



Subject card

Subject name and code	Fuzzy Control, PG_00047408						
Field of study	Automatic Control, Cybernetics and Robotics						
Date of commencement of studies	February 2026		Academic year of realisation of subject		2026/2027		
Education level	second-cycle studies		Subject group		Obligatory subject group in the field of study Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery		at the university		
Year of study	2		Language of instruction		English		
Semester of study	3		ECTS credits		1.0		
Learning profile	general academic profile		Assessment form		assessment		
Conducting unit	Department of Automatic Control -> Faculty of Electronics Telecommunications and Informatics -> Faculties of Gdańsk University of Technology						
Name and surname of lecturer (lecturers)	Subject supervisor		dr inż. Piotr Fiertek				
	Teachers		dr inż. Piotr Fiertek				
Lesson types	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	0.0	0.0	0.0	15
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	15		2.0		8.0	25
Subject objectives	Students taking this course get acquainted with the basic elements of the theory of fuzzy sets and fuzzy logic, and learn how this theory can be applied to control of dynamic systems.						

Learning outcomes	Course outcome	Subject outcome	Method of verification
	[K7_W03] knows and understands, to an increased extent, the construction and operating principles of components and systems related to the field of study, including theories, methods and complex relationships between them and selected specific issues - appropriate for the curriculum	Student has a basic knowledge of the fuzziness paradigm in control structured in the following two parts: (i) fundamental concepts of fuzzy sets theory, fuzzy logic and approximate reasoning, (ii) designing of the classical control systems. Student knows how to use the fuzzy systems approach to solving engineering problems in control.	[SW1] Assessment of factual knowledge
	[K7_W08] knows and understands, to an increased extent, the fundamental dilemmas of modern civilisation, the main development trends of scientific disciplines relevant to the field of education	The student knows the principles of designing fuzzy drivers.	[SW1] Assessment of factual knowledge
	[K7_W10] knows and understands, to an increased extent, the basic processes occurring in the life cycle of equipment, objects and technical systems, as well as methods of supporting processes and functions, specific to the field of study	The student knows the principles of designing fuzzy drivers.	[SW1] Assessment of factual knowledge
	[K7_W01] knows and understands, to an increased extent, mathematics to the extent necessary to formulate and solve complex issues related to the field of study	Student has a basic knowledge of the fuzziness paradigm in control structured in the following two parts: (i) fundamental concepts of fuzzy sets theory, fuzzy logic and approximate reasoning, (ii) designing of the classical control systems. Student knows how to use the fuzzy systems approach to solving engineering problems in control.	[SW1] Assessment of factual knowledge
Subject contents	Course content – lecture 1. Fuzzy sets theory introduction, basic definitions and examples. 2. Operations of fuzzy sets. Fuzzy relations. The extension principle. 3. Approximate reasoning. Fuzzy propositions. Fuzzy inference rules. 4. Linguistic variables. Fuzzy if-then statements. Fuzzy knowledge based control principle. 5. Structure of fuzzy knowledge based controller: fuzzification module, knowledge base, inference engine, defuzzification module. 6. Mamdani and Takagi Sugeno models. PID-like fuzzy control. 7. MATLAB Fuzzy Logic toolbox. 8. Fuzzy models of dynamic systems. Identification of fuzzy models. 9. Stability in the sense of Lyapunov. An idea of adaptive fuzzy control. 10. Adaptive fuzzy control. Direct and indirect methods of adaptation. 11. Adaptive fuzzy control with a supervisor. Robustness of fuzzy control systems. 12. Internal model control (IMC) principle for fuzzy control. 13. Non-linear fuzzy control. Stability of fuzzy control systems. 14. Optimal fuzzy control systems. Expert systems with fuzzy logic. Process diagnostics based on fuzzy rules. 15. Examples of complex fuzzy control systems.		
Prerequisites and co-requisites			
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	Midterm colloquium	50.0%	100.0%
Recommended reading	Basic literature	1. A. Piegat: Modelowanie i sterowanie rozmyte, Exit, 1999. 2. L.-X. Wang: A Course in Fuzzy Systems and Control, Prentice Hall, 1997	
	Supplementary literature	Yager Ronald R.: <i>Podstawy modelowania i sterowania rozmytego</i> , Warszawa: Wydawnictwo Naukowo-Techniczne 1995	
	eResources addresses		
Example issues/ example questions/ tasks being completed	1. Give the definition and an interesting example of fuzzy set. 2. Draw the full functional diagram of a fuzzy inference system. Describe the meaning of each element of such system. 3. Describe the chosen method of defuzzification. 4. What is the T-norm? Give an example of such an operator. 5. What is the core and support (fuzzy set base) of fuzzy set? 6. Describe fuzzy controller based on the <i>Mamdani</i> scheme. (How its work? In a few sentences)		
Practical activities within the subject	Not applicable		

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