAR method and evaluated under low SNR conditions.						
Work placement Not applicable						

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