



Subject card

Subject name and code	Modelling and Basics of Identification, PG_00058307						
Field of study	Automation, Robotics and Control Systems						
Date of commencement of studies	October 2026	Academic year of realisation of subject				2028/2029	
Education level	first-cycle studies	Subject group				Optional subject group Subject group related to scientific research in the field of study	
Mode of study	Full-time studies	Mode of delivery				at the university	
Year of study	3	Language of instruction				Polish	
Semester of study	5	ECTS credits				4.0	
Learning profile	general academic profile	Assessment form				exam	
Conducting unit	Faculty of Electrical and Control Engineering -> Faculties of Gdańsk University of Technology						
Name and surname of lecturer (lecturers)	Subject supervisor		dr hab. inż. Michał Grochowski				
	Teachers						
Lesson types	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	30.0	0.0	30.0	0.0	0.0	60
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	60		8.0		32.0	100
Subject objectives	Presentation of modern methods of systems modeling and estimation of their parameters. Analytical, fuzzy and neural technology will be presented						
Learning outcomes	Course outcome		Subject outcome			Method of verification	
	[K6_W07] has basic knowledge related to control and automation systems		- Students is able to build mathematical models of objects and dynamic processes - The student is able to study simulation and experimentally behaviour of of dynamic objects. - The student formulates and solves optimization problems with constraints.			[SW1] Assessment of factual knowledge	
	[K6_U07] can build and analyze models of systems and systems in the field related to control systems and automation		Student potrafi zaplanować przygotować i przeprowadzić eksperymenty, pomiary i symulacje komputerowe do oceny realizacji zadań z zakresu modelowania i identyfikacji systemów			[SU1] Assessment of task fulfilment [SU4] Assessment of ability to use methods and tools [SU5] Assessment of ability to present the results of task	

Subject contents	<p>Course content – lecture</p> <p><b>LECTURES</b></p> <ol style="list-style-type: none"> <li>1. Deterministic signals - parametric and non parametric models of deterministic signals. Multiplexing, demultiplexing, sampling and extrapolating, A/C and C/A processing. Selected models of deterministic signals. Random signals.</li> <li>2. System theory in modelling and identification: categories of the systems. Static and dynamic models. Linear and nonlinear models. Continuous and discrete models. Kinds of description. Linearization.</li> <li>3. Parametric and nonparametric models. Fenomenological modelling, behavioral modelling and mixed modelling grey box modelling. Steps of modeling.</li> <li>4. Phenomenological modelling: example of models - continuous and discrete, linear and nonlinear, stationary and nonstationary, deterministic and stochastic. Uncertainty modelling. Modelling with usage of fuzzy technology. Fuzzy reasoning systems. Structures of fuzzy models - Mamdani, Larsen, Takagi-Sugeno and Tsukamoto models.</li> <li>5. Optimisation methods In identification: optimisation problems for parametric models. Criteria of optimisation. Optimisation methods with and without constraints. Fundamentals of usage of the genetic algorithms.</li> <li>6. Behavioural models and identification: System identification - problems. Linear and nonlinear models considering the parameters. Least squares method. Modelling with usage of neural technologies; training of neural models.</li> <li>7. Modelling with usage of hybrid techniques; example of advanced applications: neural - fuzzy models and their tuning. Examples of hybrid models .</li> </ol> <p><b>EXERCISE</b></p> <ul style="list-style-type: none"> <li>• Continuous systems - building of phenomenological models based on principle rules of conservation - Designing of analogue diagrams.</li> <li>• Linearization.</li> <li>• Continuous/discrete signals - differences, ways of conversions.</li> <li>• Discrete systems - definitions, analysis.</li> <li>• Selected optimisation problems.</li> <li>• Fuzzy systems - definitions, properties, fuzzy reasoning.</li> </ul> <p><b>LABORATORY</b></p> <ul style="list-style-type: none"> <li>• Continuous systems - building of phenomenological models based on principle rules of conservation.</li> <li>• Linearization.</li> <li>• Modelling of discrete systems.</li> <li>• Model parameter estimations, Least squares method.</li> <li>• Fuzzy logic - fundamentals of reasoning.</li> </ul>														
Prerequisites and co-requisites	There are no requirements														
Assessment methods and criteria	<table border="1"> <thead> <tr> <th data-bbox="448 1310 794 1346">Subject passing criteria</th> <th data-bbox="794 1310 1141 1346">Passing threshold</th> <th data-bbox="1141 1310 1487 1346">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="448 1346 794 1382">Laboratory</td> <td data-bbox="794 1346 1141 1382">80.0%</td> <td data-bbox="1141 1346 1487 1382">15.0%</td> </tr> <tr> <td data-bbox="448 1382 794 1417">Exercises</td> <td data-bbox="794 1382 1141 1417">70.0%</td> <td data-bbox="1141 1382 1487 1417">15.0%</td> </tr> <tr> <td data-bbox="448 1417 794 1451">Exam</td> <td data-bbox="794 1417 1141 1451">60.0%</td> <td data-bbox="1141 1417 1487 1451">70.0%</td> </tr> </tbody> </table>			Subject passing criteria	Passing threshold	Percentage of the final grade	Laboratory	80.0%	15.0%	Exercises	70.0%	15.0%	Exam	60.0%	70.0%
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Recommended reading	Basic literature	<ol style="list-style-type: none"> <li>1. Roffel, B., Betlem, B. (2006). Process Dynamic and Control. Modelling for Control and Prediction. John Wiley &amp; Sons, Ltd.</li> <li>2. Hangos, K.M., Cameron, I.T. (2001). Process Modelling and Model Analysis. Academic Press, Ltd.</li> <li>3. Englezos, P., Kalogerakis, N. (2001). Applied Parameter Estimation for Chemical Engineers. Marcel Dekker, Inc.</li> <li>4. Ljung, L. (1999). System Identification. Theory for the User. Prentice Hall.</li> <li>5. Söderström, T., Stoica, P. (1997). Identyfikacja systemów. PWN, Warszawa 1997</li> </ol>													
	Supplementary literature	<ol style="list-style-type: none"> <li>1. Ljung, L., Glad, T. (1994). Modelling of Dynamic Systems. Prentice Hall.</li> <li>2. Wellstead, P.E. (2000). Introduction to Physical System Modelling. Academic Press Ltd.</li> </ol>													
	eResources addresses														
Example issues/ example questions/ tasks being completed	<ul style="list-style-type: none"> <li>• building a complex dynamic plant model in Matlab/Simulink software;</li> <li>• dynamic model parameter estimation;</li> <li>• process modeling using fuzzy sets;</li> <li>• introduction to artificial neural networks.</li> </ul>														
Practical activities within the subject	Not applicable														

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