

Subject card

Subject name and code	Numerical Methods, PG_00038088								
Subject name and code Field of study	Automation, Robotics and Control Systems								
Date of commencement of									
studies	OCIONEI 2020		Academic year of realisation of subject		2025/2026				
Education level	first-cycle studies		Subject group						
Mode of study	Full-time studies		Mode of delivery		at the university				
Year of study	1		Language of instruction		Polish				
Semester of study	2		ECTS credits			3.0			
Learning profile	general academic profile		Assessment form			assessment			
Conducting unit	Faculty of Electrical and Control Engineering -> Wydziały Politechniki Gdańskiej								
Name and surname	Subject supervisor dr hab. inż. Mirosław Wołoszyn								
of lecturer (lecturers)	Teachers								
Lesson types and methods	Lesson type	Lecture	Tutorial	Laboratory	atory Project		Seminar	SUM	
of instruction	Number of study hours	15.0	30.0	0.0	0.0		0.0	45	
	E-learning hours included: 0.0								
Learning activity and number of study hours	Learning activity	Participation in classes includ plan		Participation in consultation hours		Self-study		SUM	
	Number of study hours	45		4.0	1.0			75	
Subject objectives	The purpose of the course is for the student to master the numerical methods used in engineering calculations.								
Learning outcomes	Course out	Subject outcome			Method of verification				
	[K6_W01] has basic knowledge in the field of mathematics including algebra, geometry, mathematical analysis, probabilistics, numerical methods - necessary to describe and analyze automation and robotics systems		Student use computer tools for numerical calculations			[SW3] Assessment of knowledge contained in written work and projects			
	[K6_U05] can use an simulation methods to in the field of automal robotics and use varitechniques to carry dengineering tasks relautomation and robotics and systems	o solve tasks ation and ious out ated to				[SU1] Assessment of task fulfilment			
Subject contents	Computer arithmetic and round-off error, floating-point representation. Numerical matrix algebra: systems of linear algebraic equations, Gauss elimination, Gauss - Jordan elimination, LU decompostion, computation of the inverse matrix, iterative methods. Nonlinear algebraic equations: one equation: bisection, regula-falsi method, secant method, Newtons method, system of equations: fixed-point iterations, Newtons method. Function interpolation: Lagrange polynomials. Numerical differentiation of a function of one variable, backward, centered, and forward differences. Approximation of functions: least-squares n polynomials. Numerical integration of one-dimensional integrals: Newton-Cotes rules, Romberg integration, Gauss-Legendre quadrature, singular integrands, integrals over infinite domains. Initial-value problems for ordinary differential equations: polynomial approximation, Euler method.								
Prerequisites and co-requisites									
Assessment methods and criteria	Subject passin	g criteria	Pass	ing threshold		Per	centage of the	final grade	
	tests and work on exercises					88.0%			
	tasks from lectures		60.0%			12.0%			
Recommended reading	Basic literature		C. Pozrikidis: Numerical Computation in Engineering,Oxford University Press 19				998.		
	Supplementary literature		James F. Epperson: An introduction analysis. Wiley, 2013			to numerical methods and			
	eResources addresse	es							

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example questions/	The solution of equations by Gauss, LU, GS. Lagrange interpolation function method. Approximation of the function sin (x) using the mean square approximation. Calculation of integrals by Simpson. The solution of nonlinear equations using Newton's method. The solution of differential equations using Euler's method.
Work placement	Not applicable

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