



Subject card

Subject name and code	, PG_00056136						
Field of study	Mechatronics						
Date of commencement of studies	October 2024	Academic year of realisation of subject			2026/2027		
Education level	first-cycle studies	Subject group					
Mode of study	Full-time studies	Mode of delivery			at the university		
Year of study	3	Language of instruction			Polish		
Semester of study	6	ECTS credits			2.0		
Learning profile	general academic profile	Assessment form			assessment		
Conducting unit	Department of Manufacturing and Production Engineering -> Faculty of Mechanical Engineering and Ship Technology -> Faculties of Gdańsk University of Technology						
Name and surname of lecturer (lecturers)	Subject supervisor	dr inż. Norbert Piotrowski					
	Teachers						
Lesson types	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	15.0	0.0	15.0	0.0	0.0	30
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan	Participation in consultation hours		Self-study	SUM	
	Number of study hours	30	0.0		0.0	30	
Subject objectives	Conveying basic knowledge on methods and means of production automation as well as robotisation technologies of manufacturing processes, along with the issues related to controlling the related process flow as determinants of modern economy. The development of the capability for selecting the adequate technical measures and means aimed at enhancing the operational efficiency of individual machines by robotisation and automation of related working cycles as well as the entire process flow within multi-machine systems.						
Learning outcomes	Course outcome	Subject outcome			Method of verification		
	[K6_W08] knows and understands design and production processes of elements and simple mechatronic devices	The student is able to design simple robotic stations applicable in production.			[SW3] Assessment of knowledge contained in written work and projects		
	[K6_U06] is able to identify and formulate specification of simple, practical engineering tasks, distinctive for mechatronics	The student is able to solve the kinematic tasks of robots used in production systems.			[SU3] Assessment of ability to use knowledge gained from the subject		
	[K6_U05] is able to use properly chosen tools to compare design solutions of elements and mechatronics systems according to given application and economic criteria (e.g. power demand, speed, costs)	The student is able to use the tools and techniques to optimize the processes of automation and robotization of production stations.			[SU4] Assessment of ability to use methods and tools		
	[K6_W10] has knowledge about development trends in the field of engineering and technology sciences and scientific disciplines: Mechanical Engineering, Automation, Electronics, Electrical Engineering and Space Technologies, adequate for Mechatronics course	The student has a basic knowledge of development trends in the field technical sciences and scientific disciplines: Construction and operation of machines, Mechanics appropriate for the field of study Mechatronics. The student explains the structure and principle of operation of mechatronic systems.			[SW3] Assessment of knowledge contained in written work and projects		
	[K6_W11] has knowledge about the life cycle of mechatronic systems and objects	The student has a basic knowledge of the life cycle of devices, objects and mechatronic systems. The student explains the structure and principle of operation of mechatronic systems.			[SW3] Assessment of knowledge contained in written work and projects		

Subject contents	<p>Course content – lecture</p> <p>Planning the composition and organisational structure of a cellular system for manufacturing elements of the fixturing equipment with variant processing solutions for the needs of simulation analysis in FlexSim® system, together with quantitative evaluation of results obtained.</p> <p>Selected elements of matrix calculus and solving the task of simple kinematics and inverse kinematics of an industrial robot (IR) in Matlab® software.</p> <p>Analysis of the IR manipulation space by its functional characteristics; programming the material handling cycles in the material supply subsystem of machine stands. Modelling and analysis of automated processes using graphical models, matrix notation and event networks.</p>											
Prerequisites and co-requisites	Basic knowledge of manufacturing technologies as well as the structure and operation of machine tools and manufacturing equipment.											
Assessment methods and criteria	<table border="1" data-bbox="451 528 1487 674"> <thead> <tr> <th data-bbox="451 528 794 562">Subject passing criteria</th> <th data-bbox="794 528 1142 562">Passing threshold</th> <th data-bbox="1142 528 1487 562">Percentage of the final grade</th> </tr> </thead> <tbody> <tr> <td data-bbox="451 562 794 618">Written colloquium for credit of the lectures</td> <td data-bbox="794 562 1142 618">56.0%</td> <td data-bbox="1142 562 1487 618">50.0%</td> </tr> <tr> <td data-bbox="451 618 794 674">Reports related to laboratory classes</td> <td data-bbox="794 618 1142 674">56.0%</td> <td data-bbox="1142 618 1487 674">50.0%</td> </tr> </tbody> </table>			Subject passing criteria	Passing threshold	Percentage of the final grade	Written colloquium for credit of the lectures	56.0%	50.0%	Reports related to laboratory classes	56.0%	50.0%
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Recommended reading	Basic literature	<ol style="list-style-type: none"> 1. Honczarenko J.: Obrabiarki sterowane numerycznie, Warszawa, WNT, 2008. 2. Honczarenko J., Roboty przemysłowe, Wydawnictwo Naukowe PWN, Warszawa 2010. 3. Kost G., Łebkowski P., Węsierski Ł. N.: Automatyzacja i robotyzacja procesów produkcyjnych. Seria: Zarządzanie i Inżynieria Produkcji, PWE, Warszawa 2013. 4. Pająk E.: Zarządzanie produkcją. Produkt, technologia, organizacja, PWN, Warszawa 2013. 5. FlexSim. 3D Simulation software, User manual, FlexSim software Products Inc., USA, 2017. 										
	Supplementary literature	<ol style="list-style-type: none"> 1. Grzesik W., Niesłony P., Kiszka P., Programowanie Obrabiarek CNC. Wydawnictwo Naukowe PWN, Warszawa 2020. 2. Honczarenko J.: Elastyczna automatyzacja wytwarzania. Obrabiarki i systemy obróbkowe, WNT, Warszawa 2000. 3. Kaczmarek W., Panasiuk J.: Robotyzacja procesów produkcyjnych, z cyklu: Robotyka, PWN, Warszawa 2017. 4. Mechatronika. Praca zbiorowa pod kier. D. Schmida (oprac. polskie M. Olszewski i inni), Verlag Europa - Lehrmittel Rea. Warszawa 2002. 										
	eResources addresses											

<p>Example issues/ example questions/ tasks being completed</p>	<ol style="list-style-type: none"> 1. Models of concentration and diversification of manufacturing operations in the viewpoint of the productivity of the manufacturing processes. 2. Quantitative description of automation and of manufacturing process operations. 3. The concept of (total) complete machining and its realisation with the use of use of working machining centres. 4. The classification of machine tool systems in terms of part diversification and the scale of production. 5. The general purpose machine tools and machine specialisation, and the forms of production automation. 6. Functional division of the means for programmed control and the factors for related application tor specific production tasks. 7. Palletising and part supply and flow for machining centre operation in flexible manufacturing systems. 8. Typical applications of industrial robots and handling equipment for the operation of manufacturing facilities. 9. The basic parameters used in the description of atributes and operational characteristics of industrial robots. 10. Application features of machining centres (MCs)and stand-alone machining stations (SMSs). 11. The criteria and conditions determining the selection of multi-axis CNC machine tools. 12. The classification schemes of layout structures in parts manufacture with regard to automation of production processes. 13. The rationale behind and conditions (technical measures) for selecting multi-part machining operations; sketches of selected examples of applications. 14. The techniques and means used in the subsystems allocated to the parts - and tool storage meeting the demands of flexible manufacturing. 15. Techniques and means for automated inspection and measurement functions in modern manufacturing systems.
<p>Practical activites within the subject</p>	<p>Not applicable</p>

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