

## Subject card

Subject name and code	Change Detection in Signals, PG_00064257								
Field of study	Automatic Control, Cybernetics and Robotics								
Date of commencement of studies	February 2026		Academic year of realisation of subject			2025/2026			
Education level	second-cycle studies		Subject group			Optional subject group Specialty subject group Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the	at the university		
Year of study	1		Language of instruction			Polish			
Semester of study	1		ECTS credits			2.0			
Learning profile	general academic pro	general academic profile Assessment form		assessment					
Conducting unit	Department Of Decision Systems And Robotics -> Faculty Of Electronics Telecommunications And Informatics -> Wydziały Politechniki Gdańskiej								
Name and surname	Subject supervisor		dr inż. Janusz Kozłowski						
of lecturer (lecturers)	Teachers		dr inż. Janusz Kozłowski						
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	Projec	:t	Seminar	SUM	
of instruction	Number of study hours	15.0	15.0	0.0	0.0	0.0		30	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	30		4.0		16.0		50	
Subject objectives	Assimilation of principles of mathematical modelling of dynamic systems.  Expanding knowledge on parameter identification and change detection algorithms.  Practical implementations of algorithms.								

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Learning outcomes	Course outcome	Subject outcome	Method of verification				
	[K7_W03] knows and understands, to an increased extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum	Student got practical knowledge on applications of the on-line detection and identification procedures. Student got familiar with analytical methods for examination of algorithms.	[SW1] Assessment of factual knowledge				
	[K7_U03] can design, according to required specifications, and make a complex device, facility, system or carry out a process, specific to the field of study, using suitable methods, techniques, tools and materials, following engineering standards and norms, applying technologies specific to the field of study and experience gained in the professional engineering environment	Student got practical knowledge on mathematical modelling of control systems, learned the identification methods of deterministic and stochastic models.	[SU4] Assessment of ability to use methods and tools				
	[K7_K02] is ready to provide critical evaluation of received content and to acknowledge the importance of knowledge in solving cognitive and practical problems	Student solved practical problems using expert knowledge on system identification and rationally compares different approaches.	[SK2] Assessment of progress of work				
	[K7_U01] can apply mathematical knowledge to formulate and solve complex and non-typical problems related to the field of study by: - appropriate selection of source information and its critical analysis, synthesis, creative interpretation and presentation, - application of appropriate methods and tools	Student implemented modern procedures of parameter estimation and optimal filtering. Student also utilized familiar with methods used to improve accuracy of estimates of parameters.	[SU4] Assessment of ability to use methods and tools				
Subject contents	Selected applications of detection methods.						
	Deterministic and stochastic models. Linear integrating filters and Poisson moment functionals time approximations of continuous systems.  Estimation of process parameters and detection of parameter variations using parameter ident methods: properties of algorithms.  Least-squares method: recursive and non-recursive algorithms.						
	Instrumental-variable method, properties of the method and selection of instrumental variables.						
	Tracking the evolution of process parameters with the aid of error weighting mechanism.						
	Robust to measurement faults parameter identification algorithms derived from minimization of non-quadratic criteria. Applications of robust algorithms in diagnostics.						
	Minimization of non-quadratic criteria: simplex method and recursively-iterative method.						
	Direct method of continuous-time system identification.						
	d parameter systems.						
Drorogujojtes							
Prerequisites and co-requisites							

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Assessment methods	Subject passing criteria	Passing threshold	Percentage of the final grade			
and criteria	Final test on theory. It is necessary to score at least 13 out of total amount of 25 pts. Time for the test: 60 minutes.	50.0%	100.0%			
Recommended reading	Basic literature  Basseville M., Nikiforov I.V.: Detection of abrupt changes: theory and application. Prentice-Hall Inc., 1993.					
		Ljung L.: System identification. Theory for the user. Prentice-Hall Inc., 1987.				
		Korbicz J., Kościelny J.M., Kowalczuk Z., Cholewa W. (Editors): Fault diagnosis: models, artificial intelligence, applications. Springer, Berlin New York, 2004.				
	Supplementary literature	Anderson B.D.O., Moore J.B.: Optimal filtering. Information and System Sciences Series. Prentice-Hall Inc., 1979.				
	eResources addresses	Adresy na platformie eNauczanie:				
Example issues/ example questions/ tasks being completed	Specify in brief possible application necessarily mean changes large in respectively.	ons of change detection algorithms. E magnitude.	xplain why abrupt changes do not			
	Enumerate and describe in brief common performance indices used for evaluation of quality of change detection.					
	Compare the Kalman approach and the Wiener approach to optimal filtering. Indicate situations where Kalman filter demonstrates its supremacy.					
	Compare the so-called direct and indirect approaches to identification of continuous-time systems.     Enumerate the benefits and drawbacks of both concepts.					
	5. Describe the direct method of identification of continuous-time systems based on the method of linear integral filtering (LIF). Introduce the transfer function of the LIF operator and derive the ultimate formula for the numerical LIF realization using the bilinear operator. Formulate and justify the rule of thumb for proper selection of the integration horizon.					
Work placement	Not applicable					

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