

Subject card

Subject name and code	PROGRAMMABLE CONTROLLERS, PG_00053202								
Field of study	Automation, Robotics and Control Systems								
Date of commencement of studies	October 2025		Academic year of realisation of subject			2027/2028			
Education level	first-cycle studies		Subject group			Obligatory subject group in the field of study Subject group related to scientific research in the field of study			
Mode of study	Full-time studies		Mode of delivery			at the university			
Year of study	3		Language of instruction			Polish			
Semester of study	5		ECTS credits			4.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Department Of Intelligent And Decision Support Systems -> Faculty Of Electrical And Control Engineering -> Wydziały Politechniki Gdańskiej								
Name and surname	Subject supervisor		dr inż. Jarosław Tarnawski						
of lecturer (lecturers)	Teachers			1				<u> </u>	
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Projec	t	Seminar	SUM	
	Number of study hours	30.0	0.0	30.0	0.0		0.0	60	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study :		SUM	
	Number of study hours	60		6.0		34.0		100	
Subject objectives	Understanding of the tasks, functions and location of PLC in the control system. Knowledge of PLC programming methods. Practical programming skills in ladder language and structured text. Ability to implement basic control algorithms in PLC. Understanding the principles of implementing more complex control algorithms. Ability to design and implement PLC cooperation with the SCADA system using dedicated and unified OPC communication servers. Using PLC to work in the loop (Hardware-in-the-loop), including connecting a physical object or real-time system.								
Learning outcomes	Course outcome		Subject outcome			Method of verification			
	[K6_K02] can work in a group taking on different roles in it		Working in a group, students acquire leader and subordinate skills.			[SK1] Assessment of group work skills			
	[K6_W06] knows the structure of computers and microprocessors and the tasks of operating systems, has basic knowledge of the basics of computer software, drivers, microprocessor technology, design of simple algorithms and the operation of information networks					[SW1] Assessment of factual knowledge			
	[K6_U05] can use analytical and simulation methods to solve tasks in the field of automation and robotics and use various techniques to carry out engineering tasks related to automation and robotics devices and systems			The student is able to build a control system in the so-called hardware loop with the simulated object, PLC and SCADA system.			[SU5] Assessment of ability to present the results of task		

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Subject contents	Control structures and the place of PLC in these structures. Historical outline of the creation of PLCs replacing contactor-relay control systems. Main features and requirements for PLC: reliability, flexibility, ease and programming capabilities, scalability, communication capabilities. IEC-1131 and EN61131 standards. Principle of operation of PLC. Duty cycle. PLC as devices that meet the real-time requirement. Issues in the selection of PLC for the task of automating the technological process. PLC programming methods, languages: ladder, instruction list, sequential function diagrams, function block diagrams, structured text. Control and regulation algorithms in PLC. Embedded algorithms, methods of program implementation of simple control and regulation methods. Methods of implementing selected discrete control algorithms. Communication issues in PLC: data exchange between controllers, data exchange with other elements of the control structure. Limitations on the applicability of PLC. PLC cooperation with supervisory control systems, SCADA data acquisition systems and databases using the universal OPC data exchange method.						
Prerequisites and co-requisites	Completed courses: Real-time systems, Industrial IT networks						
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade				
	Laboratory assessment	50.0%	50.0%				
	Oral theoretical examination	50.0%	50.0%				
Recommended reading	Basic literature	1. Legierski T., Kasprzyk J., Wyrwał J., Hajda J.: Programowanie sterowników PLC, Wydawnictwo Pracowni Komputerowej Jacka Skalmierskiego, Gliwice, 1998 2. Kwaśniewski J.: Programowalne sterowniki przemysłowe w systemach sterowania, ZP Roma-Pol, 1999 3. Pasierbński J., Legierski T.: Programowanie sterowników PLC, Wydawnictwo Pracowni Komputerowej Jacka Skalmierskiego,1998 4. Kasprzyk J.: Programowanie sterowników przemysłowych, WNT, 2013					
	Supplementary literature	5. Tatjewski P.: Sterowanie zaawansowane obiektów przemysłowych, Akademicka Oficyna Wydawnicza EXIT, 2002 6. Grega W., Metody i algorytmy sterowania cyfrowego w układach scentralizowanych i rozproszonych, Wydawnictwo AGH, 2004 7. Broel-Plater Bogdan, Układy wykorzystujące sterowniki PLC, PWN, 2015 8. Kwaśniewski J., Sterowniki PLC w praktyce inżynierskiej, btc, 2008					
	eResources addresses Adresy na platformie eNauczanie:						
Example issues/ example questions/ tasks being completed	Design and build a control system using PLC for a selected laboratory facility						
Work placement	Not applicable						

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