



## Subject card

Subject name and code	Robotics, PG_00064813						
Field of study	Mechanical Engineering						
Date of commencement of studies	February 2026		Academic year of realisation of subject		2025/2026		
Education level	second-cycle studies		Subject group		Obligatory subject group in the field of study Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery		at the university		
Year of study	1		Language of instruction		Polish		
Semester of study	1		ECTS credits		2.0		
Learning profile	general academic profile		Assessment form		assessment		
Conducting unit	Institute of Mechanics and Machine Design -> Faculty of Mechanical Engineering and Ship Technology -> Wydziały Politechniki Gdańskiej						
Name and surname of lecturer (lecturers)	Subject supervisor		dr inż. Michał Mazur				
	Teachers						
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	15.0	0.0	0.0	30
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	30		5.0		15.0	50
Subject objectives	Expanding knowledge about robots and manipulators. Some specific issues relating to the actors, sensors and control systems.						
Learning outcomes	Course outcome		Subject outcome		Method of verification		
	[K7_W12] identifies and interprets the main developmental trends and significant new achievements in the field of engineering and technical sciences and disciplines relevant to the course of study		identifies and interprets the main developmental trends and significant new achievements in the field of engineering and technical sciences and disciplines relevant to the course of robotics		[SW3] Assessment of knowledge contained in written work and projects [SW2] Assessment of knowledge contained in presentation		
	[K7_W01] explains and describes, on the basis of general knowledge of the scientific disciplines forming the theoretical basis of Mechanics and Mechanical Engineering, the structure and principles of operation of mechanical systems and processes		explains and describes, on the basis of general knowledge of the scientific disciplines forming the theoretical basis of Mechanics and Mechanical Engineering, the structure and principles of operation of robots and robotic systems		[SW1] Assessment of factual knowledge		
	[K7_K11] is aware of importance of professional acting, the need for critical verification of acquired knowledge and consulting experts opinion in case of facing difficulties with individual problem solving		is aware of importance of professional acting, the need for critical verification of acquired knowledge and consulting experts opinion in case of facing difficulties with individual problem solving when using robotic systems		[SK5] Assessment of ability to solve problems that arise in practice [SK4] Assessment of communication skills, including language correctness [SK3] Assessment of ability to organize work [SK2] Assessment of progress of work [SK1] Assessment of group work skills		

Subject contents	LECTURE: 1 Introduction 2 Modern trends in the development of two industrial robots 3 Sensors 4 Signal Conditioning 5 Tactile and haptic sensors 6 Methods of localization of mobile robots 7 Effectors 8 Elements of power supply systems 9 Drive chain elements used in robots 10 Tools for robot programming and simulation  Laboratory: 1 Programming delta type robot task for ABB IRB360 robot 2 Programming collaborative robot tasks for HCR3a robot using OnRobot vision system 3 Programming of industrial robot movements with force sensor feedback for Nachi NC04 robot		
Prerequisites and co-requisites	Basics of mathematics, mechanics and automation, the ability to program engineering calculations.		
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	Team projects	50.0%	40.0%
	Midterm colloquium	50.0%	60.0%
Recommended reading	Basic literature	Craig J., J., Wprowadzenie do robotyki. Mechanika i sterowanie, WNT, Warszawa 1993 Honczarenko J., Roboty przemysłowe. Budowa i zastosowanie, WNT, Warszawa 2002 Jarzębowska E., Podstawy dynamiki mechanizmów i manipulatorów, Oficyna Wydawnicza Politechniki Warszawskiej, Warszawa 1998 Morecki A., Knapczyk J., Podstawy robotyki. Teoria i elementy manipulatorów i robotów, WNT, Warszawa 1993 Morecki A., Knapczyk J., Kędzior K., Teoria mechanizmów i manipulatorów, WNT, Warszawa 2002 Vidyasagar M., Spong Mark W.: Dynamika i sterowanie robotów. WNT, Warszawa 1997	
	Supplementary literature	Dulęba I., Metody i algorytmy planowania ruchu robotów mobilnych i manipulacyjnych, Akademicka Oficyna Wydawnicza EXIT, Warszawa 2001 Giergiel M. J., Hendzel Z., Żylski W.: Modelowanie i sterowanie mobilnych robotów kołowych. PWN, Warszawa 2002 Tchoń K., Mazur A., Dulęba I., Hossa R., Muszyński R.: Manipulatory i Roboty Mobilne. Modele, planowanie ruchu, sterowanie. Warszawa: Akademicka Oficyna Wydawnicza PLJ 2000	
	eResources addresses		
Example issues/ example questions/ tasks being completed	What is a sensor? Advantages and disadvantages of digital sensors? Advantages and disadvantages of analog sensors? Discuss conditioning. Haptic systems.Robots development trends. Advantages and disadvantages of ultrasonic sensors for distance measurement. List the location methods. Techniques for measuring distance. Advantages and disadvantages of monolithic architecture. Advantages and disadvantages of distributed architecture. Robust programming - fault detection techniques. Application of real-time systems in robot control. What is SLAM? What do we use quaternions for? Discuss Spherical Linear Interpolation Applications of dual quaternions. What is ROS? Discuss MoveIT Discuss 2D Navigation in a ROS environment Discuss the control of the quadrocopeter What is Zero Moment Point?		
Work placement	Not applicable		

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